TWISTED MAGNETIZATION PHASES IN ORBITAL-DOMINANT RARE-EARTH NITRIDES

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Abstract

In this thesis we investigate the magnetic properties of NdN and SmN, members of the rare-earth nitrides, a series of intrinsic ferromagnetic semiconductors. In rare-earth systems, the strong spin-orbit coupling of the partially filled 4f shell ensures that there is a substantial orbital contribution to the ferromagnetic moment, in contrast to many transition metal systems where the orbital moment is usually quenched. In SmN and NdN the orbital moment actually exceeds the spin moment, and the resulting orbital dominant magnetization allows for the fabrication of a magnetic heterostructures showing novel behavior.

We report a new theoretical study of the magnetic properties on both SmN and NdN by considering the atomic-like 4f electrons. These calculations incorporate spin-orbit coupling, the exchange interaction in a self-consistent mean-field approach, and crystal field interactions in an arbitrary-multiplet point-charge model. Our findings show excellent agreement with the experimentally measured ferromagnetic moments of SmN and NdN, representing an advance from previous theoretical studies.

We also report an experimental study on SmN/GdN heterostructures using the element-resolved method of x-ray magnetic circular dichroism (XMCD) to probe the magnetism. The competition between the orbital-dominant Zeeman coupling in SmN and the ferromagnetic spin-based interface exchange with GdN, which has purely a spin moment, results in a twisted magnetization profile. The depth profile of the magnetization derived from XMCD measurements showed good agreement with an analytical model developed to describe the competing interactions.

In a second study, a superlattice of NdN/GdN was investigated via XMCD

and standard magnetometry techniques. A twisted magnetization was shown to be present due to the same mechanism as in the SmN/GdN system. By varying the maximum applied field and temperature, twisted phases were shown to develop in both GdN and NdN layers. These twisted phases in orbitaldominant ferromagnetic semiconductors represent a departure from previously explored spin-dominant metallic systems displaying similar twisted phases.

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"The time has come," the Walrus said, "To talk of many things: Of shoes-and ships-and sealing-wax-Of cabbages-and kings-And why the sea is boiling hot-And whether pigs have wings." – Lewis Carroll, from "The Walrus and the Carpenter"

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Chapter 1 Introduction

Research into rare-earth nitrides (RENs) has experienced a surge of interest over the past ten years, spurred by the theoretical prediction [1] that some of the RENs are half-metallic ferromagnets, which suggested the application of RENs in spin-filters. Subsequent experimental investigations have found that a majority of the RENs are in fact *intrinsic* ferromagnetic semiconductors [2–8]. This makes the RENs quite distinct from the more well known dilute magnetic semiconductors (DMS) such as (Ga,Mn)As [9]. In DMS systems, the host semiconductor is doped with magnetic impurity ions to achieve both ferromagnetism and semiconducting behavior. The Curie temperature and conductivity are thus strongly dependent on the spatial distribution of these impurity ions, which is difficult to control. The difficulty in independently manipulating the magnetic and electronic degrees of freedom is thus a large drawback in DMS systems.

The RENs derive their magnetic properties from the partially filled 4f shell of the rare-earth elements, which consists of 14 distinct single-electron states, resulting in widely varying magnetic properties as the occupation increases across the series. The magnetic order is largely insensitive to the number of free carriers arising from nitrogen vacancy defects for a wide range of concentrations [10]. This is due to the localized exchange mechanism responsible for ferromagnetic ordering, in contrast to longer range carrier-mediated exchange commonly found in metallic rare-earth systems [11–13]. This localized exchange in the RENs also leads to rather low ordering temperatures compared

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to metallic rare-earth systems, requiring liquid He temperatures. But most importantly, semiconducting and ferromagnetic behavior coincide, and electronic structure calculations show spin-polarized bands with conduction and valence band edges of the majority spin [14].

These properties have led to the integration of the rare-earth nitrides in spintronic devices, with GdN incorporated as a barrier layer in a spin-filter Josephson junction [15], and DyN as a barrier layer in a magnetic tunnel junction [16]. Incorporating various RENs into semiconducting magnetic tunnel junctions for use in magnetoresistive random access memory elements (MRAM) [17] is also an intriguing possibility due to the large spin polarizations and semiconducting nature of the RENs.

While the device implications of the rare-earth nitrides are one important motivation for studying them, fundamental physical questions about the RENs are not yet resolved. GdN is the most thoroughly investigated of the series, with numerous theoretical and experimental studies into the electronic and magnetic structure, however for the other RENs there are far fewer reports. Indeed, for the majority of the RENs there is only one recent band structure calculation which also provides a calculation of magnetic moments [14].

Understanding the magnetic moment is non-trivial, as an unquenched orbital contribution to the magnetization may result in a net magnetization parallel to the orbital moment and antiparallel to the spin moment in the first half of the rare-earth series. The presence of unquenched, orbital-dominant moments then complicates the study of magnetic heterostructures composed of RENs. In this thesis we calculate the magnetic moments of SmN and NdN within crystal-field theory in order to better understand the interplay between orbital and spin contributions to the magnetization. The crystal field calculations represent an alternative approach to the existing density functional theory calculations carried out on SmN and NdN [14, 18]. We find good agreement with experimental data within this crystal field approach.

The primary experimental work on RENs so far has been on homogeneous RENs, with only two publications on REN heterostructures, by Anton *et al.* [19] and McNulty *et al.* [20], the latter of which is part of this thesis (Chapter 5). The study of these heterostructures is a necessary step for exploring potential device applications, but more fundamentally allows us to probe unexplored interface effects in REN-based heterostructures. In this thesis we carried out magnetic studies using element specific x-ray techniques as well as more common magnetization measurements in heterostructures composed of SmN/GdN and NdN/GdN layers. In these heterostructures we demonstrate the existence of a "twisted" or inhomogeneous magnetic phase occurring at interfaces. These twisted phases are shown to be a consequence of the unique rare-earth magnetism, specifically the orbital-dominant magnetism of NdN and SmN in combination with the spin-only magnetic moment of GdN. These experimental studies, together with the new calculations of the SmN and NdN magnetic moments provide the first detailed description of REN-based heterostructures.

1.1 Outline

This thesis is organized as follows. Chapter 2 contains the theoretical background reviewing the relevant electronic structure of rare-earth ions, and introduces magnetism in the RENs, including an overview of the crystal field calculations. Chapter 3 introduces the primary experimental technique used in this thesis, x-ray magnetic circular dichroism (XMCD), and the sample preparation techniques used. In Chapter 4, the calculation of the magnetic moments of SmN and NdN is presented with comparisons to recent and published experimental data. Chapter 5 reports on x-ray magnetic circular dichroism experiments on a SmN/GdN superlattice as well as bilayers of SmN/GdN and SmN/LaN/GdN. Chapter 6 is a study of a NdN/GdN superlattice using x-ray magnetic circular dichroism and SQUID based magnetometry. And finally, Chapter 7 summarizes the conclusions from this thesis and provides an outlook for future research.

1.2 Attribution

Much of the experimental work was done in collaboration with others:

• SmN/GdN L-edge XMCD: This data is presented in

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Chapter 5. Measurements were carried out by E.-M. Anton, B. J. Ruck, C. Meyer, H. J. Trodahl, F. Wilhelm, A. Rogalev at the European synchrotron radiation facility (ESRF) in Grenoble, France. Samples were grown by H. Warring and F. Natali.

- M-edge XMCD: Presented in Chapter 5. These measurements were carried out by myself and E. -M. Anton, B. J. Ruck, H. J. Trodahl, M. Medeiros-Soares, N. B. Brookes at the ESRF. I prepared all of the samples for these experiments.
- Nd/Gd L-edge XMCD: Presented in Chapter 6. The L-edge measurements were performed by myself and E.-M. Anton, H. J. Trodahl, T. Yamada, M. Suzuki, and M. Mizumaki at the SPring 8 Synchrotron facility in Japan. The NdN/GdN superlattice was grown by E.-M. Anton and myself, while the NdN sample was prepared by E.-M. Anton.
- SQUID Measurements: NdN magnetization measurements were carried out by E.-M Anton. Magnetization measurements on the NdN/GdN superlattice, SmN/GdN, and SmN/LaN/GdN samples were carried out by myself. Many of these measurements benefited from the assistance of Simon Granville and Shen Chong.
- *Calculations:* The calculations in Chapter 4 were programmed in Python by myself, as were the calculations in Chapter 5.

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- J. F. McNulty, E. -M. Anton, B. J. Ruck, F. Natali, H. Warring, F. Wilhem, A. Rogalev, M. Madeiros-Soares, N. Brookes, and H. J. Trodahl. *Twisted magnetization in the orbital-dominant ferromagnet SmN* in GdN/SmN heterostructures. Phys. Rev. B 91, 174426 (2015).
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- J. H. Richter, B. J. Ruck, M. Simpson, F. Natali, N. O. V. Plank, M. Azeem, H. J. Trodahl, A. R. H. Preston, B. Chen, J. F. McNulty, K. E. Smith, A. Tadich, B. Cowie, A. Svane, M. van Schilfgaarde, W. R. L. Lambrecht. *Electronic structure of EuN: Growth, spectroscopy,* and theory. Phys. Rev. B. 84, 235120 (2011)

Patents

 B. J. Ruck, H. J. Trodahl, E. -M. Anton, F. Natali, J. F. McNulty, S. Granville. *Magnetic materials and devices comprising rare-earth ni*trides. N.Z. Patent 623343, 2014. Chapter 1 Introduction

Chapter 2

Theoretical Background

2.1 Electronic Structure

In order to understand the magnetic properties of the rare-earth nitrides, we must first understand the electronic configuration of the partially filled 4f shell, which is the origin of the magnetism in rare-earth systems. To do this we proceed by examining the Hamiltonian of the 4f electrons. Later we will see that the magnetic properties of the RENs can to a large degree be understood by an atomic picture of the 4f shell.

We begin by considering a single 4f electron in a rare-earth ion with wave function ψ_i . In the potential field of the ion, the electron can described by the time-independent Schrödinger equation, $\mathscr{H}_i\psi_i = E_i\psi_i$, where

$$\mathscr{H}_i = -\frac{\hbar^2}{2m_e} \nabla_i^2 + V(r_i), \qquad (2.1)$$

with $r_i = |\mathbf{r}_i|$ is the position vector of the electron and m_e is the electron mass. $V(r_i) = -Z^*e/r_i$ represents the Coulomb potential energy between the *i*-th 4felectron in the ion, and Z^* represents the effective charge of the ion, including the filled electronic shells. The rare-earth elements are most commonly found in the trivalent (3+) state, and this is found to be the case in most of the RENs. The Schrödinger equation in this form does not adequately describe the 4f electrons, however, as relativistic effects must be included. Beginning with atoms having atomic number Z = 10, binding energies require relativistic corrections, and for wave functions relativistic corrections must be considered for atoms heavier than Z = 30 [21]. Therefore, from the outset we must consider relativistic effects, as the rare-earth elements start with Lanthanum, with Z = 57.

We can obtain the correct description by considering the relativistic Dirac equation, but for our purposes it is much easier to use only the lowest order terms from the expansion of the Dirac equation in powers of v/c. The Hamiltonian obtained from this expansion is given by [21]:

$$\mathcal{H}_{i} = -\frac{\hbar^{2}}{2m_{e}}\nabla_{i}^{2} + V(r_{i}) - \frac{\alpha^{2}}{4}\left(\frac{\hbar}{2m_{e}}\nabla_{i}^{2}\right)^{2} - \frac{\alpha^{2}}{4}\left(\frac{\mathrm{d}V(r_{i})}{\mathrm{d}r}\right)\frac{\partial}{\partial r} + \frac{\alpha^{2}}{2}\frac{1}{r_{i}}\left(\frac{\mathrm{d}V(r_{i})}{\mathrm{d}r}\right)\mathbf{l}_{i}\cdot\mathbf{s}_{i},$$
(2.2)

where $\alpha = e^2/\hbar c \approx 1/137$ is the fine structure constant. This equation is the same as the Schrödinger equation 2.1 but with three additional terms. The third and fourth terms only give a rigid shift to the absolute energy levels, which is not important for our purposes. The last term contains $\mathbf{l}_i \cdot \mathbf{s}_i$, which represent the orbital and spin angular momentum operators of the *i*th 4felectron. This term is known as the *spin-orbit coupling* term and plays a major role in the electronic configuration in the rare-earths. The coefficient

$$\lambda(\mathbf{r}_i) = \frac{\alpha^2}{2} \frac{1}{r_i} \left(\frac{\mathrm{d}V(r_i)}{\mathrm{d}r} \right)$$
(2.3)

is the spin-orbit coupling parameter. This parameter is large for tightly bound orbitals with small radii, such as the 4f electrons, due to the dependence of V(r) on r^{-1} . Figure 2.1 shows the expectation value $\langle r \rangle$ for various orbitals as a function of atomic number Z. The 4f radii can be seen to be smaller than all orbitals with principal quantum number $n \ge 5$, which includes the completely filled 5s and 5p shells, as well as valence 6s and 5d states in the rare-earths. These larger orbitals keep the 4f orbitals shielded from surrounding ions, so that they remain atomic-like even in a solid [2].

To consider all the electrons in the 4f shell, we must add together each single electron Hamiltonian, and in addition we must also include the Coulomb



Figure 2.1: Expectation values of r for various atomic orbitals as a function of atomic number Z, calculated within a Hartree-Fock scheme with relativistic corrections, taken from Cowan [21].

interaction between pairs of electrons.¹ The total Hamiltonian for the partially filled 4f shell is then

$$\mathscr{H}_{4f} = -\frac{\hbar^2}{2m_e} \sum_i \nabla_i^2 - \sum_i V(r_i) + \frac{1}{2} \sum_{i \neq j} \frac{e^2}{|\mathbf{r}_j - \mathbf{r}_i|} + \sum_i \lambda(\mathbf{r}_i) \mathbf{l}_i \cdot \mathbf{s}_i.$$
(2.4)

The first two terms are the same for all the electrons in the same shell, and just provide an overall rigid shift to the energy levels. The effective Hamiltonian for the 4f shell can finally be reduced to

$$\mathscr{H}_{4f} = \frac{1}{2} \sum_{i \neq j} \frac{e^2}{|\mathbf{r}_j - \mathbf{r}_i|} + \sum_i \lambda(\mathbf{r}_i) \mathbf{l}_i \cdot \mathbf{s}_i, \qquad (2.5)$$

where the first term is the electron-electron interaction (\mathscr{H}_{e-e}) , and the last term is the total spin-orbit interaction (\mathscr{H}_{SO}) . These two terms determine the relative energies of different electron configurations of the partially filled

¹Here we neglect terms $\mathbf{s_i} \cdot \mathbf{s_j}$, and $\mathbf{l}_i \cdot \mathbf{l}_j$, which are much smaller than the spin-orbit interaction term [21, 22]

4f shell. The electron-electron interaction term \mathscr{H}_{e-e} makes the Hamiltonian impossible to solve in general, thus various approximation schemes must be used, such as Hartree-Fock [23]. Depending on which term is larger, two coupling schemes for the angular momenta are used to describe the Hamiltonian. We note that \mathscr{H}_{e-e} commutes with the operators $\mathbf{L} = \sum_i \mathbf{l}_i$, $\mathbf{S} = \sum_i \mathbf{s}_i$, $\mathbf{J} = \mathbf{L} + \mathbf{S}$ and their z components L_z, S_z and J_z , while \mathscr{H}_{SO} commutes with \mathbf{J} and $\mathbf{j}_i = \mathbf{l}_i + \mathbf{s}_i$, but not \mathbf{L} or \mathbf{S} .

When \mathscr{H}_{e-e} is larger than the spin-orbit term, then to a good approximation the stationary states of the full Hamiltonian are the eigenstates of $\mathbf{L}^2, \mathbf{S}^2, \mathbf{J}^2$ and J_z , with eigenvalues L(L+1), S(S+1), J(J+1) and M_J , respectively. This is known as the *LS*-coupling or Russell-Saunders coupling. The quantum numbers describing the states are then L, S, J, M_J .

The second coupling scheme is known as jj-coupling, used when $\mathscr{H}_{SO} \gg \mathscr{H}_{e-e}$, so that the full Hamiltonian is close to diagonal when written in terms of \mathbf{j}_i and j_i^z . For atoms lighter than Pb (Z = 82), \mathscr{H}_{e-e} dominates, and so the rare-earth 4f shell then falls into the LS coupling regime.

In LS coupling, \mathscr{H}_{SO} can be rewritten in terms of **L** and **S** as

$$\mathscr{H}_{SO} = \Lambda \mathbf{L} \cdot \mathbf{S}, \qquad (LS\text{-coupling})$$
(2.6)

where Λ is the total spin-orbit coupling parameter for the 4f shell.² In the LS coupling regime, the relative energy of an electron configuration depends only on the quantum numbers J, L, and S, often represented by a term symbol ${}^{2S+1}L_J$. The energy of a configuration with a term symbol ${}^{2S+1}L_J$ is

$$E_{LSJ} = \left\langle {^{2S+1}L_J} \right| \mathscr{H}_{e-e} + \mathscr{H}_{SO} \left| {^{2S+1}L_J} \right\rangle.$$
(2.7)

In the absence of spin-orbit coupling, all configurations would have the same energy, with (2L+1)(2S+1)-fold degeneracy. The spin-orbit coupling partially reduces this degeneracy. The energy levels are split based on the J value, each with degeneracy 2J + 1.

Fortunately, for LS coupling there exist empirical rules which specify the

²This assumes that the quantum numbers L and S are fixed, and higher values of L or S are far off in energy.

ground state configuration, known as Hund's rules. These rules accurately give the ground state configuration (L, S, J) of all the rare-earth ions [2]. The ground state is of most interest for us for the magnetic and spectroscopy applications we will use later on.

2.2 Hund's Rules

Hund's rules can be heuristically argued by trying to minimize the energy of the atomic Hamiltonian $\mathscr{H} = \mathscr{H}_{e-e} + \mathscr{H}_{SO}$. The rules should be applied in the following order:

- 1. Maximize S
- 2. Given the maximum S, maximize L,
- 3. J = |L S| for a less than half-filled shell, J = |L + S| for a more than half-filled shell.

The first rule arises from the Pauli exclusion principle, where parallel spins are farther apart, reducing the Coulomb repulsion. Maximizing L follows the same reasoning; for large L the spatial wave function has more nodes and the probability of finding electrons close together is reduced. The third rule comes from considering the spin-orbit coupling. For less than half-filled shells, $\Lambda > 0$, so minimizing the magnitude of J will reduce \mathscr{H}_{SO} . For a more than half-filled shell, $\Lambda < 0$, and thus a maximum value of J reduces \mathscr{H}_{SO} .

For example, Sm^{3+} has five 4f electrons out of the 2(2l+1) = 14 possible states in the 4f shell. The largest value S can have is given by the maximum value of the z component, M_S . Since there are only five electrons, they each have the same z component of the spin m_s , and $M_S = \sum m_s = 5/2$, and so S = 5/2. The maximum orbital moment is then found by $M_L = \sum m_l =$ 3 + 2 + 1 + 0 - 1 = 5, thus L = 5. Because the shell is less than half filled, J = |L - S| = 5/2.

The term symbol ${}^{2S+1}L_J$ is unfortunately written using spectroscopic notation for L, with $0, 1, 2, 3, \ldots = S, P, D, F \ldots$, thus Sm³⁺ has the term symbol



Figure 2.2: Hund's rule ground state values of S, L, and J for the triply ionized rare-earth ions.

 ${}^{6}H_{5/2}$.³ The Hund's rules ground state values of J, L and S for the trivalent rare-earth ions are shown in Figure 2.2. We note that in the first half of the series, where J = |L - S|, L exceeds both S and J in some cases, which gives rise to orbital dominant magnetism.

In the following sections, we discuss how the Hund's rule ground state values of J, L and S, determine the magnetic properties of rare-earth ions.

2.3 Rare-earth Magnetism

In this section we discuss rare-earth magnetism, which will provide crucial background for later sections. In general rare-earth based materials have quite different magnetic properties compared to itinerant d electron systems. This comes primarily from the fact that the 4f wave functions are spatially localized and atomic-like, which has some important consequences:

• The spin-orbit coupling of the 4*f* electrons is large compared to crystal field and Zeeman energies, so that usually only the ground-state *J*-multiplet is important.

³In this thesis we do not use the term symbols, but instead write out J, L, S explicitly.

- The orbital moments are not necessarily quenched,⁴ as is often the case in light transition metal systems.
- The magnetic moments reside mainly in the localized 4f shell, with only small contributions from band magnetism.
- The inter-ion exchange producing ferromagnetism cannot arise from direct exchange between 4f orbitals, as the inter-ionic 4f wave functions do not appreciably overlap.
- Carrier mediated exchange mechanisms typical of rare-earth metals are not as important in the rare-earth nitrides, which are semiconductors.

These features will play a key role in later Chapters. Now we proceed to outline in more detail the basic magnetic features of the rare-earth ions, including more in-depth discussion of the above points.

2.3.1 Atomic magnetism

We start by examining a quantum mechanical model of atomic magnetism. We define **H** with magnitude $|\mathbf{H}| = H$, as the uniform applied magnetic field.⁵ The effect of **H** on a single electron is twofold. First, the momentum of the electron is modified by $\mathbf{p}_i \to \mathbf{p}_i + \frac{|\mathbf{e}|}{c} \mathbf{A}_i$ where \mathbf{A}_i is the vector potential associated with **H**. Second, the interaction of the electron spin \mathbf{s}_i with **H** must be accounted for by adding $\frac{|\mathbf{e}|\hbar}{mc} \mathbf{H} \cdot \mathbf{s}_i$ to the Hamiltonian.⁶

This means that the Hamiltonian for the partially filled 4f shell described previously, $\mathscr{H}_{e-e} + \mathscr{H}_{SO}$, then acquires additional terms. By choosing the vector potential as $\mathbf{A} = \frac{1}{2}\mathbf{H} \times \mathbf{r}$, the inclusion of these two effects yields

$$\mathscr{H}_{4f} = \mathscr{H}_{4f}^{0} + \frac{|e|}{2m_e c} \mathbf{H} \cdot \sum_{i} \mathbf{r}_i \times \mathbf{p}_i + \frac{e^2}{8m_e c^2} \sum_{i} \left(\mathbf{H} \times \mathbf{r}_i\right)^2 + \frac{|e|\hbar}{m_e c} \mathbf{H} \cdot \mathbf{S}, \quad (2.8)$$

⁴Quenching of the orbital moment occurs when $\langle L_z \rangle = 0$

⁵We use the cgs unit Oe for H, though in some chapters $\mu_0 H$ which has units of Tesla is used.

⁶This can be derived by an expansion of the Dirac equation [24, 25].

where $\mathscr{H}_{4f}^0 = \mathscr{H}_{e-e} + \mathscr{H}_{SO}$ is the Hamiltonian in the absence of **H**. We can simplify this expression by using the definition of the total orbital momentum operator $\hbar \mathbf{L} = \sum_i \mathbf{r}_i \times \mathbf{p}_i$, to replace the second term above, and define the Bohr magneton as $\mu_B = |e|\hbar/m_ec$:

$$\mathscr{H}_{4f} = \mathscr{H}_{4f}^0 + \mu_B (\mathbf{L} + 2\mathbf{S}) \cdot \mathbf{H} + \frac{e^2}{8m_e c^2} \sum_i (\mathbf{H} \times \mathbf{r}_i)^2.$$
(2.9)

The last term is responsible for diamagnetism, and is much smaller compared to the first term, and so we may ignore it in the following discussion [23]. The term linear in **H** is known as the Zeeman term, and the prefactor of **H** is the magnetic moment operator,⁷ which we denote $\mathbf{m} = -\mu_B(\mathbf{L} + 2\mathbf{S})$. The expectation value of **m** is what is measured experimentally, and with the choice of **H** in the z-direction, the magnetic moment is given by

$$m = -\mu_B \langle L_z + 2S_z \rangle$$
. magnetic moment (2.10)

Often we will speak of the spin and orbital contribution to the total moment, given by

$$m_L = -\mu_B \langle L_z \rangle$$
 orbital moment,
 $m_S = -2\mu_B \langle S_z \rangle$ spin moment. (2.11)

The magnetic moment is present even in the absence of a field, and is only non-zero for partially filled shells.

We haven't precisely defined the meaning of the expectation values $\langle \cdots \rangle$ used above. In general, to calculate the expectation value of **m** at a temperature *T*, we must use an ensemble or "thermodynamic" average. For an arbitrary quantum mechanical operator \mathcal{O} , the thermodynamic average is given by

$$\langle \mathcal{O} \rangle_T = \frac{1}{\mathcal{Z}} \sum_n \langle n | \mathcal{O} | n \rangle e^{-\beta E_n},$$
 (2.12)

⁷This is analogous to the classical magnetic dipole moment, with energy $E = -\mathbf{m} \cdot \mathbf{H}$

where $\beta = (k_B T)^{-1}$ with k_B Boltzmann's constant. The $|n\rangle$ are eigenstates of \mathscr{H} with associated energy E_n : $\mathscr{H} |n\rangle = E_n |n\rangle$. The partition function \mathcal{Z} is given by

$$\mathcal{Z} = \sum_{n} e^{-\beta E_n}.$$
 (2.13)

If the system is in its ground state at T = 0, then $\langle \mathcal{O} \rangle_T = \langle 0 | \mathcal{O} | 0 \rangle$ where $| 0 \rangle$ is the ground state. In this thesis, $\langle \cdots \rangle$ should be taken as the ground state expectation value if the states are not explicitly indicated.

As we shall later see, the magnetic moment can be calculated for the free-ion case of the rare-earth elements relatively easily. In a crystalline environment however, the presence of neighboring ions makes calculation of the magnetic moment and other related quantities more complex.

We next turn to the magnetic properties of a collection of N ions in the presence of a magnetic field.

2.3.2 Paramagnetism

We follow a general approach for discussing paramagnetism, as outlined in Nolting & Ramakanth [22]. The aim is to gain a good understanding of how the strong spin-orbit coupling of the rare-earths, in combination with the Zeeman coupling, influences the paramagnetic response. We start by considering a system of N identical, non-interacting ions in a magnetic field **H**. In this case, the Hamiltonian is just the sum of the effective Hamiltonian for a single ion:

$$\mathscr{H} = \sum_{i=1}^{N} \mathscr{H}_{e-e}^{i} + \mathscr{H}_{SO}^{i} + \mathscr{H}_{Z}^{i}, \qquad (2.14)$$

where the sum is over N ions and $\mathscr{H}_Z = -\mathbf{m} \cdot \mathbf{H}$ is the Zeeman term. The average magnetic moment of this system is called the magnetization \mathbf{M} , related to the magnetic moment of a single ion by

$$\mathbf{M} = \frac{N}{V} \left\langle \mathbf{m} \right\rangle, \qquad (2.15)$$

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where V is the volume of the system. We will calculate **M** for a rare-earth ion, but first it helps to make the connection to thermodynamics. For a Hamiltonian \mathscr{H} which has eigenvalues E_n , the free energy F is defined as $e^{-\beta F} = \sum_n e^{-\beta E_n} = \mathcal{Z}$, or equivalently $F = -\frac{1}{\beta} \ln \mathcal{Z}$, where \mathcal{Z} is the partition function. The magnetization can then be written

$$\mathbf{M}(T,H) = -\frac{1}{V} \frac{\partial F}{\partial \mathbf{H}} \Big|_{T}$$

$$= \frac{1}{\beta V} \left(\frac{\partial}{\partial \mathbf{H}} \ln \mathcal{Z} \right)_{T}.$$
(2.16)

We can also define the *volume susceptibility* χ , which links the response of the system (the magnetization) to the applied magnetic field. In general it is a tensor,

$$\chi_{\alpha\beta} = \frac{\partial M_{\alpha}}{\partial H_{\beta}}$$

= $-\frac{1}{V} \left(\frac{\partial^2 F}{\partial H_{\alpha} \partial H_{\beta}} \right)_T,$ (2.17)

where $\alpha, \beta = x, y, z$ label the Cartesian components. In this thesis we are usually mostly interested in one component and take H in the z direction, so we do not use explicit subscripts for the components. Thus $\mathbf{M} = (0, 0, M)$, and $\chi(T) = \partial M / \partial H$, without explicit subscript.

To calculate the magnetization, we note that the partition function of N ions factorizes as $\mathcal{Z} = (\mathcal{Z}_0)^N$, where \mathcal{Z}_0 is the single-ion partition function

$$\mathcal{Z}_{0} = \sum_{n} \langle n | e^{-\beta(\mathscr{H}_{e-e} + \mathscr{H}_{SO} + \mathscr{H}_{Z})} | n \rangle.$$
(2.18)

The magnetization can then be calculated by

$$M = -\frac{N}{V}k_B T \frac{\partial \ln \mathcal{Z}_0}{\partial H}.$$
(2.19)

To calculate \mathcal{Z}_0 we must define the states $\{|n\rangle\}$. In *LS* coupling, the basis states are given by $\{|LSJM_J\rangle\}$, but when a magnetic field is present another basis labeled by $\{|LSM_SM_L\rangle\}$ is sometimes convenient. As we saw earlier, \mathscr{H}_{e-e} does not depend on J, L or S, and just sets an energy scale: $\langle n|\mathscr{H}_{e-e}|n\rangle = E_0$. The choice of basis now depends on whether the spin-orbit term or Zeeman term is larger. In the rare-earths, the spin-orbit term is always larger than the Zeeman term for typical laboratory magnetic fields, and the resulting magnetization is sometimes referred to as the "weak-field Zeeman effect". Recall that in LS-coupling the spin-orbit term then takes the form

$$\mathscr{H}_{SO} = \Lambda \mathbf{L} \cdot \mathbf{S}, \tag{2.20}$$

however this is not diagonal in the basis $\{|LSM_SM_L\rangle\}$, but only in the basis $\{|JM_JLS\rangle\} \equiv \{|JM_J\rangle\}$.⁸ This can be seen by noting $\mathbf{L} \cdot \mathbf{S} = \frac{1}{2}(\mathbf{J}^2 - \mathbf{L}^2 - \mathbf{S}^2)$, which has the eigenvalue of $\frac{1}{2}[J(J+1) - L(L+1) - S(S+1)]$ when acting on $|JM_J\rangle$. The expectation value of \mathscr{H}_{SO} is then

$$\langle JM_J | \mathscr{H}_{SO} | JM_J \rangle = \frac{1}{2} \Lambda (J(J+1) - L(L+1) - S(S+1)).$$
 (2.21)

We now determine the Zeeman term in this basis. If the field is in the z direction the Zeeman term takes the form

$$\mathscr{H}_Z = -\mathbf{m} \cdot \mathbf{H} = \mu_B (L_z + 2S_z) H = \mu_B (J_z + S_z) H.$$
(2.22)

However, \mathscr{H}_Z is not diagonal in the JM_J basis because of the presence of S_z , so \mathscr{H}_{SO} and \mathscr{H}_Z do not share the same eigenstates. We note that $[S_z, J_z] = 0$, so if we are restricted to only the ground state *J*-multiplet, \mathscr{H}_Z is diagonal with respect to M_J within this *J*-multiplet. Only with inclusions of higher *J* multiplets does S_z cause off-diagonal terms.

The expectation value of \mathscr{H}_Z within the ground state J-multiplet can be calculated with the help of the Wigner-Eckart Theorem [23],⁹ which states that the matrix elements of any vector operator in the 2J + 1 dimensional space of

⁸We refer to $\{|JM_JLS\rangle\} \equiv \{|JM_J\rangle\}$ as the JM_J basis because L and S are fixed, depending only on the rare-earth ion, while all other quantum numbers J, M_J, M_L, M_S are not necessarily fixed.

⁹See Appendix A for a more general discussion of the Wigner-Eckart theorem.

J and J_z is proportional to the matrix elements of **J**, thus we can write

$$\langle JM_J | J_z + S_z | JM_J \rangle = g_J \langle JM_J | J_z | JM_J \rangle = g_J M_J$$
(2.23)

where g_J is the constant of proportionality known as the Landé g-factor:

$$g_J = \frac{3}{2} + \frac{1}{2} \left[\frac{S(S+1) - L(L+1)}{J(J+1)} \right].$$
 (2.24)

The Zeeman energy is thus given by $\langle JM_J | \mathscr{H}_Z | JM_J \rangle = g_J M_J \mu_B H$. We can now show that in the JM_J basis the Hamiltonian takes the expectation value

$$\langle \mathscr{H} \rangle = \underbrace{E_0 + \frac{1}{2} \Lambda [J(J+1) - L(L+1) - S(S+1)]}_{E_{LSJ}^0} + g_J M_J \mu_B H. \quad (2.25)$$

Figure 2.3 shows a sketch of the energy levels for SmN where $\Lambda \approx 430$ K,¹⁰ and so the separation between the J = 5/2 ground state and J = 7/2 state is about 1500 K. Sm³⁺ has the second smallest separation between ground and the first excited multiplet among the rare-earths after Eu³⁺, which has a separation 500 K, while for Nd³⁺ the separation increases to 2750 K and for Yb³⁺ it goes to 14,800 K [26].

The partition function can now be written as

$$\mathcal{Z}_{0} = \sum_{J=|L-S|}^{J=|L+S|} \left(e^{-\beta E_{LSJ}^{0}} \sum_{M_{J}=-J}^{J} e^{-\beta g_{J} M_{J} \mu_{B} H} \right).$$
(2.26)

Because Λ is large in the rare-earths compared to the temperatures of interest (less than 300 K), we only need to consider the Hund's ground state value of J, which simplifies \mathcal{Z}_0 to

$$\mathcal{Z}_{0} = e^{-\beta E_{LSJ}^{0}} \sum_{M_{J} = -J}^{J} e^{-\beta g_{J} M_{J} \mu_{B} H}$$
(2.27)

¹⁰We frequently use Kelvins to denote energies, however Boltzmann's constant k_B must be included to convert to an actual energy unit, e.g. $k_B 300 \text{ K} \approx 25 \text{ meV}$.



Figure 2.3: The energy levels of Sm^{3+} $(4f^5)$ free-ion, where the electronelectron interaction and all other atomic terms have been incorporated into E_0 . The spin orbit term orders states by J values, with separation $E_{J+1} - E_J = \Lambda(J+1)$. The Zeeman term breaks the degeneracy among M_J values. The higher J-multiplets are also split by the Zeeman term, though not shown here.

The sum can be written in terms of hyperbolic functions,

$$\mathcal{Z}_{0} = e^{-\beta E_{LSJ}^{0}} \frac{\sinh(\beta g_{J} \mu_{B} H (J + \frac{1}{2}))}{\sinh(\frac{1}{2}\beta g_{J} \mu_{B} H)},$$
(2.28)

and by calculating the magnetization as $M = -\frac{N}{V}k_BT\frac{\partial \ln \mathcal{Z}_0}{\partial H}$, we find

$$M = \frac{N}{V} J g_J \mu_B B_J (\beta g_J J \mu_B H)$$
(2.29)

where B_J is the Brillouin function [23]. When the field H becomes large, $B_J(x) \to 1$ and the magnetization is the saturation magnetization

$$M = \frac{N}{V} J g_J \mu_B, \tag{2.30}$$

here the susceptibility $\partial M/\partial H$ is zero. This corresponds to the saturation moment of $g_J J \mu_B$ for a single ion. We can also calculate the susceptibility in the high temperature limit where $k_B T \gg \mu_B H$. Then $B_J(x) \rightarrow \frac{J+1}{3J}x$ and

 $\chi = \partial M / \partial H$ gives us *Curie's law* for a free ion:

$$\chi = \frac{N}{V} \mu_B^2 \frac{g_J^2 J(J+1)}{3k_B T}.$$
(2.31)

Often this will be written in terms of the effective paramagnetic moment $m_{eff} = g_J \sqrt{J(J+1)} \mu_B$. As we shall see Equation (2.31) can be modified in a solid due to crystal field effects, in which case m_{eff} takes on a different value from the free-ion value.

We emphasize that this form of Curie's law was derived on the basis that the spin-orbit coupling is larger than both the Zeeman splitting $(\Lambda \gg \mu_B H)$ and the thermal energy $(\Lambda \gg k_B T)$, while the thermal energy is larger than the Zeeman splitting $(k_B T \gg \mu_B H)$.

2.3.3 Van Vleck paramagnetism

A subtle correction to Curie's law occurs if at a given temperature, the spacing between J-multiplets is not very large ($\Lambda \gtrsim k_B T$). In the rare-earths, Eu³⁺ and Sm³⁺ are most strongly affected by this due to their small multiplet separations. The Eu³⁺ ion, with $4f^6$, has a J = 0 ground state which is nonmagnetic. However, the van Vleck contribution allows for paramagnetism due to the presence of higher multiplets. In Sm³⁺, the van Vleck contribution is not as large, but is still appreciable.

The derivation of the van Vleck term comes from the consideration of higher *J*-multiplets in the partition function, thus one has to calculate

$$\mathcal{Z}_{0} = e^{-\beta E_{LS}^{0}} \sum_{J=|L-S|}^{|L+S|} \sum_{M_{J}=-J}^{J} e^{-\beta(\mathscr{H}_{SO}+\mathscr{H}_{Z})}.$$
(2.32)

The calculation is shown in Nolting & Ramakanth [22]. For the light rareearths where J = |L - S|, and if only the first excited J multiplet contributes, the resulting van Vleck susceptibility is

$$\chi_{VV} = \frac{N}{V} \left(\frac{J(J+1)}{3k_B T} g_J^2 \mu_B^2 + \mu_B^2 \frac{2(L+1)S}{3(J+1)\Delta} \right),$$
(2.33)

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where $\Delta = E_{J+1} - E_J$. The origin of this correction is due to the operator S_z in \mathscr{H}_Z , which is non-diagonal in the JM_J basis. Because it is not diagonal, it creates transitions between *J*-multiplets, which manifest in the temperatureindependent term. This term is present *even* when only the ground state multiplet is thermally occupied. For Sm³⁺ the ratio of the van Vleck term to the Curie term is

$$\frac{\chi_{VV}}{\chi_C} = 12 \frac{k_B T}{\Delta} = 0.008 \ T \ \mathrm{K}^{-1}, \tag{2.34}$$

where $\Delta = 1500$ K. Thus at 125 K the two contributions have equal magnitude, with being χ_{VV} dominant above 125 K. While this situation is altered to some degree in a solid due to the effects of exchange and crystal field interactions, the van Vleck contribution is still significant. This indicates that the J mixing from the excited J = 7/2 should be taken into account in any quantitative calculation involving the magnetic moment in trivalent Sm systems like SmN.

2.3.4 Ferromagnetism

Ferromagnetism arises due to the exchange interaction between ions which tends to align the spins. This can be understood from the Pauli exclusion principle, which states that a multi-electron wave-function must be antisymmetric with respect to switching any two coordinates. For a two electron system this means $\psi(\mathbf{r}_1\sigma_1, \mathbf{r}_2\sigma_2) = -\psi(\mathbf{r}_2\sigma_2, \mathbf{r}_1\sigma_1)$ where σ_i is the spin of the *i*-th electron. For an *N*-electron system the multi-electron wave function $\Psi(\mathbf{r}_1\sigma_1, \ldots, \mathbf{r}_N\sigma_N)$ can in general be written as a sum of Slater determinants to satisfy the Pauli principle [23]. In the Hartree-Fock approximation, the many body state is taken as single Slater determinant, and we use this approximation here. If we calculate the expectation value of electron-electron interaction term \mathcal{H}_{e-e} using $\Psi(\mathbf{r}_1\sigma_1, \ldots, \mathbf{r}_N\sigma_N)$, we find

$$\langle \Psi | \mathscr{H}_{e-e} | \Psi \rangle = \frac{1}{2} \sum_{i,j} \left(U_{ij} - \delta_{\sigma_i,\sigma_j} J_{ij} \right)$$
(2.35)

where the sums are over the occupied electronic states and $\delta_{\sigma_i,\sigma_j}$ is the delta function between spins. The "direct" term U_{ij} is given by

$$U_{ij} = \int d\mathbf{r} \ d\mathbf{r}' \ |\psi_i(\mathbf{r})|^2 \frac{e^2}{|\mathbf{r} - \mathbf{r}'|} |\psi_j(\mathbf{r}')|^2, \qquad (2.36)$$

and the "exchange term" J_{ij} is given by

$$J_{ij} = \int d\mathbf{r} \ d\mathbf{r}' \ \psi_i^*(\mathbf{r}) \psi_j^*(\mathbf{r}') \frac{e^2}{|\mathbf{r} - \mathbf{r}'|} \psi_i(\mathbf{r}') \psi_j(\mathbf{r}), \qquad (2.37)$$

The direct term is the analogue to the classical Coulomb repulsion between electrons, independent of their spin. Due to the delta function, the exchange term is only present when two spins have the same value. Because the sign in front of J_{ij} is negative in Eq. (2.35), this means that the two electrons with the same spin will have a lower energy. This results in a tendency for the spins to align themselves,¹¹ and is the basis of ferromagnetism.

Mean-field approximation

Calculating the exchange integrals is extremely difficult in solids, so usually an effective theory is preferred. The Heisenberg Hamiltonian is the most well known effective theory of exchange, where the exchange integral is replaced with an exchange constant $J_{i,j}$, which might be obtained empirically. The Heisenberg Hamiltonian is given by

$$\mathscr{H} = -\sum_{i \neq j} J_{i,j} \mathbf{S}_i \cdot \mathbf{S}_j, \qquad (2.38)$$

where the sum is over all pairs of spins \mathbf{S}_i and \mathbf{S}_j (i, j = 1, ..., N). We note that for parallel spins, the energy is at a minimum (assuming $J_{i,j}$ is positive, for ferromagnetic behavior). The Heisenberg model is an approximation best suited for localized moments, which is the case in the rare-earths with tightly bound 4f shells. Furthermore, we assume the exchange $J_{i,j}$ is isotropic. The study of this Hamiltonian encompasses a vast body of literature, and here we

¹¹While the Coulomb energy may be reduced, the kinetic energy may increase enough to make ferromagnetism unfavorable, depending on the band structure.

review one of the basic results, known as the mean-field or molecular field approximation.¹²

In the mean-field approximation, the Heisenberg Hamiltonian can be rewritten as 13

$$\mathscr{H}_{ex} = -2J_{ex}\sum_{i=1}^{N} S_{z}^{i} \langle S_{z} \rangle, \qquad (2.39)$$

where fluctuations from the thermodynamic average have been ignored, and the quantization axis is taken along z. Translational symmetry is assumed (i.e. $\langle S_z^i \rangle \equiv \langle S_z \rangle$), and the sum is over N spins. Equation (2.39) treats the exchange by assuming each spin S_z^i feels an average exchange due to all the other spins in the system. When an applied field is present, the Zeeman term $g_J \mu_B H \sum_i J_z^i$ can be added. Note the presence of total angular momentum J_z , and not S_z in the Zeeman term.¹⁴ It is more convenient to use J_z in the exchange term, so we make use of the Wigner Eckart theorem, and note that within a single multiplet $S_z = (g_J - 1)J_z$, so we can write the Hamiltonian including the Zeeman term as

$$\mathscr{H} = g_J \mu_B \left(H - \frac{2J_{ex}(g_J - 1)^2}{g_J \mu_B} \left\langle J_z \right\rangle \right) \sum_i J_z^i.$$
(2.40)

Written this way it is clear that the exchange acts as an effective magnetic field H_{eff} , given by

$$H_{eff} = -\frac{2J_{ex}(g_J - 1)^2}{g_J \mu_B} \langle J_z \rangle \,. \tag{2.41}$$

If we use the definition of the magnetization as $M = -\frac{N}{V}g_J\mu_B \langle J_z \rangle$, we link

 $^{^{12}}$ See for example Nolting & Ramakanth [22].

¹³Only one component of **S** is non-zero within the approximation, chosen as the z component

¹⁴It is often not emphasized in textbooks that in general, $S_z \neq J_z$ when discussing the exchange interaction. For the rare-earths, it is crucial to consider the orbital contribution.

 H_{eff} and M:

$$H_{eff} = \frac{2J_{ex}(g_J - 1)^2}{(N/V)(g_J \mu_B)^2} M = \lambda M.$$
(2.42)

Thus the effect of exchange is to modify the applied field, with the modified field given by $\tilde{H} = H + \lambda M = H(1 + \lambda \chi)$. This also implies that the meanfield approximation must be *self-consistent* in the sense that magnetization is a function of itself. This can be seen by using the result for the magnetization (Eq. 2.29) found before, except now in terms of \tilde{H} :

$$M(T) = \frac{N}{V} g_J \mu_B J B_J \left(\beta g_J \mu_B (H + \lambda M(T))\right).$$
(2.43)

The susceptibility can be calculated directly from Eq. 2.43, but alternatively we note that

$$\chi = \frac{\partial M}{\partial H} = (1 + \lambda \chi) \chi_0. \tag{2.44}$$

where $\chi_0 = \partial M / \partial \tilde{H} = \partial M / \partial H |_{\lambda=0}$ is the susceptibility in the absence of exchange. This can be written in the form [27]:

$$\frac{1}{\chi} = \frac{1}{\chi_0} - \lambda. \tag{2.45}$$

If we take χ_0 as the Curie law susceptibility derived in the previous section, the susceptibility including exchange is

$$\chi = \frac{C}{T - C\lambda} \qquad \text{where } C = \frac{N}{V} \frac{g_J^2 \mu_B^2 J(J+1)}{3k_B}.$$
 (2.46)

We note that when $T = C\lambda \equiv \theta_p$, the susceptibility diverges. This is the paramagnetic Curie temperature. Below θ_p the system is in the ferromagnetic phase where a spontaneous magnetization may occur even if H = 0. Above θ_p , in the paramagnetic phase, the magnetization is only non-zero when a field
is applied. In this approximation θ_p is explicitly given by

$$\theta_p = \frac{2J_{ex}(g_J - 1)^2 J(J+1)}{3k_B}.$$
(2.47)

We note that this estimation of θ_p considers only the ground state *J*-multiplet, and assumed *T* was large compared to $\mu_B H$. For this reason we call θ_p the high-temperature paramagnetic Curie temperature. In general this does not coincide with the actual ordering point, T_C , though often it is relatively close if the assumptions given in the derivation hold. A more common version of this relationship is usually given when there is no orbital moment: $\theta_p = 2J_{ex}S(S+1)/3k_B$. This is appropriate for Gd^{3+} , which has L = 0, but is not in general applicable to the other rare-earths.

Equation (2.47) allows us to estimate the strength of the exchange interaction from the experimentally measured susceptibility, which we will make use of in later chapters. We note that the origin of the exchange in the rare-earth nitrides is not fully understood,¹⁵ though various models have been put forth [2, 28]. A contribution to exchange from conduction electrons which plays an important role in rare-earth metals (the so-called Ruderman-Kittel-Kasuya-Yosida (RKKY) interaction [22]) is not as important in the non-metallic rareearth nitrides. This is the reason for the much lower Curie temperatures found in the RENs compared to metallic rare-earth systems [28]. For example metallic SmZn, SmCd, and SmAl₂ have ordering temperatures of about 128, 195, and 125 K, while SmN orders around 27 K [29, 30].

Due to the localized nature of the 4f electrons the direct 4f-4f inter-ion exchange interaction is negligible, so the exchange interaction must proceed indirectly through superexchange mechanisms, which involve unoccupied 5dstates. It is commonly assumed that through intra-ion 4f-5d exchange, ferromagnetic exchange exists between nearest neighbor (nn) rare-earth ions via the 4f-5d-5d-4f chain. Another exchange channel is antiferromagnetic superexchange via the N 2p states: 4f-5d-N2p-5d-4f (next nearest neighbor, nnn). In this picture there are then two contributions to the overall exchange energy,

 $^{^{15}\}mathrm{We}$ have only considered an *effective* exchange so far, ignoring the underlying states responsible.

and thus to the ordering temperature, with $T_C \sim (J_{nn} + J_{nnn})/k_B$, where J_{nn} is the ferromagnetic and J_{nnn} the antiferromagnetic exchange. These contributions through p and d states mean the exchange is not isotropic, as we have assumed in the mean-field theory. Experimentally however, it is not always possible through magnetization measurements to distinguish different contributions to T_C (or θ_p), and one can only extract a single isotropic effective exchange constant, J_{ex} .

2.3.5 The crystal field

We have so far ignored the effect of the nitrogen ions on the magnetic properties of the RENs. In principle, it is possible to consider these effects within density functional theory techniques, though there have been very few of these studies on the rare-earth nitrides with the exception of GdN. Instead, an approach originally due to Bethe [31] can be used which treats the N anions as electric point charges. This so-called crystal field can then be incorporated as a potential energy term in the Hamiltonian of the magnetic ion.

For the rare-earths, the crystal field energy is smaller than the spin-orbit interaction because the 4f orbital cloud is tightly bound, and shielded by the filled 5s and 5p shells, only weakly feeling the influence of the crystal field. The crystal field can then be considered as a perturbation to the spin-orbit coupling energy. The situation is reversed for light transition metal systems however, where the d orbitals are delocalized enough to strongly feel the crystal field. In the transition metal case, the spin-orbit coupling acts as a perturbation on the crystal field Hamiltonian. For heavy transition metal systems and the actinides, where the 4d, 5d and 5f shells are partially filled, the situation is somewhere in between, and the spin-orbit and crystal field energies lie on nearly equal footing.

One important consequence of the crystal field interaction is quenching of the orbital moment, where the expectation value of the orbital moment vanishes (i.e. $\langle L_z \rangle = 0$). In this case the magnetic moment then resides only in the spin moment. Full quenching usually only occurs in systems where the spin-orbit coupling is small, such as the 3*d* transition metals. One way to see this is to note that the crystal field potential is a real function of the coordinates (as we shall see), and if the ground state ψ_0 is non-degenerate, then ψ_0 may be chosen to be real; $\psi_0^* = \psi_0$. In this case, the expectation value of $L_z = -i\hbar \frac{\partial}{\partial \phi}$ can be calculated as

$$\langle \psi | L_z | \psi \rangle = -i\hbar \int d\phi \ d(\cos\theta) \psi^*(\theta,\phi) \frac{\partial}{\partial \phi} \psi(\theta,\phi).$$
 (2.48)

$$= i \times \text{constant}$$
 (2.49)

The result is thus an imaginary number for the expectation value $\langle L_z \rangle$, however all observable operators must have *real* eigenvalues. Thus $\langle L_z \rangle \equiv 0$ for real, non-degenerate wave functions, and the orbital angular momentum is said to be *quenched*.¹⁶ For a degenerate ground state, the orbital moment is not necessarily fully quenched, but will be partially quenched, depending on the symmetry properties of the degenerate states [33].

In contrast, the spin-orbit coupling tries to maximize the orbital moment given that a spin-moment is present. This is because the energy of the spinorbit term $\Lambda \mathbf{L} \cdot \mathbf{S}$ is minimized by having a large orbital moment, either parallel or antiparallel to \mathbf{S} , depending on the sign of Λ . The competition between \mathcal{H}_{SO} and the crystal field term, \mathcal{H}_{CF} , then determines the degree of quenching. Thus the light 3*d* systems, where $\langle \mathcal{H}_{SO} \rangle \ll \langle \mathcal{H}_{CF} \rangle$, are nearly fully quenched, while the rare-earths experience much less quenching. Any quenching that does occur in the rare-earths however, is also transferred to \mathbf{S} due to the spin-orbit coupling. This is also the origin of the large magnetocrystalline anisotropy in rare-earths. We note that the effective paramagnetic moment of the light transition metals is often given by $m_{eff} = g\mu_B \sqrt{S(S+1)}$ because the crystal field effectively sets L = 0 [23], while for the rare-earths J is still a good quantum number at large enough temperatures.

 $^{^{16}}$ This can also be shown to be a consequence of time-reversal invariance of the Hamiltonian, if the ground state is non-degenerate [32].

Crystal field calculations

While crystal field effects are generally smaller in the rare-earths than in transition metal systems, they are not negligible (except for the Gd^{3+} ion, with L = 0). Thus, in order to quantify the effects of the crystal field on SmN and NdN we carry out crystal field calculations in Chapter 4. Here we give an overview of the crystal field theory most applicable to rare-earth ions in cubic environments, which is outlined in detail by Hutchings when only the ground state J-multiplet is included [34]. A review by De Wijn *et al.* [35] extends the crystal field model for rare-earth ions to arbitrary multiplets; here we mostly follow their notation. Chapter 3 will describe further details for calculations within arbitrary multiplets, while here we present the basic theory.

The effect of the crystal field on a rare-earth ion can be written as an additional term in the rare-earth ion Hamiltonian corresponding to the electric potential energy;

$$\mathscr{H}_{CF} = \sum_{i} \sum_{j} \frac{Z_{j} e^{2}}{|\mathbf{R}_{j} - \mathbf{r}_{i}|},$$
(2.50)

where $-Z_j|e|$ is the ligand charge at position \mathbf{R}_j (N in the rare-earth nitride case) and \mathbf{r}_i is the position of the *i*th 4f electron. Because the 4f orbital radius, $\langle r \rangle_{4f} \approx 0.5$ Å (approximately equal to the Bohr radius $a_B = 0.53$ Å)¹⁷, is smaller than the Re-N separation of about 2.5 Å, an expansion of the denominator is justified. Strictly speaking, this electrostatic approach is not fully justified (see discussion in, e.g. [36]), however for the ground state properties, the electrostatic approximation produces good agreement with experiment and is far more straightforward to apply compared to quantum-mechanical *ab-inito* techniques. This expansion is well known in electrostatics, and is usually carried out in either Cartesian coordinates, Legendre polynomials, or normalized spherical harmonics, $Y_k^q(\theta, \phi)$. Here, we carry out the expansion using tesseral harmonics f_{kq} , which are purely real functions, and are related to the spherical

¹⁷The Re-N separation is given by a/2 where a is the lattice constant. Experimental and theoretical lattice constants for the RENs are given in Ref. [2]

harmonics by

$$f_{kq} = \frac{r^k}{\sqrt{2}c_{kq}} [Y_k^{-q} + (-1)^q Y_k^q], \qquad (2.51)$$

where c_{kq} are normalization constants. For example, f_{40} is given by

$$f_{40}(\mathbf{r}) = 35z^4 - 30z^2r^2 + 2r^2.$$
(2.52)

Other tesseral harmonics are given in Ref. [34]. For a single point charge at position \mathbf{R}_{j} and a single 4f electron at \mathbf{r}_{i} we can write the expansion as

$$\frac{1}{|\mathbf{R}_j - \mathbf{r}_i|} = \sum_{k=0}^{\infty} \frac{1}{R_j^{2k+1}} \left[\sum_{q=0}^k c_{kq}^2 \frac{4\pi}{2k+1} f_{kq}(\mathbf{R}_j) f_{kq}(\mathbf{r}_i) \right],$$
(2.53)

which is valid for $r_i < R_j$. The total contribution to \mathscr{H}_{CF} is the sum of Eq. 2.53 over the *i* 4*f* electrons and *j* N-ion point charges coordinating the rare-earth ion, leading to

$$\mathscr{H}_{CF} = \sum_{k=0}^{6} \sum_{q=0}^{k} A_k^q \sum_i f_{kq}(\mathbf{r}_i).$$

$$(2.54)$$

The sum over k can be shown to be non-zero only for even values of $k \leq 6$ for the 4f shell electrons, determined by the orthogonality properties of tesseral (or spherical) harmonics. The A_k^q are constants describing the strength of the crystal field

$$A_k^q = e^2 \frac{4\pi}{2k+1} c_{kq}^2 \sum_j Z_j \frac{f_{kq}(\mathbf{R}_j)}{R_j^{2k+1}},$$
(2.55)

where terms with k = 4, 6 describe the fourth and sixth order contributions to the crystal field. Often, instead of calculating the A_k^q explicitly, it is easier to factor out the q dependence by making use of the point symmetry of the ligand atoms, so that $A_k^q = A_k B_q$, where B_q is a geometric scaling factor that takes into account all the q dependence. We then use the A_k to parametrize the crystal field strength. For cubic symmetry, as in the RENs, \mathscr{H}_{CF} with the

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z axis along the [001] direction is given by

$$\mathscr{H}_{\rm CF} = A_4 \sum_i \left[f_{40}(\mathbf{r}_i) + 5f_{44}(\mathbf{r}_i) \right] + A_6 \sum_i \left[f_{60}(\mathbf{r}_i) - 21f_{64}(\mathbf{r}_i) \right].$$
(2.56)

Only fourth and sixth order contributions are present in cubic symmetry. The crystal field parameters can be calculated in the point-charge model for octahedral coordination (six nearest Re neighbors) of the rare-earth ion as

$$A_4 = \frac{7}{16} \frac{Ze^2}{R^5}, \qquad A_6 = \frac{3}{64} \frac{Ze^2}{R^7}, \tag{2.57}$$

where R is the Re-N distance. These parameters are depend on the coordination number of the magnetic ion, which can be 4,6, or 8 in cubic symmetry.

As we will see in Chapter 3, the excited *J*-multiplets are important to consider, because, depending on the size of the crystal field parameters, offdiagonal matrix elements of \mathscr{H}_{CF} can cause significant mixing between *J*multiplets. This is especially important for SmN, and to a lesser degree for NdN. In addition to the crystal field, the spin-orbit coupling and exchange may be considered, and so the Hamiltonian of a rare-earth ion is given by

$$\mathscr{H} = \Lambda \mathbf{L} \cdot \mathbf{S} - 2J_{ex} \langle S_z \rangle S_z + \mathscr{H}_{CF}, \qquad (2.58)$$

where the exchange is included via self-consistent mean-field theory. The exchange constant J_{ex} is estimated from the paramagnetic susceptibility, as discussed earlier. This Hamiltonian will allow us to calculate the ground state magnetic moment as well as the temperature dependent susceptibility.

We remark that when only the ground state multiplet is considered, the effect of a cubic crystal field on the rare-earth ions is to remove some the degeneracy present in the M_J levels in the absence of a field. This is sketched in Figure 2.4 for the Sm³⁺ ion, where the J = 5/2 ground state (with 2J+1 = 6degenerate levels) is split into a doubly degenerate state (doublet) labelled Γ_7 and a quadruply degenerate state (quartet) labelled Γ_8 . The number and degeneracy of these crystal field states can be predicted on the basis of group theory [31, 37] with knowledge of the symmetry of the crystal field and the J



Figure 2.4: A sketch of the energy levels of Sm^{3+} in a cubic crystal field with octahedral coordination. The crystal field splits the ground state J = 5/2 multiplet into a Γ_7 doublet and a Γ_8 quartet. Not shown are the crystal field and Zeeman splittings of the higher *J*-multiplets.

value of the ion. When an exchange or Zeeman term is present, these crystal field levels split again, though these splittings are small compared to the crystal field levels.

2.4 Exchange Springs

In this section we include a discussion of conventional exchange-spring systems, which are related to the topics discussed in Chapters 4 and 5. The first exchange-spring system was reported by by Goto *et al.* [38], who studied the magnetization of bilayer thin films composed of hard (large anisotropy) and soft (small anisotropy) ferromagnets. The study found that with a large field \mathbf{H}_0 applied in-plane, both layers were magnetized in the *x*-direction. When a small field \mathbf{H}_1 was subsequently applied in the -x direction, a rotation of the soft layer magnetization formed for a large enough value of $|\mathbf{H}_1|$ (see Figure 2.5).

This was shown to be due to competing interactions within the soft ferromagnetic layer. Because the hard ferromagnetic is layer insensitive to the

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Figure 2.5: A sketch of a conventional exchange-spring system. (a) Both layers are magnetized in the x-direction with a large field \mathbf{H}_0 . (b) A small field \mathbf{H}_1 begins to reverse the soft layer magnetization, while the hard layer remains fixed and pins the soft-layer magnetization at the interface, with an exchange spring forming in the soft layer.

smaller field in the -x direction, it acted as a rigid layer which pinned the soft layer magnetization at the interface through ferromagnetic exchange coupling. Away from this interface, the Zeeman coupling of the soft layer caused the magnetic moment of ions to align with the field. The exchange interaction with the soft layer then mediated these two competing interactions, resulting in a gradual rotation of the spins. The term *exchange-spring* is used because of the analogy between a mechanical system made in the original paper, where the exchange coupling between the films is viewed as a spring.

The basic physics can be understood by treating the spins in a one dimensional model where each atomic plane in the soft layer rotates uniformly, while the hard layer is fixed. In this case, the magnetic free energy can be described in a micromagnetic approach [39].

Using the geometry of Figure 2.5, we can calculate the free energy per unit area of the soft layer, integrated of the thickness L of the layer. In the simplest

case, where various anisotropies can be ignored, the free energy is given by

$$\mathcal{E} = \int_0^L \mathrm{d}z \left[A \left(\frac{\mathrm{d}\theta(z)}{\mathrm{d}z} \right)^2 - \mathbf{M} \cdot \mathbf{H} \right], \qquad (2.59)$$

where A is a constant describing the strength of the exchange, and $\theta(z)$ is the azimuthal angle as shown in Fig. 2.5. The first term represents the energy cost associated with the magnetization of neighboring spins deviating from parallel. It can be derived by noting that the exchange energy between spins is $E_{ex} \sim J_{ex} \cos \Delta \theta$, where $\Delta \theta$ is the angle between spins. This can be approximated for small angular displacements as $\Delta \theta \approx a \frac{d\theta}{dz}$ where a is the separation between spins, and z is the position in the film depth. Expanding the cosine leads to Equation 2.59 with $A = 2J_{ex}S^2/a^3$, where S is the spin. The second term is just the Zeeman term, which tries to align the spins with the field.

The form of $\theta(z)$ which minimizes the free energy can be found in this case analytically using the calculus of variations, as was calculated by Goto. It gives the magnetization as $\mathbf{M}(z) = M(\cos \theta(z), \sin \theta(z), 0)$, and results in the Blochwall like behavior shown in Figure 2.5. We note that the two requirements for this model are are 1) a hard layer magnetization which is rigidly fixed, and 2) the magnetic field must reverse from its original direction, such that there is competition between interface exchange and the Zeeman coupling.

This domain-wall like magnetization phase is part of a more general set of competing interactions in magnetic systems. These "twisted phases" as we call them here, can be due to a variety of interactions. Interface exchange, bulk and surface anisotropies, and anisotropic or chiral exchange interactions can lead to diverse types of twisted phases. But all of these twisted magnetic observed so far have been in "conventional" spin-dominant, metallic systems. The light rare-earth nitrides provide the ability to host novel twisted phases due to their unconventional orbital-dominant magnetism and non-metallic conductivity. In Chapters 4 and 5 we will investigate magnetic heterostructures involving SmN, NdN and GdN, and provide evidence for the existence of these twisted phases.

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Chapter 3

Experimental Techniques

3.1 Synchrotron Techniques

The main experimental tool used in this thesis is x-ray magnetic circular dichroism (XMCD). It is one of the most powerful tools for studying magnetism, providing the ability to measure element-resolved magnetization as well as distinguish spin and orbital contributions to the magnetization. The technique has only been in use since the mid 1980s, with the introduction of elliptically polarized x-rays at undulator beamlines in synchrotron facilities [40]. The development of the XMCD sum rules in the early 1990s has made it possible to extract the spin and orbital magnetic moments directly from the experimental spectra.

Synchrotron radiation is a specific type of radiation which occurs when ultra-relativistic¹ charged particles are accelerated in circular orbits by magnetic fields. In this energy regime, the emitted radiation from the particle has a much narrower angular and spatial divergence compared to a non-relativistic particle. The main advantage of using a synchrotron is its range of energies, spanning from about 10 eV to 50,000 eV, and the high brilliance compared to lab based sources. Modern undulator beamlines now provide elliptically polarized light over a wide range of x-ray energies. In this work, we consider the soft and hard X-ray regimes, in the range of 200-1500 eV and over 1500 eV, respectively. These two ranges contain the binding energies of the

¹i.e. $\gamma = \frac{1}{\sqrt{1 - v^2/c^2}} \gg 1$



Figure 3.1: Mass attenuation coefficient $\mu/\rho = \sigma^{\text{tot}}/m_A$ for elemental Sm and Nd, where ρ is the density, m_A is the mass, and σ^{tot} is the total absorption cross section. Data from NIST.

rare-earth 3d and 2p shells we are interested in. XMCD is a type of x-ray absorption spectroscopy (XAS), and so we begin with a discussion of XAS in the rare-earths.

X-ray absorption spectroscopy (XAS)

XAS can be most simply described as an absorption process where we measure the transmitted X-ray intensity before (I_0) and after (I(E, d)) passing through a sample of thickness d. The relationship is given by

$$I(E,d) = I_0 e^{-\mu(E)d},$$
(3.1)

where $\mu(E)$ is the linear absorption coefficient, which depends on the energy E of the X-ray photons. The absorption coefficient is related to the X-ray absorption cross-section σ^{abs} through $\mu(E) = \rho_A \sigma^{abs}(E)$, where ρ_A is the number of atoms per unit volume. If the X-ray energy is resonant with an atomic transition between two states, i.e. $E = E_f - E_i$, then $\sigma^{abs}(E)$ increases dramatically at this resonance, known as the absorption edge. The change in σ^{abs} from right before this absorption threshold to immediately after is known as

Edge		Nd	Sm	Gd
L_2	$2p_{1/2} \rightarrow 5d$	6,722 eV	$7{,}312~{\rm eV}$	$7,930~{\rm eV}$
L_3	$2p_{3/2} \rightarrow 5d$	$6{,}208~{\rm eV}$	$6,459~\mathrm{eV}$	$7,243~{\rm eV}$
M_4	$3d_{3/2} \rightarrow 4f$	$1{,}003~{\rm eV}$	1,111 eV	1,222 eV
M_5	$3d_{5/2} \rightarrow 4f$	$980~{\rm eV}$	$1{,}083~{\rm eV}$	$1{,}190~{\rm eV}$

 Table 3.1: Rare-earth absorption edges

the absorption edge-jump (Figure 3.1 shows edge-jumps for elemental Sm and Nd). Each atom has a specific energy for the absorption edge corresponding to the electronic transition.

This demonstrates the usefulness of synchrotron radiation, which provides the ability of tuning the X-ray energy E to specific absorption edges. This means different elements can be selected, as well as different absorption edges of the same element. The edges are labelled by the principal quantum number n = 0, 1, 2... = K, L, M... with a subscript to distinguish spin-orbit split states according to $l \pm s$.

In this work we examine four of the rare-earth absorption edges. In the soft x-ray regime are the M_4 and M_5 edges, corresponding to transitions from $3d_{3/2} \rightarrow 4f$ and $3d_{5/2} \rightarrow 4f$, where the core level 3d states are spin-orbit split according to $j = 2 \pm 1/2$. In general we will refer to the two edges together as the M-edge. In the hard X-ray regime are the L₂ and L₃ edges (or L-edge for both), which correspond to transitions from $2p_{1/2} \rightarrow 5d$ and $2p_{3/2} \rightarrow 5d$, respectively. Table 3.1 lists the x-ray energies at which the absorption edges occur.

To gain a more fundamental insight, we can look at a more detailed quantum mechanical picture (for a full account, see e.g. Stohr [41] or de Groot & Kotani [42]). The cross-section for absorption is proportional to the probability of an electron in an initial state $|\psi_i\rangle$ going to a final state $|\psi_f\rangle$ due to an incident X-ray photon. This probability P_{fi} is given in first order by Fermi's golden rule,

$$P_{fi} = \frac{2\pi}{\hbar} |\langle \psi_f | T | \psi_i \rangle|^2 \delta(E_f - E_i - \hbar\omega) \rho(E_f), \qquad (3.2)$$

where the Dirac delta function preserves conservation of energy, $\hbar\omega$ is the

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photon energy, and $\rho(E_f)$ is the density of final states. If there are multiple final states, a sum over each final state must be included. Here T represents the transition operator for the photon, which is given by

$$T = \frac{e}{m_e} \mathbf{p} \cdot \boldsymbol{\epsilon} e^{i\mathbf{k}\cdot\mathbf{r}},\tag{3.3}$$

where $\boldsymbol{\epsilon}$ is the polarization of the photon, \mathbf{k} is its wavevector, and \mathbf{p} the electron momentum operator. If $|\mathbf{k} \cdot \mathbf{r}| \ll 1$, then we approximate the exponential as $\exp(i\mathbf{k} \cdot \mathbf{r}) \approx 1$. This is known as the dipole approximation and is well justified at the rare-earth M-edge. For the rare-earths the atomic radii are approximately $\langle r \rangle_{3d} \approx 0.15$ Å, and the typical M-edge energy of 1 keV corresponds to $k = E/\hbar c \approx 5 \times 10^9 \text{ m}^{-1}$, thus $\mathbf{k} \cdot \mathbf{r} \approx 0.0008$. At the L-edge, where $E \sim 7 \text{ keV}$ and $\langle r \rangle_{2p} \approx 5 \times 10^{-12} \text{ m}$, we find $\mathbf{k} \cdot \mathbf{r} \approx 0.002$.

The absorption cross section σ^{abs} is proportional to P_{fi} , and is given by

$$\sigma^{abs} = 4\pi^2 \alpha \hbar \omega \left| \langle \psi_f | \mathbf{r} \cdot \boldsymbol{\epsilon} | \psi_i \rangle \right|^2 \delta(E_f - E_i - \hbar \omega) \rho(E_f), \qquad (3.4)$$

where $\alpha \approx 1/137$ is the fine structure constant. The polarization in the matrix element $\langle \psi_f | \mathbf{r} \cdot \boldsymbol{\epsilon} | \psi_i \rangle$ plays an important role. For example, the photon polarization tensor has three components $\boldsymbol{\epsilon}_z^q$ corresponding to linear polarization (q = 0), and both right (q = +1) and left (q = -1) circular polarizations. In terms of position basis vectors given by $\hat{\mathbf{e}}_i$ (i = x, y, z), we have $\boldsymbol{\epsilon}_z^0 = \hat{\mathbf{e}}_z$, and $\boldsymbol{\epsilon}_z^{\pm 1} = (\hat{\mathbf{e}}_x \pm i \hat{\mathbf{e}}_y)/\sqrt{2}$. The dipole operator can then be written

$$\mathbf{r} \cdot \boldsymbol{\epsilon}_{z}^{0} = z = r \cos \theta = r \sqrt{\frac{4\pi}{3}} Y_{1,0}(\theta, \phi)$$
(3.5)

$$\mathbf{r} \cdot \boldsymbol{\epsilon}_{z}^{\pm 1} = \mp \frac{1}{\sqrt{2}} (x + iy) = \mp r \frac{1}{\sqrt{2}} \sin \theta e^{\pm i\phi} = r \sqrt{\frac{4\pi}{3}} Y_{1,\pm 1}(\theta,\phi)$$
(3.6)

Where the $Y_{l,m}(\theta, \phi)$ are spherical harmonics and the angles θ, ϕ correspond to the usual definition of spherical coordinates.² The presence of these spherical

²For circular polarization, if the photon wavevector **k** is in the z direction, then **E** is in the x - y plane. For linear polarization, **E** must again be perpendicular to $\mathbf{k} = k\hat{\mathbf{e}}_z$, e.g. the x or y direction. But to retain the convention that J_z is diagonal in the $\{|JM_J\rangle\}$ basis, we can rotate the coordinate system so that $\mathbf{k} = k\hat{\mathbf{e}}_x$ and **E** (and thus ϵ^0) is in the z direction, giving the correct selection rule for linear polarization.

harmonics is responsible for polarization-dependent selection rules, which only allow certain transitions to take place. Because the states involved in the transition are products of radial and angular wave functions, according to $|\psi_i\rangle = |R_n^i\rangle |JM_J\rangle$, we see that $Y_{l,m}(\theta, \phi)$ acts only on the angular wave function and r on the radial wave function. Thus the absorption cross-section depends on the polarization by

$$\sigma^{\rm abs} \propto \left| \left\langle J' M_{J'} \right| \boldsymbol{\epsilon}_z^q \left| J M_J \right\rangle \right|^2. \tag{3.7}$$

The result is that $\langle J'M_{J'} | \epsilon_z^q | JM_J \rangle$ is only non-zero if the following relations are satisfied:

$$\Delta M = M_{J'} - M_J = q \tag{3.8}$$

$$\Delta J = J' - J = \pm 1,0 \tag{3.9}$$

$$\Delta S = 0, \quad \Delta L = \pm 1, \tag{3.10}$$

however $\Delta J = 0$ transitions are allowed only if $J \neq 0$. The selection rule $\Delta S = 0$ means no spin flips are allowed in the transition. In the normal XAS measurement, the polarization is linear (q = 0), so there are no transitions between different M_J states. On the other hand, for circularly polarized light $\Delta M = \pm 1$ for right (+) and left (-) polarizations. As we shall see later, these transitions between values of M_J are the basis of XMCD.

3.1.1 M-edge absorption

At the rare-earth M-edge, an electron in the 3d shell is excited to one of the empty 4f levels. This creates a hole in the core 3d states which can interact with the 4f electrons due to 3d-4f overlap. Because of this, the single electron picture of the absorption process is no longer valid, and the multi-electron initial and final states (labeled by the total S, L, J quantum numbers) must be considered. We denote this configuration dependent process by $4f^n \rightarrow 3d^94f^{n+1}$, where n is the number of 4f electrons in the ground state. The 3d hole then couples to the f^{n+1} electrons so that the total angular momentum of the final state results in a variety of multiplets with different



Figure 3.2: Calculated Sm^{3+} XAS spectra. Vertical bars represent dipole allowed transitions and their strength, the curves simulate broadening effects due to instrumental and lifetime effects, calculated using the program *Missing* [44].

term symbols ${}^{2S+1}L_J$. There can be a large number of multiplets, for example Sm^{3+} has 2,725 different multiplets in the final state $3d^9f^6$ configuration. The dipole selection rule $\Delta J = 0, \pm 1$ reduces the actual number of final states which are accessible to 946 for Sm^{3+} [43]. For this reason, the resulting absorption spectrum reflects the many possible final states; they can be included in σ^{abs} by a sum over the final states;

$$\sigma^{\text{abs}} = 4\pi^2 \hbar \omega \sum_{f} |\langle \psi_f | \mathbf{r} \cdot \boldsymbol{\epsilon} | \psi_i \rangle|^2 \,\delta(E_f - E_i - \hbar \omega) \rho(E_f). \tag{3.11}$$

Figure 3.2 shows a simulated absorption spectrum at the M-edge of Sm³⁺ for the three different dipole allowed transitions. The spectrum is composed of hundreds of closely spaced transitions, due to the hundreds of matrix elements $\langle \psi_f | \mathbf{r} \cdot \boldsymbol{\epsilon} | \psi_i \rangle$. The density of states factor $\rho(E_f)$ in the cross section only serves to broaden each line, however. The transitions are concentrated around the two edges, the lower energy M_5 corresponding to the hole with J = 5/2 and the M_4 corresponding to the 3*d* hole with J = 3/2. The rare-earth M-edge can be simulated using Cowans code [21], which is based on atomic multiplet calculations [45].

3.1.2 L-edge absorption

At the L-edge the $2p^6 \rightarrow 2p^55d^1$ transition is not dominated by multiplet effects, so the single electron picture of a core 2p electron transitioning into the band-like 5d states describes the absorption process. This is because the overlap between the 2p core hole and 5d states is small compared to the strong core-hole-4f interaction at the M-edge. The result is that the absorption crosssection measures the unoccupied partial density of states (PDOS) $\rho(E_f)$ of the 5d level;³

$$\sigma^{\rm abs} \propto \mathcal{M}\rho(E_f),\tag{3.12}$$

where $\mathcal{M} = |\langle \psi_f | \mathbf{r} \cdot \boldsymbol{\epsilon} | \psi_i \rangle|^2$ is approximately constant over the energy range of the absorption edge. Because of the band-like nature of the 5*d* states, band structure calculations are needed to simulate the PDOS. In the RENs the strong electron correlations from the 4*f* states have to be accounted for when calculating the PDOS, which makes band structure calculations difficult [14, 46].

3.1.3 Detection methods

At the M and L edges, indirect methods of measuring the absorption are used instead the transmission mode, where $I = I_0 e^{-\mu(E)}$. Once the absorption process takes place, the core hole can decay via radiative and non-radiative decay channels. The non-radiative channel is via Auger and Coster-Konig processes. The number of such secondary electrons produced is then proportional to the X-ray absorption cross section σ^{abs} , this is known as the total electron yield (TEY). The electrons are usually measured by the drain current or by using a

³The selection rules prevent transitions into the full unoccupied density of states.

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channeltron electron multiplier. The resulting intensity is then normalized to the incident beam. For an electron mean-free path λ_e and the X-ray photon absorption length λ_x (i.e. the inverse of the absorption coefficient, $\mu = \lambda_x^{-1}$) the absorption intensity is

$$I_{\text{TEY}} = I_0 G \frac{\lambda_e}{\lambda_e + \lambda_x \cos \theta}, \qquad (3.13)$$

where θ is the measured angle relative to the surface normal, I_0 is the incident beam intensity, and G is the electron gain factor. As long as $\lambda_x \cos \theta \gg \lambda_e$ the measured signal is proportional to the absorption coefficient, $I_{\text{TEY}} \propto \mu(E)$. Typically $\lambda_e \approx 1\text{-}3$ nm, while λ_x is generally of order 100 nm, though λ_x may decrease significantly at the absorption edge in rare-earths [45]. However even at the absorption edge $\lambda_x > \lambda_e$. In grazing incidence measurements λ_x may become comparable to λ_e and the spectrum can become distorted. [41, 47]. These effects must be corrected for when applying the sum rules, however for temperature or magnetic field dependent measurements these effects are less important.

When radiative decay occurs, the emitted X-rays can be measured via a channeltron electron multiplier. The photon flux is called total fluorescence yield (TFY). In the limit that the λ_x is larger than both the emitted fluorescence absorption length, $\lambda_{x'}$, and background fluorescence absorption length, λ_B ,

$$I_{TFY} = c_1 + c_2 \mu, (3.14)$$

where c_1 represents a constant background due to e.g. a capping layer or substrate [48]. Saturation effects are more common in the TFY mode due to the similar length scales of λ_x and $\lambda_{x'}$, and generally the sum rules are not applicable.

A variant of the TFY mode is the partial fluorescence yield (PFY), where specific fluorescence decay channels are measured with an energy selective spectrometer. For instance, at the rare-earth L_3 edge the most prominent radiative decay channel occurs when the $2p_{3/2}$ hole is filled with an electron transition



Figure 3.3: Electronic transitions corresponding to various emission lines, taken from [40]. The spectroscopic notation is used, where $K, L, M \dots = 0, 1, 2 \dots$ refers to s, p, d-states.

from a $3d_{5/2}$ state with the L α_1 emission line at 5,230 eV. Similarly, at the L₂ edge the L $_{\beta_1}$ emission line at 5,722 eV is the most prominent radiative decay channel (see Figure 3.3 for emission lines). This method has the advantage of removing unwanted background signals from different atomic species which have absorption edges close by, for instance in multilayers. Even if there are no nearby absorption edges, higher order harmonics in the X-ray beam can excite edges far away in energy resulting in unwanted spectral features, making PFY a very useful tool.

3.1.4 XMCD

The description of XAS in the preceding sections will simplify our discussion of XMCD, which is essentially an application of XAS. The XMCD signal ΔI can be defined as

$$\Delta I = I_{+}(\mathbf{H}) - I_{-}(\mathbf{H}), \qquad (3.15)$$

where I_{\pm} is the XAS spectrum taken with positive (q = +1) or negative (q = -1) helicity photons, and the magnetic field $\mathbf{H} = (0, 0, -H)$ is in the

 $-\hat{\mathbf{z}}$ direction. The photon momentum direction and spin quantization axis are taken in the $+\hat{\mathbf{z}}$ direction.⁴ This can equivalently be written as

$$\Delta I = I_{-}(-\mathbf{H}) - I_{+}(-\mathbf{H}), \qquad (3.16)$$

when the field is reversed. This definition corresponds to the difference between antiparallel and parallel arrangements of the spin and magnetic field.⁵ We will generally keep **H** fixed, so use the simpler notation I_{\pm} to refer to the absorption spectra taken with different polarizations. I_0 refers to the absorption spectra with linear polarization parallel to $\hat{\mathbf{z}}$.

3.1.5 The two-step XMCD model

The basic picture of XMCD is often described in a two step model [41], usually for transition metal systems. This standard view is not strictly applicable to the rare-earths, but nevertheless provides a useful intuitive picture of the XMCD process, and so we review XMCD in transition metal systems before describing the XMCD process in the rare-earths.

We consider XMCD at the L₂ and L₃ edge $2p \rightarrow 3d$ transitions which occur in the 3d transition metals. In the first step, a polarized photon excites an electron from the 2p state. The spin-orbit splitting of the 2p state means at the L₂ edge, where j = l - s = 1/2, the spin and orbital momentum are antiparallel, and at the L₃ edge, where j = 3/2, the spin and orbital moments are parallel. Photons of positive helicity q = +1 will have a higher transition probability of exciting spin-up electrons, and negative helicity photons (q = -1) will preferentially excite spin-down electrons (see Figure 3.4). This is because the matrix elements are largest for parallel helicity, spin, and orbital momentum.⁶

The second step of the process occurs when the spin-polarized photoelectrons transition into the unoccupied 3d states. If the bands are spin-polarized due to exchange splitting, the majority (spin-down in this case) and minority

 $^{^4} The$ helicity is defined as the projection of the photon spin onto its momentum vector $(\hat{\mathbf{p}}\cdot\mathbf{S})$

⁵The spin-moment is antiparallel to the expectation value of the spin : $\mathbf{m}_S = -2\mu_B \mathbf{S}$.

⁶Because the dipole operator $\mathbf{r} \cdot \boldsymbol{\epsilon}$ does not act on spin, but only on orbital angular momentum, the spin-orbit coupling of the core level is responsible for the spin polarization.

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Figure 3.4: A sketch of the XMCD process, showing only the dominant transitions into the unoccupied exchange-split d states. The asymmetry in absorption between x-rays with $q = \pm 1$ polarization results in the dichroic signal.

(spin-up) bands form. The excited 2p photoelectrons cannot change their spin due to the selection rule $\Delta S = 0$, so the unoccupied d states act as a spin detector. The imbalance in occupation is proportional to the magnetization $(|\mathbf{m}| \propto \rho^{\uparrow}(E) - \rho^{\downarrow}(E))$, and thus the imbalance in I_{\pm} is proportional to the magnetic moment per atom projected on the quantization axis; $\Delta I \propto |\mathbf{m}| \cos \varphi$, where φ is the angle between the magnetic field and quantization axis. Because the exchange splitting ε is small compared to the overall bandwidth, we can write $\rho^{\uparrow}(E) = \rho^{\downarrow}(E + \varepsilon)$, and expanding to first order find $\Delta I \propto \frac{d\rho^{\downarrow}(E)}{dE}$. The XMCD signal is thus proportional to the derivative of the density of states of the final d levels. This is observed experimentally in Chapters 5 and 6 at the rare-earth L-edge where the XMCD has a dispersive lineshape.

To summarize, circular dichroism at a spin-orbit split edge originates from two effects: the spin-orbit splitting of the core levels and the exchange-splitting of the unoccupied final states. The process is of course element specific, which gives XMCD a major advantage over standard magnetometry methods which cannot distinguish individual elemental contributions to the magnetization.



Figure 3.5: Calculated atomic Gd 5*d* radial wave functions with spin up and spin down, showing the spin-up wave function pulled slightly closer to the nucleus, from Ref. [49].

3.1.6 Rare-earth L-edge XMCD

The rare-earth L-edge probes $2p \rightarrow 5d$ transitions. As we saw in Chapter 2, the unoccupied 5d states mediate exchange between ions in a superexchange process. The 5d XMCD signal is thus a measure of this indirect exchange mechanism. A further difference from the transition metal case is that the matrix elements of the transition are spin-dependent.

In the RENs, the 5d bands are exchange-split into majority and minority bands. These bands overlap with the 4f states enough that there is an exchange interaction between the 5d and 4f majority spin bands. Because the exchange energy is negative, the 5d majority band then contracts towards the nucleus, which increases the overlap with the 4f band and lowers the energy. This can be seen in Figure 3.5, where a calculation for atomic Gd shows the contraction of the Gd 5d spin-up radial wavefunction.

The contracted 5*d* majority band then overlaps more strongly with the 2*p* orbitals, leading to an enhancement in transitions through the majority spin channel, resulting in the spin dependence of the $2p \rightarrow 5d$ transition matrix elements. This spin-dependence of the matrix elements leads to a large branching ratio between the L₂ and L₃ edges, with L₂/L₃ ~ 10 for the light rare-earths,

while the ratio is reversed for the heavy rare-earths. This makes direct application of the sum rules impossible at the rare-earth L-edge, giving the wrong sign and magnitude of the 5d spin and orbital moments [50–53].

Additionally, an electric quadrupole transition $(2p \rightarrow 4f)$ is also visible in the XMCD spectrum of the light rare-earths due to relatively weak dipole transition contributions [53], allowing a direct probing of the 4f magnetism. The quadrupole feature is usually much weaker than the dipole transitions but is often still visible. In Chapter 5 we shall see that the $2p \rightarrow 4f$ quadrupole transition at the Sm L₃ edge is visible.

3.1.7 Rare-earth M-edge XMCD



Figure 3.6: The initial J = 7/2 (f^{13} configuration) and final state J = 5/2 ($d^9 f^{14}$ configuration) multiplet of Yb³⁺. When T = 0, only the J = M = 7/2 ground state is occupied, and there is only one transition (bold) to the J' = M' = 5/2 final state. After Goedkoop *et al.* [54]

In M-edge XMCD of the rare-earths, the single-electron band picture we described previously is complicated by the multiplet structure. In this case, it is

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easier to view the two-step XMCD process from an atomic point of view instead of the energy band point of view, though the two pictures are equivalent. We give an example of the rare-earth XMCD process in the simplest case of Yb³⁺, with a ground state f^{13} multiplet given by S = 1/2, L = 3, J = 7/2 [54]. The same principles apply to the other rare-earths, which have much larger number of dipole-allowed transitions.

We start with the Hunds' rule ground state multiplet, in the presence of a magnetic field. The presence of **H** lifts the 2J + 1 degeneracy of the Jmultiplet, and the sublevels are split according to $M = -J, -J + 1, \ldots, J$ (see Figure 3.6). In the ground state, only the lowest energy M level is occupied, given by M = 7/2 when **H** is in the $-\hat{z}$ direction. From this J = M = 7/2level the dipole selection rule states that $\Delta J = 0, \pm 1$, and depending on the photon helicity, $\Delta M = \pm 1$.

If we examine the possible final states, we see there is only one, $3d^9f^{14}$, which is equivalent to a single 3d hole with quantum numbers S = 1/2, L = 2, J = 5/2. This means that there is only one allowed transition with $\Delta J = -1$ and $\Delta M = -1$ to the final state J = M = 5/2 level. Thus photons with q = +1 excite no photoelectrons and there is no absorption for I_+ . The XMCD spectrum is just $\Delta I = -I_-$ and consists of one transition (Figure 3.6). The same reasoning determines the transitions from Sm^{3+} , with a ground state labeled by J = M = 5/2 in a magnetic field. However there are 946 final states, with varying strengths, making the XMCD spectrum far more complex than for Yb³⁺. For example, atomic multiplet calculations of the XMCD spectra for Gd³⁺ and Sm³⁺ are shown in Figure 3.7, showing the three separate ΔJ contributions to the total XMCD signal at the M-edge.

3.1.8 XMCD sum rules

The resulting XMCD spectrum ΔI can be related to the spin $(m_S = -2\mu_B \langle S_z \rangle)$ and orbital $(m_L = -\mu_B \langle L_z \rangle)$ moments of the *occupied* states via the sum rules developed by Thole *et al.* [55] and Carra *et al.* [56]. We write them specifically for the rare-earth M-edge for simplicity, though they can be written similarly for any edge. In the case of the M-edge, the moments obtained from the sum



Figure 3.7: Atomic multiplet calculations of Gd^{3+} and Sm^{3+} XMCD spectra including simulated lifetime broadening and instrumental resolution broadening. The dipole-allowed transitions to the final states with $\Delta J = 0, \pm 1$ are shown, with the sum over all these final states representing the XMCD spectrum. Calculated using *Missing* [44].

rules refer to the occupied 4f states only. The isotropic absorption can be written as $I_S = I_+ + I_- + I_0$, and

$$A_{4,5} = \int_{M_4,M_5} dE \ I_S, \qquad \Delta A_{4,5} = \int_{M_4,M_5} dE \ \Delta I, \qquad (3.17)$$

are the integrals of I_S and ΔI over either the M_4 or M_5 edge energies. The orbital sum rule is given by

$$\langle L_z \rangle = n_h \frac{\Delta A_4 + \Delta A_4}{A_4 + A_5} \tag{3.18}$$

where $n_h = 14 - n$ is the number of 4f shell holes in the initial state (denoted $4f^n$). The spin sum rule is slightly more complex and is given by

$$\langle S_z \rangle = n_h \frac{\Delta A_5 - \frac{3}{2} \Delta A_4}{A_4 + A_5} + 6 \langle T_z \rangle, \qquad (3.19)$$

where T_z is the magnetic dipole operator which is related to the asphericity of the charge distribution. For the rare-earths this term is significant and must

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be calculated in order to apply the sum rules. In 3*d* transition metal systems the magnetic dipole contribution is very small and often ignored. There are many limitations to applying the sum rules, as outlined in de Groot & Kotani [42], however they provide the theoretical link between the XMCD spectra and the orbital and spin moments. In the RENs information on the overall sign of $\langle L_z + 2S_z \rangle$ can be determined from XMCD. This is especially important in the case of SmN, where the the spin and orbital moments are nearly equal in magnitude but have opposite signs. By looking at the overall sign of the ΔI spectrum can tell if m_L or m_S is larger.

3.2 Thin Film Growth

The growth of rare-earth nitride samples is a challenge due to the propensity for the rare-earth elements to oxidize when in atmosphere, which is especially strong in the light rare-earths. In order to prevent oxidation of samples special preparation conditions must be in place. The methods of growing high quality rare-earth nitride thin films have recently been established in the laboratory at Victoria University, and are reviewed in detail by Natali *et al.* [2]. The most successful methods used include molecular beam epitaxy, pulsed-laser deposition, and dc/rf magnetron sputtering. The benefits of these methods are the use of high and ultra-high vacuum systems as inert gas environments which prevent contaminants in the growth process. In this thesis, we use a molecular beam epitaxy technique (MBE).

In the MBE growth of REN thin films, an ultra-high vacuum chamber with a base pressure of $\leq 10^{-8}$ Torr is used to minimize contaminants and prevent oxidation of the highly reactive rare earths. The basic operating principle can be summarized in the following way. High purity rare-earth metals are heated to the point of evaporation with either an electron gun or by using a thermal evaporator (a boron nitride crucible heated with tungsten filaments). At the same time ultra-high purity N₂ gas is released into the chamber at a pressure between 10^{-5} and 10^{-4} Torr (another variant uses an NH₃ nitrogen precursor [13]). A crystalline substrate is then mounted on a rotating platform and the REN forms on the surface of the substrate. The evaporation rate of the RE metal is measured using a quartz crystal balance. The temperature of the substrate, N₂ pressure, and evaporation rate all must be carefully controlled to achieve high quality films. Epitaxial REN films are achieved at higher growth temperatures, while room temperature growth generally leads to textured polycrystalline films [57]. The number of nitrogen vacancies also depends on the growth parameters, and thus strongly affect the electric transport properties, while the magnetic properties are affected to a lesser degree. For GdN, the Curie temperature is seen to vary from 50 K with low carrier concentration (< 10^{18} cm⁻³) to 70 K for concentrations greater than 3×10^{20} cm⁻³. The mechanism is thought to be due to the formation of magnetic polarons, and not an RKKY exchange mechanism [12, 13].

For *ex-situ* study, however, a passivating capping layer must be used to prevent oxidation of the film. Typical choices are insulating GaN or AlN films, grown with the same technique as the REN films. Low energy ions from a Kaufman type ion source are used for the growth of GaN and AlN films, as well as EuN.

The choice of substrates plays an important role in the REN film growth. The rocksalt structure of the RENs suggests the use of substrates with cubic structure, however MgO and ytrria stabilized zirconia (YSZ) have shown the propensity for oxygen contamination due to oxygen diffusing into the REN film during high temperature growths. Non-cubic crystal structure substrates may also be used. High quality epitaxial REN films have been demonstrated on commercially available single crystal *c*-plane GaN and AlN buffer layers (100 nm thick) on sapphire substrates, while sapphire substrates may also be used to produce highly textured polycrystalline samples. The six-fold hexagonal symmetry results in a [111] oriented growth direction for the rocksalt structure RENs.

In this thesis, the specific growth conditions of each sample are listed in the experimental details section of the corresponding Chapter. Chapter 3 Experimental Techniques

Chapter 4

SmN and NdN Magnetism

4.1 Introduction

In this chapter we investigate the ferromagnetic state of SmN and NdN using atomic calculations and compare with experimental data. These calculations consider only the 4f states, ignoring other possible contributions such as conduction electron polarization to the magnetic moment. In the calculations we explore the results when excited J multiplets and crystal field interactions are incorporated. We employ methods developed by Buschow, Dewijn *et al.* [35, 58–60] for Sm systems, which allows for calculation of crystal fields within arbitrary multiplets. We also use a self-consistent method to deal with the exchange interaction [29, 61] and carry out the first detailed study on SmN and NdN using this method.

The motivation for this endeavor is twofold. First, we would like to compare these crystal field calculations to band-structure calculations previously carried out on the RENs. Only a few such band-structure calculations exist for the RENs, and the calculated magnetic properties contradict experimental results in some cases. Second, a better understanding of how the spin and orbital moments contribute to the net moment in SmN and NdN will be useful for the XMCD study of SmN/GdN and NdN/SmN superlattices in Chapters 5 and 6.

There are relatively few theoretical studies of NdN and SmN, compared to GdN. This is perhaps because GdN is in some ways simpler, having the S = J = 7/2, L = 0 Hund's rule ground state. This L = 0 state means that there is no spin-orbit coupling, thus the orbital wave function is spherical, leading to nearly zero interaction with the crystal field.¹ In comparison the other RENs have $L \neq 0$ orbital wave functions, and in addition strong spinorbit coupling means that any effects from the crystal field are felt by both orbital and spin moments.

For SmN and NdN then, the coupling of the orbital moment to the lattice (crystal field interaction) and the spin-orbit coupling may have significant effects on the resulting magnetic properties in both ferromagnetic and paramagnetic phases. Our aim then, is to determine the degree to which the crystal field arising from the N ions influences the 4f magnetic moments.

The calculations in the following were all carried out with original code written in Python by the author.

4.2 SmN Magnetism

4.2.1 Experimental background

Before proceeding to the calculations, we review some experimental SmN data. The most careful examination of SmN magnetization in thin films was carried out by Meyer *et al.* [30], who demonstrated that SmN has a ferromagnetic ground state with an ordered moment of $m = 0.035 \ \mu_B$ per Sm³⁺ below the Curie temperature of 27 ± 3 K. Some of the low temperature hysteresis curves are shown in Figure 4.1. We note that this moment is considerably smaller than the free-ion moment of $\mu_B g_J J = 0.74 \ \mu_B$. The paramagnetic susceptibility follows a Curie-Weiss law with a temperature independent van Vleck contribution, with an effective paramagnetic moment of $0.45 \ \mu_B$ per ion, smaller than the paramagnetic $\mu_B g_J \sqrt{J(J+1)} = 0.85 \ \mu_B$ free-ion value. These findings agreed well with an earlier study of SmN that found an ordered moment of less than 0.1 μ_B per ion and observed semiconducting behavior over the measured temperature range [5].

The paramagnetic moment in Ref. [30] was interpreted within a crystal

 $^{^1\}mathrm{In}$ this case the small magnetic anisotropy is mainly due to dipolar interactions between ions.

field model assuming that the cubic crystal field in SmN splits the ground state J = 5/2 level into a doubly degenerate Γ_7 state and a four-fold degenerate Γ_8 state. Assuming only the Γ_7 doublet was occupied at temperatures just above the ordering temperature, the effective paramagnetic moment was calculated as 0.41 μ_B , using first order perturbation theory to calculate the susceptibility. The calculation was equivalent to restricting the sum over the Zeeman substates used in the derivation of the free-ion paramagnetic moment (Chapter 2). The good agreement with this calculated paramagnetic moment and the observed value suggests that the crystal field is significant and should be taken into account when calculating the ground state magnetic moment.

In an effort to separate the spin and orbital contributions to the magnetization, an XMCD study was carried out on a homogeneous SmN sample [19]. This study found that the orbital moment in SmN is parallel to the net magnetization, making SmN an orbital-dominant ferromagnet. Other Sm³⁺ systems do not necessarily share this orbital-dominant feature, which depends on the bonding environment of the ion and the contribution of conduction electrons. SmAl₂ is known to be an orbital dominant ferromagnet, with a moment of $0.26 \ \mu_B$, while SmZn and SmCd have their net magnetization antiparallel to the orbital moment [29]. However, we note that in distinction to SmN, all these systems are metallic, and the effects of conduction electron polarization and screening are quite different in SmN.

4.2.2 SmN calculations

Many of the properties of SmN are dictated by the Sm³⁺ ion, which has been studied in a number of compounds in the past, including metallic Laves-phase compounds such as SmAl₂, Sm_{1-x}Gd_xAl₂, and Sm_{1-x}Nd_xAl₂ [35, 58, 60, 62– 65], CsCl-type structure SmZn and SmCd [29], and Sm metal [61]. One conclusion to be drawn from these studies is that the magnetic properties of Sm³⁺ ions in various compounds are influenced to a significant degree by the first excited J = 7/2 states, in addition to the ground J = 5/2 state. There are two reasons for this, 1) the exchange and Zeeman terms along with the crystal field of the surrounding N ions cause admixtures of the ground and excited



Figure 4.1: Plots taken from Meyer *et al.* [30] showing magnetization measurements of SmN. a) Susceptibility shows a fit to Curie-Weiss with temperature independent van Vleck contribution. b)–d) Hysteresis curves with field cooling in 6 T (white squares) and with zero field cooling (red circles). The coercive field at 2 K is greater than 6 T, preventing significant hysteresis, however the shift in the field cooled loop at 2 K shows that ferromagnetic order is present.

states, and 2) the small ground state g factor of 2/7 for Sm³⁺ means the matrix elements within the J = 5/2 state are small compared to matrix elements between the ground and excited states. We shall demonstrate these statements explicitly in the following.

For SmN we are interested in understanding the origin of the small ferromagnetic moment of about 0.035 μ_B . Calculations carried out by Larson et al. [14] using density functional theory calculations in the LSDA+U approximation found the same magnitude ferromagnetic moment, however they found that the net moment was parallel to the 4f spin moment, in contradiction to experimental results [19]. The 4f orbital and spin moments were calculated to be $m_L^{4f} = -4.85 \ \mu_B$ and $m_S^{4f} = 4.91 \ \mu_B$. Small contributions were also found to the Sm 5d states (0.105 μ_B parallel to m_S^{4f}) and from the N 2p states $(0.136 \ \mu_B \text{ parallel to } m_L^{4f})$. It is interesting to note that these moments were calculated by assuming a "modified" Hund's rule ground state as a starting point for the calculation², assuming not that L is a maximum (Hund's second rule, as in Chapter 2) but that L_z should be a maximum in the ferromagnetic phase. In this case they a priori assume the z components of the 4f moments are at the maximum, and let the calculation run until convergence. However, it is not clear that this is a good starting point. To gain some insight into we turn to the atomic 4f Hamiltonian.

4.2.3 Calculation procedure

To calculate the spontaneous ferromagnetic moment of SmN effects, we consider the single ion Hamiltonian

$$\mathscr{H} = \mathscr{H}_{\rm SO} + \mathscr{H}_{\rm ex} + \mathscr{H}_{\rm CF}, \tag{4.1}$$

where the terms correspond to contributions from the 4f spin-orbit coupling, exchange coupling, and crystal field interaction. In the Sm³⁺ ion, the J = 5/2ground state is separated by about 1500 K from the first excited J = 7/2 state

²They found that a guess of the initial state following the modified Hund's rules symmetry yielded a lower energy solution compared to an initial state which obeyed strict cubic symmetry.

Chapter 4 SmN and NdN Magnetism

[29, 30]. This seems to be large enough a separation to ignore any contribution from the J = 7/2 state when considering that the ferromagnetic phase of SmN occurs below 30 K. However, in the Sm³⁺ ion the inclusion of this state is known to be important[29, 35]. We begin by examining the simplest case, where there is no external field or crystal field. The Hamiltonian (4.1) including only spinorbit coupling and exchange can then be written as

$$\mathscr{H} = \Lambda \mathbf{L} \cdot \mathbf{S} + \mathbf{H}_{\mathrm{ex}} \cdot \mathbf{S}, \qquad (4.2)$$

The spin-orbit coupling constant Λ is approximately $\Lambda = 430$ K, calculated from a knowledge of the energy splittings between J multiplets, which is expressed as $\Delta E = E_{J+1} - E_J = \Lambda(J+1)$, where $\Delta E = 1500$ K, [29, 30].

The second term represents the effect of inter-ion exchange through an exchange field \mathbf{H}_{ex} which is defined by $\mathbf{H}_{\text{ex}} = -2J_{\text{ex}} \langle S_z \rangle$, where J_{ex} is the exchange energy and $\langle S_z \rangle$ is the expectation value of the spin operator. This is just the mean-field approximation discussed in Chapter 2. We note that while the mean-field approximation is often written with the molecular field proportional to the magnetization, this is only true if there is no orbital moment. The exchange acts only on the spin.

The constant $J_{\text{ex}} = 7.9$ K is estimated from the SmN $\theta_p \approx 27$ K using the mean-field approximation (Chapter 2).³ However, we note that the meanfield theory we derived in Chapter 2 only considered θ_p in the case of a single multiplet. For Sm³⁺, there is a temperature independent contribution to the susceptibility χ_{VV} . In this case, the mean-field relationship described in Chapter 2 is modified by the van Vleck susceptibility χ_{VV} :

$$\frac{1}{\chi} = \frac{1}{\chi_0} - \lambda = \frac{1}{\chi_{CW} + \chi_{VV}} - \lambda, \qquad (4.3)$$

where $\lambda = (V/N)2J_{ex}(g_J - 1)^2/(g_J\mu_B)^2$. This changes the relationship $\theta_p = 2J_{ex}(g_J - 1)^2J(J + 1)/3k_B$ slightly, and thus our estimate of J_{ex} . Solving for

³In this chapter Kelvins are the most convenient unit to represent the exchange constant, where k_B 300 K ≈ 25 meV.

 J_{ex} gives

$$J_{ex} = \frac{3}{2} \frac{k_B \theta_p}{(g_J - 1)^2 J (J + 1)} \left[\frac{1}{1 + 12k_B \theta_p / \Delta E} \right].$$
 (4.4)

where $\Delta E = 1500$ K. The term in brackets is the correction due to the van Vleck contribution, which can be viewed as a first order correction to the exchange constant due to the first excited J multiplet. Only for Sm and Eu is this correction large enough to be considered, and in the case of Sm³⁺ it gives a correction factor of $[1+12k_B\theta_p/\Delta E]^{-1} = 0.83$, yielding $J_{ex} = 7.9$ K. We note that using the data from Meyer, the estimate of θ_p was within uncertainty equal to T_C . While the correction here does not significantly change the results of the following calculations, we include it demonstrate how excited J-multiplets can influence the exchange constant.

In order to diagonalize \mathscr{H} , we need to consider two things; 1) an initial value of $\langle S_z \rangle$, and 2) the basis states to include. The first issue can be addressed by adopting a self-consistent routine where an initial guess of $\langle S_z \rangle$ is made. Then \mathscr{H} can be diagonalized, yielding the energy eigenvalues and eigenstates from which we can then calculate the expectation value $\langle S_z \rangle$. This value is then put back into \mathscr{H} and the process repeated until the calculated expectation value differs from the initial by $|\langle S_z \rangle_{\text{out}} - \langle S_z \rangle_{\text{in}}| < \epsilon$, where ϵ is some sufficiently small number. The expectation values can then be used to calculate the total ferromagnetic moment

$$m = -\mu_B \left\langle L_z + 2S_z \right\rangle. \tag{4.5}$$

The next question is which basis states to use. There are two choices, the so-called JM-basis or M_LM_S -basis (as discussed in Chapter 2). Both are bases are complete, however we use the JM basis for convenience, primarily because crystal field calculations are simplified in this basis. This is the normal scheme used for rare-earths because \mathcal{H}_{SO} is diagonal in this basis, and is generally much larger than exchange, Zeeman, and crystal field energies. In transition metal systems where the Zeeman contribution is dominant, it is more

Chapter 4 SmN and NdN Magnetism

convenient to use the $M_L M_S$ basis. If we consider only a $single^4 J$ multiplet, the matrix elements of the angular momentum operators can be derived via the Wigner-Eckart theorem [23, 32]:

$$\langle J'M_{J'} | \mathbf{L} \cdot \mathbf{S} | JM_J \rangle = \frac{1}{2} \left[\mathbf{J}^2 - (\mathbf{L}^2 + \mathbf{S}^2) \right] \delta_{M_{J'}, M_J}$$

$$= \frac{1}{2} \left[J(J+1) - (L(L+1) + S(S+1)) \right] \delta_{M_{J'}, M_J}$$
(4.6)

$$\langle J'M_{J'}|S_z|JM_J\rangle = (g_J - 1)M_J \,\delta_{M_{J'},M_J}$$
(4.7)

$$\langle J'M_{J'}|L_z|JM_J\rangle = (2-g_J)M_J\,\delta_{M_{J'},M_J}$$
(4.8)

$$\langle J'M_{J'}|L_z + 2S_z |JM_J\rangle = g_J M_J \,\delta_{M_{J'},M_J},\tag{4.9}$$

where the delta functions $\delta_{M_J,M_{J'}}$ show that the matrix elements are diagonal with respect to M_J .

We are interested in the ground state ferromagnetic moment as $T \rightarrow 0$, which we can compare with low temperature experimental data. This means we diagonalize \mathscr{H} and calculate expectation values within the ground state only, without any thermal averaging. If we restrict to only the J = 5/2multiplet, the Hamiltonian (4.5) is already diagonal, and the ground state magnetic moment is simply given by Equation (4.9),

$$m = -\mu_B \langle JM_J | L_z + 2S_z | JM_J \rangle = -\mu_B g_J M_J \approx 0.714 \ \mu_B, \tag{4.10}$$

where the ground state is denoted by J = 5/2 and $M_J = -5/2$. This is just the saturation moment $g_J \mu_B J$, which is 20 times larger than the experimentally observed 0.035 μ_B per ion. This is because we have neglected higher multiplets and crystal field effects. We note that the inclusion of the exchange term has

⁴When considering excited J multiplets, there is no simple relationship linking $\langle L_z + 2S_z \rangle$ and $\langle S_z \rangle$, and the ratio $\langle L_z \rangle$ and $\langle S_z \rangle$ is no longer fixed, but depends on the parameters of the Hamiltonian.
no effect on the ground state if only a single multiplet is considered.

4.2.4 Excited states

If we now include the J = 7/2 and higher multiplets, the Hamiltonian acquires off-diagonal terms. The exchange term, proportional to S_z , has matrix elements connecting states with J differing by 1, and with the same M value. In fact, we find that the matrix elements of the total moment $\langle S_z + 2L_z \rangle$, within the J = 5/2 multiplet (which are of order g_J) are smaller than the matrix elements connecting the J = 5/2 and J = 7/2 multiplets. We first show how to calculate the matrix elements for arbitrary J using the algebraic techniques originally developed by Racah [66]. In particular we follow the approach of Buschow, Dewijn *et al.*[35, 58–60], who have shown how to carry out crystal field calculations within arbitrary multiplets (See Appendix A for the derivation). In this approach we can calculate the matrix elements of S_z and L_z as:

$$\langle JM | S_z | J'M' \rangle = (-1)^{J-M+L+S+J'+1} \sqrt{(2J+1)(2J'+1)} \\ \times \begin{pmatrix} J & 1 & J' \\ -M & 0 & M' \end{pmatrix} \begin{cases} S & S & 1 \\ J & J' & L \end{cases} \sqrt{S(S+1)(2S+1)},$$
(4.11)

and

$$\langle JM | L_z | J'M' \rangle = (-1)^{J-M+L+S+J'+1} \sqrt{(2J+1)(2J'+1)} \\ \times \begin{pmatrix} J & 1 & J' \\ -M & 0 & M' \end{pmatrix} \begin{cases} L & L & 1 \\ J & J' & S \end{cases} \sqrt{L(L+1)(2L+1)},$$
(4.12)

where the term in parenthesis is the Wigner 3j symbol, proportional to a Clebsch-Gordan coefficient:

$$\begin{pmatrix} J_1 & J_2 & J_3 \\ M_1 & M_2 & M_3 \end{pmatrix} = \frac{(-1)^{J_1 - J_2 - M_3}}{\sqrt{2J_3 + 1}} \langle J_1 M_1 J_2 M_2 | J_3 - M_3 \rangle.$$
(4.13)

The term in braces is the Wigner 6j symbol, which is equal to a sum over products of Wigner 3j symbols (see, e.g. Cowan [21] for various properties of

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the Wigner symbols). Values of the symbols can be found in tables [21], however algorithms for calculating them are available, e.g., in the SymPy Wigner package [67], written in Python.

The properties of the 3j and 6j symbols result in the selection rules $\Delta J = J' - J = 0, \pm 1$ and M = M'. The matrix representation S_z or L_z will then be composed of pseudo-diagonal submatrices. For example, if we consider the lowest three multiplets (J = 5/2, 7/2, 9/2) of Sm³⁺, then the matrix representation of S_z has the following structure:

$$[S_z]_{24\times24} = \begin{bmatrix} [J=5/2]_{6\times6} & [\Delta J=\pm 1]_{6\times8} & [0]_{6\times10} \\ [\Delta J=\pm 1]_{8\times6} & [J=7/2]_{8\times8} & [\Delta J=\pm 1]_{8\times10} \\ [0]_{10\times6} & [\Delta J=\pm 1]_{10\times8} & [J=9/2]_{10\times10} \end{bmatrix}, \quad (4.14)$$

where each of the nine submatrices is diagonal with respect to M. The submatrices corresponding to the same J are square matrices, while the off diagonal submatrices ($\Delta J = \pm 1$) involving transitions between multiplets have dimension (2J + 1) × (2J' + 1). The $\Delta J = \pm 2$ matrix elements are all zero by the properties of the 3j and 6j symbols.

Figure 4.2 shows the sign and magnitude of all the matrix elements of S_z , L_z and M_z within the J = 5/2, 7/2, 9/2 multiplets. In this figure one can observe the matrix elements of $L_z + 2S_z$ connecting the J = 5/2 and J = 7/2 states are larger than the matrix elements with the J = 5/2 state. This is due to the small g factor of the J = 5/2 state, and is one reason why incorporating higher multiplets is necessary when dealing with the Sm^{3+} ion.

Now that we have the tools to evaluate all the matrix elements, we can find the eigenstates and eigenvalues of the Hamiltonian (4.1) in the representation which includes excited states. Like in the previous section, we calculate only the ground state expectation value of $L_z + 2S_z$. We label the eigenstates of \mathscr{H} as $|\psi_i\rangle$ with associated eigenvalues E_i , which satisfy

$$\mathscr{H} \left| \psi_i \right\rangle = E_i \left| \psi_i \right\rangle. \tag{4.15}$$

These eigenstates can be written as a linear combination of the basis states



Figure 4.2: The matrix elements of S_z , L_z and $L_z + 2S_z$ with for the lowest three multiplets, J = 5/2, 7/2, 9/2.

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J multiplets	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$
5/2	-1.786	4.286	0.714
5/2, 7/2	-1.852	4.352	0.648
5/2, 7/2, 9/2	-1.852	4.352	0.648

Table 4.1: Expectation values based on number of multiplets included.

 $|JM_J\rangle;$

$$|\psi_i\rangle = \sum_{J=5/2}^{9/2} \sum_{M_J=-J}^J C^i_{J,M_J} |JM_J\rangle.$$
(4.16)

where the C_{J,M_J}^i are the coefficients found in the diagonalization process. We are interested in the ground state $|\psi_0\rangle$ which has the lowest energy eigenvalue, E_0 . In this case the expectation value of S_z can be calculated as

$$\langle \psi_0 | S_z | \psi_0 \rangle = \sum_{J=5/2}^{9/2} \sum_{M_J=-J}^{J} \sum_{J'=5/2}^{9/2} \sum_{M_{J'}=-J'}^{J'} C_{J,M_J}^{*0} C_{J',M_{J'}}^0 \\ \times (-1)^{J-M_J+L+S+J'+1} \sqrt{(2J+1)(2J'+1)} \\ \times \begin{pmatrix} J & 1 & J' \\ -M_J & 0 & M_{J'} \end{pmatrix} \begin{cases} S & S & 1 \\ J & J' & L \end{cases} \sqrt{S(S+1)(2S+1)} \\ \times \delta_{J,J'\pm 1}, \delta_{M_J,M_{J'}}. \end{cases}$$
(4.17)

The properties of the 3j symbol make the matrix element zero unless $M_J = M_{J'}$ and $J' = J \pm 1$, this has been incorporated explicitly via the delta functions. Calculating the expectation values of L_z and $L_z + 2S_z$ follows similarly.

After carrying out the self-consistent calculation, we find that by including the J = 7/2 and J = 9/2 states in addition to the ground state, we obtain $\langle \psi_0 | L_z + 2S_z | \psi_0 \rangle = 0.648$, which is about 10% smaller than the saturation value of 0.714. This is primarily due to the influence of the J = 7/2 multiplet, as to the quoted precision $\langle \psi_0 | L_z + 2S_z | \psi_0 \rangle = 0.648$ is returned without inclusion of the J = 9/2 multiplet, as shown in Table 4.1.

We can see that there is some reduction of the ground state magnetic moment due to the exchange interaction mixing in contributions from the J = 7/2 multiplet. However, there is no further reduction in the moment by inclusion of the higher multiplets, so a simple exchange mechanism is not enough to explain the small ferromagnetic moment of the SmN. However, we have so far neglected the effects of the crystal field, which are known to be important in rare-earth elements, and which we will explore in the next section.

We note that if the spin orbit coupling is very small, and acts only as a perturbation to the exchange term, then the moment is reduced to zero when higher multiplets are included. This is because for small spin-orbit coupling, L_z and S_z take on fixed values of M_L and M_S (i.e $L_z |\psi\rangle = M_L |\psi\rangle$ and $S_z |\psi\rangle =$ $M_S |\psi\rangle$), and the ground state then has $M_L = 5$ and $M_S = -5/2$, which gives zero net moment. This seems to be equivalent to the modified Hund's rules given in Larson *et al*[14], where they assume that $|L_z|$ should be a maximum in the ferromagnetic state.

4.2.5 SmN crystal field

In this section we incorporate the crystal field terms following the discussion in Chapter 2. The crystal field further mixes the J = 5/2 ground state with the higher multiplets due to off-diagonal terms in the Hamiltonian. We choose the z axis to be along the [111] direction, which is the easy axis if the anisotropy is only due to the single-ion anisotropy.⁵ The crystal field Hamiltonian is given by [34, 35]

$$\mathscr{H}_{CF} = -\frac{2}{3}A_4 \sum_{i} \left(f_{40}(\mathbf{r}_i) - 20\sqrt{2}f_{43}(\mathbf{r}_i) \right) + \frac{16}{9}A_6 \sum_{i} \left(f_{60}(\mathbf{r}_i) + \frac{35\sqrt{2}}{4}f_{63}(\mathbf{r}_i) + \frac{77}{8}f_{66}(\mathbf{r}_i) \right),$$
(4.18)

where the Tesseral harmonics $f_{kq}(\mathbf{r}_i)$ described in Chapter 2 are tabulated in Hutchings [34], and A_4 and A_5 are the crystal field parameters. The sum is over the five 4f electrons. To calculate the matrix elements of \mathscr{H}_{CF} we

⁵This was reported in [58] for some Sm systems with similar parameters, and here we also found that choosing z parallel to [001] gave a higher ground state energy. This gave moments differing by no more than 15 %, which is not large given experimental uncertainties and the neglect of other contributions to the net moment.

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must consider the **r**-dependence, which means that the radial part of the 4f wave function, which we denote by $\Psi(4f^n)$, must be included. For example, in Chapter 2 we saw that $f_{kq}(\mathbf{r}_i) \propto r^k [Y_k^{-q}(\theta, \phi) + (-1)^q Y_k^q(\theta, \phi)]$, so a typical matrix element to be calculated is given by

$$\langle \Psi(4f^{n})JM| \sum_{i} r_{i}^{k} Y_{k}^{q}(\theta_{i},\phi_{i})|\Psi(4f^{n})J'M_{J'}\rangle =$$

$$(-1)^{J-M+L+S+J+k} \sqrt{(2J+1)(2J'+1)} \times \begin{pmatrix} J & k & J' \\ -M & q & M' \end{pmatrix}$$

$$\times \left\{ \begin{array}{ccc} L & L & k \\ J & J' & S \end{array} \right\} \langle \Psi(4f^{n})L|| \sum_{i} r_{i}^{k} Y_{k}||\Psi(4f^{n})L\rangle.$$

$$(4.19)$$

where the reduced matrix element $R_{k,n} = \langle \Psi(4f^n)L||\sum_i r_i^k Y_k||\Psi(4f^n)L\rangle$ is independent of q but does depend on the number n of 4f electrons (n = 5for Sm³⁺). It has been calculated for all of the rare-earths in [35] as $R_{k,n} =$ constant $\times \langle r^k \rangle$. Appendix A discusses the evaluation of $R_{k,n}$ and lists the $R_{k,n}$ values for Sm³⁺ and Nd³⁺. The selection rules from the 3j and 6j symbols tell us that q = M - M', $|J - J|' \leq k \leq J + J'$, and $k \leq 2L$. We are now in a position to calculate the matrix elements of Equation (4.18). However, we have not calculated the radial integrals $\langle r^k \rangle$, and instead factor them out along with the constants A_k . In this way an arbitrary matrix element of \mathscr{H}_{CF} has the form

$$\langle JM | \mathscr{H}_{CF} | J'M_{J'} \rangle = aA_4 \langle r^4 \rangle + bA_6 \langle r^6 \rangle, \qquad (4.20)$$

where a, b are real numbers. By doing this, we leave $A_4 \langle r^4 \rangle$ and $A_6 \langle r^6 \rangle$ being adjustable parameters that don't depend on the validity of the radial integral calculations, which are calculated within various approximations. Our aim is to determine the expectation value of $\langle L_z + 2S_z \rangle$ for a range of crystal field parameters $A_4 \langle r^4 \rangle$ and $A_6 \langle r^6 \rangle$.

We now have all the tools to diagonalize the full Hamiltonian using the self-consistent scheme for $\langle S_z \rangle$:

$$\mathscr{H} = \Lambda \mathbf{L} \cdot \mathbf{S} - 2J_{ex} \langle S_z \rangle S_z + \mathscr{H}_{CF}. \tag{4.21}$$

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Figure 4.3: Plot of $\langle L_z + 2S_z \rangle$ for values of $A_4 \langle r^4 \rangle$ and $A_6 \langle r^6 \rangle$ which includes the three lowest J multiplets. The symbols correspond to the value of $\langle L_z + 2S_z \rangle$ calculated using the crystal field parameters derived from a point charge model using an effective charge Z. The area to the right of the grey curve corresponds to the Γ_7 ground state.

The result for a parameter range of $A_4 \langle r^4 \rangle$, $A_6 \langle r^6 \rangle \in [-350 \text{ K}, +350 \text{ K}]$ is given in Figure 4.3. We see contours of constant $\langle L_z + 2S_z \rangle$ plotted, with the experimental moment of 0.035 μ_B shown with a dashed line.

We recall the discussion of Chapter 2, in which we noted that in a cubic crystal field the J = 5/2 ground state splits into a twofold degenerate Γ_7 (doublet) state and fourfold degenerate Γ_8 (quartet) state. Depending on the crystal field parameters, either the doublet or quartet state is lower. By examining the eigenvalues of \mathscr{H}_{CF} it becomes clear that the states to the right of the grey line all have the Γ_7 doublet as the ground state, while to the left of the grey area the quartet is the ground level.

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From the results of Meyer [30] it was determined from the magnitude of the paramagnetic moment, that the Γ_7 doublet has the lower energy in the J = 5/2 manifold. We can thus restrict our attention to this area, and see to return a ferromagnetic moment of 0.035 μ_B there is a single line of possible crystal field values. We can compare these values with the point-charge model for comparison.

In the point charge-model, the coefficients A_4 , and A_6 can be calculated in the following way, assuming that the rare-earth ion has octahedral coordination [68]:

$$A_4 = \frac{7}{16} \frac{Ze^2}{R^5}, \qquad A_6 = \frac{3}{64} \frac{Ze^2}{R^5}, \tag{4.22}$$

where -Z|e| is the effective charge of each N ligand, and R is the separation between the Sm ion and N. The radial integrals $\langle r^k \rangle$ can be calculated in various approaches. Here we use the non-relativistic Hartree-Fock values from Freeman and Watson [69], with $\langle r^4 \rangle = 1.897 \ a_0^4$ and $\langle r^6 \rangle = 8.775 \ a_0^6$, where $a_0 = 0.529$ Å is the Bohr radius. This leads to

$$A_4 \langle r^4 \rangle = 335 \text{ K}, \qquad A_6 \langle r^6 \rangle = 7.4 \text{ K}, \qquad (Z = 3)$$
 (4.23)

for Z = 3, the value we might expect for the trivalent N. From these values one can calculate a moment of $-0.039 \ \mu_B$, which is about the same magnitude as the experimental moment, however here it is negative because the spin moment is larger than the orbital moment. If we calculate for say Z = 2 the parameters returned are

$$A_4 \langle r^4 \rangle = 222 \text{ K}, \qquad A_6 \langle r^6 \rangle = 4.9 \text{ K}, \qquad (Z = 2)$$
 (4.24)

for which a moment of 0.080 μ_B is returned, only about twice as large as the experimental moment, but with the correct orbital dominant sign. We find that using Z = 2.4 gives the crystal field parameters $A_4 \langle r^4 \rangle = 267$ K and $A_6 \langle r^6 \rangle = 5.9$ K which return the experimental moment. We note that if only the J = 5/2 multiplet is included in the calculation, the moment returned is 0.28 μ_B , nearly an order of magnitude larger.

J = 5/2, 7/2, 9/2 included					
J_{ex}	Z	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$	
7.9 K	3	-1.00	1.95	-0.039	
$7.9~{ m K}$	2.4	-0.98	2.00	0.032	
$7.9~{ m K}$	2	-0.98	2.05	0.081	
		T - //			
J = 5/2 only					
J_{ex}	Z	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$	
7.9 K	2.4	-0.70	1.69	0.28	

Table 4.2: Expectation values of magnetic moments in SmN with crystal field parameters calculated in the point charge model, where -Z|e| is the charge of the N ions.

The parameter Z (or rather -Z|e|) is essentially an empirical fitting parameter, and a value less than 3, expected for trivalent nitrogen in the ionic limit, indicates that the point charge model breaks down. The view of point-like charges is clearly an oversimplification as the nitrogen orbitals overlap with the rare-earth valence shell and screening reduces the effective charge felt by the rare-earth ion. Furthermore, calculation of the radial integrals depends on the method used to some degree, with relativistic calculations giving slightly different values.

Nevertheless, while the point charge model cannot explain the crystal field parameters in terms of wave functions, we still see excellent agreement between the experimental moment and the point charge model with Z between 2 and 3. Aside from just the magnitude of the moment, the correct orbital dominant sign is returned. And finally, the Γ_7 doublet ground state observed in the paramagnetic phase is in agreement with the ferromagnetic moment.

We note that another mechanism for the moment reduction is conduction electron polarization, which has a contribution of $m_{CE} = -2 \mathscr{J} \rho(E_f) \langle S_z \rangle \mu_B$, where \mathscr{J} is the exchange integral between the 4f and conduction electrons, and $\rho(E_F)$ is the density of states at the Fermi level [29]. Because $m_{CE} \propto m_S$, the effect of the conduction electron polarization is to reduce the net moment in the current case. If this contribution is large enough, $m_S + m_{CE}$ can even exceed m_L and the net moment will be spin-dominant. Because this spin-dominance is not observed in SmN, we can conclude that the conduction electron polarization does not play a dominant role, as it does in some metallic Sm systems [29]. This is not surprising as it appears SmN is not metallic but semiconducting [5], though nitrogen vacancies provide some donor doping. We can make a rough estimate of the contribution of nitrogen vacancies to the magnetic moment. If each vacancy contributes 1-3 electrons (1 μ_B per vacancy), then if 1% of the N sites are vacant the contribution to the conduction electron moment is only about $0.01\mu_B$. This 1% nitrogen vacancy leads to a carrier concentration of about $(0.3-1) \times 10^{21}$ cm⁻³ which is common in the RENs, with even lower values found in GdN [12]. This is a much smaller effect than the crystal field even for a large number of vacancies.

The contributions to the net moment from N 2p and Sm 5d states are unknown, due to the inapplicability of the XMCD sum rules at the N K-edge and the rare-earth L-edge. N K-edge XMCD has been observed in GdN for example [3], and is likely present in SmN as well. The results of Larson indicate that these contributions are around 0.1 μ_B (though of opposite sign, cancelling to a large degree).

Band structure calculations are necessary to fully understand the picture in SmN by taking into account the overlap and hybridization effects between the various rare-earth and N orbitals. However, only two published band-structure calculations are available for SmN, made by Larson *et al.* [14] and Morari *et al.* [18] who both used the LSDA+U method. In both cases the calculations found that the spin moment is larger than the orbital moment, and find values m_S^{4f} and m_L^{4f} close to 5 μ_B . This is at odds with the experimental finding of an orbital dominant moment in SmN [19], and the present calculations, where the spin moment of SmN is shown to be antiparallel to the net moment. Furthermore, the current calculations show that both spin and orbital moments have magnitudes close to 2 μ_B , signalling partial quenching of the moments. This partial quenching is in agreement with recent studies of some heavy rare-earth nitrides, ErN, HoN, and DyN [6, 70].

4.3 NdN Magnetism

NdN, another light rare-earth nitride, is interesting to study alongside SmN as it also shares an orbital dominant moment. The Hund's rule ground state of Nd^{3+} is given by L = 6, S = 3/2, and J = 9/2. Unlike the near cancellation between spin and orbital moments in ferromagnetic SmN, in NdN the orbital moment should exceed the spin moment considerably, and indeed leads to sizable moments. A handful of magnetic studies on NdN were carried out in 1960s and 1970s on powder samples, with experimental ferromagnetic moments reported in the range 1.8 to 3.1 μ_B , along with Curie temperatures of 28–35 K (see table 33.9 in Ref. [71] and references therein). The 3.1 μ_B ferromagnetic moment (from Ref. [72]) should not be taken seriously, as the moment was calculated from neutron diffraction data measured at 80 K and 290 K, well into the paramagnetic regime where the occupation of crystal field levels is different from the ground state. In particular, an analysis of the magnetization by Schumacher and Wallace [73] found a paramagnetic moment of 3.70 μ_B at 296 K, but an ordered moment of 2.15 μ_B at 2.5 K. The paramagnetic Curie temperature was found to be $\theta_p = 15$ K, with $T_C = 35$ K (See Figure 4.4).

For comparison, in the NdN J = 9/2 ground state, with $g_J = 8/11$, the saturation magnetization is $\mu_B g_J J = 3.27 \ \mu_B$, much larger than any of the reported ordered moments, while the effective paramagnetic moment can be calculated as $\mu_B g_J \sqrt{J(J+1)} = 3.62 \ \mu_B$, close to the value obtained by Schumacher and others [71].

Other Nd pnictides (P, As, Sb, Bi), which order antiferromagnetically, are known to undergo a small tetragonal distortion around the Néel temperature T_N [71, 74], with the octahedron of N anions compressed along one axis. There are also a single reference to the same effect occuring in a study of Nd_{1-x}O_xN_{1-x} with $x = 0.02 \pm 0.01$. [75]. In this case they also found values of the paramagnetic and ordered moments similar to Schumacher. The indication from the Nd pnictides is that the structural transition occurs at, or slightly above the magnetic ordering temperature [72, 76, 77].

We present here magnetization measurements on a thin film NdN sample in order to compare to previous NdN measurements. The MBE method of growth



Figure 4.4: Inverse susceptibility of the bulk NdN sample of Schumacher [73], and the thin-film NdN sample, which was measured with H = 250 Oe and in-plane.

was used, outlined in Chapter 3. The NdN film was grown on a c-plane sapphire (Al₂O₃) substrate with an AlN capping layer to prevent oxidation. The film was grown at a rate of 0.1-0.2 Å/s at 390° C. The 120 nm thickness of the film was determined via x-ray reflectivity measurements. While this particular sample was not measured with XRD, similar NdN films grown on sapphire substrates have shown [100] texturing when grown at room temperature while higher temperature growths show an additional [111] reflection.

In Figure 4.4 we present a plot of the inverse susceptibility taken from Ref. [73], along with the recently measured thin film NdN inverse susceptibility for comparison. We have fit the susceptibilities according to a Curie-Weiss approach

$$\chi = \frac{A}{T - \theta_p} + B, \tag{4.25}$$

with the parameter A given by $n\mu_0\mu_B^2m_{\text{eff}}^2/3k_B$ where n, m_{eff} , and θ_p are the theoretical Nd ion density, effective moment, and paramagnetic Curie temperature, respectively. The temperature independent contribution for the thin film sample B includes large diamagnetic contributions from both the sapphire substrate and AlN capping layer, which have been removed in Figure 4.4. In this case the thin film data represents $(\chi - B)^{-1}$. This substrate/capping layer background signal is the source of the noise in the thin film sample above 100 K. In principle a van Vleck contribution should also be present for NdN, though even at 300 K it is less than 3 % of the Curie-Weiss contribution.

For the NdN thin film sample, the fit from Equation (4.25) in the region 90–300 K returns the parameters $m_{\text{eff}} = 3.5 \pm 0.1 \ \mu_B$, with $\theta_p = 4 \pm 5$ K. This agrees well with the free-ion effective paramagnetic moment of 3.62 μ_B . The paramagnetic Curie temperature θ_p returned from the fit is however much smaller than the actual ordering temperature T_C where the inverse susceptibility intercepts the horizontal axis, at about 42 K. Within the uncertainty limits θ_p is at least a factor of four smaller than T_C . The Schumacher data, on the other hand, has an effective moment of $m_{\text{eff}} = 3.6 \pm 0.1 \ \mu_B$ (which agrees with their quoted value of 3.7 μ_B at 296 K.) The high temperature Curie temperature is $\theta_p = 15$ K, with a $T_C \approx 30$ to 35 K. Thus θ_p is about a factor of two smaller than the T_C .

It is interesting to compare the two susceptibilities. In the high temperature regime, the effective moments are about the same within uncertainty, while the values of θ_p differ within the uncertainties between 4–20 K. The lower temperature regime however quite clearly indicates different values of T_C . The uncertainty in estimates of θ_p make it difficult to conclude much about the different values between samples, so whether θ_p is intrinsically different between samples is not clear.

We can furthermore compare the ordered moments of the samples. The data from Schumacher reports a moment of 2.1 μ_B at 2.5 K. To estimate the moment in the thin film sample we turn to Figure 4.5, which shows a hysteresis loop measured at 5 K, with the diamagnetic background subtracted. The high field value corresponds to 0.86 μ_B/Nd^{3+} , which is small compared to the theoretical saturation value of $\mu_B g_J J = 3.2 \ \mu_B$. The remanent magnetization is $M_R = 0.74 \ \mu_B$, which can also be used to estimate the spontaneous moment. If the easy axis lies along one of the high symmetry directions, then in a polycrystalline sample, at remanence the moments will lie distributed within a cone of half-angle 54.7° around the magnetic field direction. M_R is then reduced from the saturation value by about 15% [78], leading to an estimate of $M_S = 0.86 \ \mu_B$ for the spontaneous moment, which is in perfect agreement



Figure 4.5: Thin-film NdN hysteresis loop measured at T = 5 K with field in-plane.

with the high field value.

The small ordered moment of the thin-film sample, coupled with the larger T_C compared to the data of Schumacher suggest that the ferromagnetic ground state is somehow different between the samples. One possibility is that the thin film is strained due to the substrate, which could change the symmetry of the ground state. Differences in contributions from conduction electrons could play a role as well. Because of the uncertainties in values of θ_p (proportional to the exchange in the mean-field approach), no conclusion can be made as to whether the exchange mechanism is intrinsically different. In the next section we explore the effects of the crystal field on NdN, in an attempt to gain insight into the magnetic properties discussed so far.

4.3.1 Magnetic moment calculation

We have already presented the machinery of crystal field calculations in the previous section on SmN, and here we apply the same technique to NdN, with some modifications. We begin by exploring the effects of exchange and additional multiplets. We can estimate the exchange energy from θ_p in the

J multiplets	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$
9/2	-1.23	5.73	3.27
9/2, 11/2	-1.24	5.74	3.26
9/2, 11/2, 13/2	-1.24	5.74	3.26

Table 4.3: Expectation values based on number of multiplets included

mean-field approximation:

$$J_{ex} = \frac{3}{2} \frac{k_B \theta_p}{(g_J - 1)^2 J (J + 1)} = 8.5 \text{ K.}$$
(4.26)

for $\theta_p = 10$ K, on the high end of the uncertainty. If we instead use $T_C = 42$ K, the exchange constant is 34 K. We will revisit the estimate of the exchange later. For now, we can estimate the spin and orbital expectation values by diagonalizing $\mathscr{H} = \mathscr{H}_{SO} + \mathscr{H}_{ex}$ with different multiplets. For the J = 9/2 ground state \mathscr{H} is a 10 × 10 matrix, while if we include the first excited state, \mathscr{H} grows to a 24 × 24 matrix. The results are displayed in Table 4.3. We see that the inclusion of the J = 11/2 multiplet reduces $\langle L_z + 2S_z \rangle$ by only 0.3%, and including the J = 13/2 multiplet has even less effect. Of course, the inclusion of crystal field terms may cause more significant mixing between J multiplets. We also note that these values are the same for either exchange parameter used.

4.3.2 NdN crystal field

We now consider the crystal field of NdN, and choose the z axis along the [001] direction,⁶ which is given in Refs. [34, 35]:

$$\mathscr{H}_{\rm CF} = A_4 \sum_i \left[f_{40}(\mathbf{r}_i) + 5f_{44}(\mathbf{r}_i) \right] + A_6 \sum_i \left[f_{60}(\mathbf{r}_i) - 21f_{64}(\mathbf{r}_i) \right].$$
(4.27)

In the absence of a Zeeman or crystal field contribution, the J = 9/2 ground state, $\left|\psi_{0}^{9/2}\right\rangle$, is ten-fold degenerate, however a cubic crystal field splits the

⁶The energy eigenvalues are slightly lower that when calculated in the [111] direction, agreeing with some previous experimental studies finding a [001] easy axis in Nd pnictides [71].



Figure 4.6: A sketch of the tetragonal distortion which occurs in some of the Nd pnictides, though not necessarily NdN. The Nd pnictides have been observed to have a compressive distortion, with $\epsilon < 0$.

ground state into three distinct eigenstates of the crystal field Hamiltonian:

$$\left|\psi_{0}^{9/2}\right\rangle \rightarrow \left|\Gamma_{6}\right\rangle + 2\left|\Gamma_{8}\right\rangle,$$
(4.28)

where the Γ_6 state is a doublet, and there are two quartets labelled $\Gamma_8^{(1)}$ and $\Gamma_8^{(2)}$. The ordering of these states depends on the crystal field parameters $A_4 \langle r^4 \rangle$ and $A_6 \langle r^6 \rangle$. There are reports claiming both Γ_6 (Schumacher [79]), and $\Gamma_8^{(2)}$ [71, 72] ground states in NdN, however the latter was only inferred from 80 K data and is not a reliable measure of the ordered state.

The tetragonal distortion of some of the rare-earth pnictides, including NdSb was studied via temperature dependent X-ray diffraction by Lévy [74], who also derived the crystal field Hamiltonian for a small tetragonal distortion along one axis. For example Figure 4.6 shows a tetragonal distortion of an octahedrally coordinated ion, where the unit cell is compressed or stretched along one axis. The Hamiltonian for the tetragonal distortion is given by Lévy

$$\mathcal{H}_{CF} = A_2 \sum_{i} f_{20}(\mathbf{r}_i) + A_4 \sum_{i} \left[\left(1 - \frac{10}{7} \epsilon \right) f_{40}(\mathbf{r}_i) + 5 f_{44}(\mathbf{r}_i) \right] + A_6 \sum_{i} \left[\left(1 - \frac{28}{3} \epsilon \right) f_{60}(\mathbf{r}_i) - 21 f_{64}(\mathbf{r}_i) \right].$$
(4.29)

for a displacement of $\epsilon = \Delta R/R$, where R is the Nd-N separation and ΔR the distortion. This is nearly the same as the cubic crystal field Hamiltonian, except for the term $\propto A_2$ and the factors in parentheses.

We may employ this Hamiltonian, in addition to the cubic version used previously, to investigate the possibility of a tetragonal phase. As there is no data available for the value of ϵ , we estimate it is of similar size as in the other Nd pnictides. For example NdSb has $\epsilon = -0.003$, corresponding to a compression along one axis. For NdN_{0.94}O_{0.06} it was found $\epsilon = -0.004$ [75]. For these small displacements, the effect of rescaling the f_{40} and f_{60} is small enough to be ignored: for $\epsilon = -0.003$ the prefactors yield 1.004 and 1.028 for f_{40} and f_{60} . The point charge model coefficients A_4 and A_6 are calculated as was shown for SmN, while A_2 in the tetragonal phase is given by

$$A_2 = -3\frac{Ze^2}{R^3}\epsilon.$$
(4.30)

So for small ϵ we only need to add the term proportional to A_2 to the cubic \mathscr{H}_{CF} . The radial integrals $\langle r^n \rangle$ for Nd³⁺ are again taken from [69], with $\langle r^2 \rangle = 1.001 \ a_0^2, \ \langle r^4 \rangle = 2.401 \ a_0^4, \ \text{and} \ \langle r^6 \rangle = 12.396 \ a_0^6, \ \text{where} \ a_0 \ \text{is the Bohr}$ radius.

We now calculate the ground state ordered moment in either cubic or tetragonal phases, as a function of the crystal field parameters. We begin with the point charge estimates, which were shown to be reasonable for SmN. Table 4.4 shows the results of the calculated ground-state expectation values, calculated within the lowest two multiplets, with varying values of J_{ex} and Z, for both cubic and tetragonal crystal fields. The variety of exchange parameters include $J_{ex} = 8.5$, estimated from the θ_p value, while $J_{ex} = 34$ K is estimated from the large value of T_C . Other values are shown to see how the

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exchange modifies the ground state moment. If we use $J_{ex} = 34$ K, the value of $\langle L_z + 2S_z \rangle$ is not very sensitive to Z when varied between 2 and 3. We note that when only the ground state multiplet is considered, the resulting expectation values differ by more than 15 % from the expectation values calculated within the J = 9/2 and 11/2 multiplets. This is because the crystal field in NdN is large enough to cause significant J mixing. Inclusion of the J = 13/2multiplet has negligible effect.

The results from the cubic crystal field Hamiltonian in Table 4.4 (a) show that for small exchange constants, a significant reduction in the moments can be found. In particular, for $J_{ex} = 12$ K (which corresponds to $\theta_p \approx 15$ K) we find a moment between 2.3 and 2.7 μ_B , which is reasonably close to the ordered moment of Schumacher, who measured 2.1 μ_B [73]. However, the thin-film NdN ordered moment of 0.86 μ_B is not close to any of the values, and only for zero exchange do we begin to approach 1 μ_B , and this seems an unreasonable exchange constant given the clear indications of ferromagnetism.

For the tetragonal phase, Table 4.4 (b) expectation values for various values of J_{ex} , Z, and ϵ are shown. Positive values of ϵ denote stretching the unit cell along one axis, while negative values represent compression. We see that small moments close to 0.85 μ_B can be obtained only by a stretching of the cell: for Z = 3 and $\epsilon = 0.003$ we obtain good agreement with the ferromagnetic moment. However, this disagrees with the other Nd pnictides, which have a *compression* of the unit cell. The negative values of ϵ tend to only give net moments of over 2.4 μ_B .

The crystal field parameters used are shown in Table 4.4 (c). To check the reasonableness of these parameters, we extend the calculation of the moments to the paramagnetic phase, where we use the same self-consistent method, except in this case the expectation values must include Boltzmann averaging. We diagonalize the full Hamiltonian now including the Zeeman interaction:

$$\mathscr{H} = \mathscr{H}_{SO} + \mathscr{H}_{CF} + \mathscr{H}_{ex} + \mathscr{H}_{Zeeman}, \qquad (4.31)$$

(a) Cubic crystal field				
J_{ex}	Z	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$
34 K	2	-1.26	5.69	3.16
$34~{ m K}$	3	-1.26	5.62	3.10
12 K	2	-1.05	4.80	2.69
$12 \mathrm{K}$	3	-0.91	4.15	2.32
8.5 K	2	-0.88	4.03	2.27
$8.5~{ m K}$	2.4	-0.82	3.76	2.11
$8.5~{ m K}$	3	-0.75	3.44	1.93
$10^{-3} { m K}$	2	-0.50	2.33	1.33
$10^{-3} \mathrm{K}$	3	-0.50	2.33	1.33

(b) Tetragonal crystal field

	,		, ,		
J_{ex}	Z	$\epsilon \times 10^3$	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$
34 K	3	3	-1.21	5.41	2.99
$34~{ m K}$	3	-3	-1.13	5.09	2.83
8.5 K	2	1	-0.66	3.04	1.72
$8.5~{ m K}$	3	1	-0.53	2.45	1.39
$8.5~{ m K}$	2	3	-0.31	1.48	0.85
$8.5~{ m K}$	3	3	-0.26	1.26	0.74
$8.5~{ m K}$	3	-1	-0.94	4.27	2.39
$8.5~{ m K}$	3	-3	-1.13	5.08	2.83
$8.5~{ m K}$	3	-5	-1.22	5.49	3.04

(c) Point-charge crystal field parameters for NdN

	0 0	-	
Ζ	A_2 (K)	A_4 (K)	A_6 (K)
2	49.9	247.1	5.8
2.4	59.8	296.5	7.0
3	74.8	370.6	8.7

Table 4.4: Ground state expectation values for cubic (a) and tetragonal (b) crystal fields, with varying effective charge Z, and with varying tetragonal distortion parameter ϵ . The two lowest J multiplets were included. (c) The crystal field parameters A_k are given for NdN in the point-charge model for various values of Z.

and calculate the expectation values as

$$m = -\mu_B \left\langle L_z + 2S_z \right\rangle_T = -\mu_B \frac{\sum_n \left\langle \psi_n \right| L_z + 2S_z \left| \psi_n \right\rangle e^{-\beta E_n}}{\sum_n E_n e^{-\beta E_n}}, \qquad (4.32)$$

where $|\psi_n\rangle$ are eigenstates of the full Hamiltonian in Equation (4.31). The susceptibility can then be calculated as $\chi = mn/H$, where $n = 4/a^3$ is the Nd ion density determined from the lattice constant a. The results are shown in Figure 4.7 alongside the experimental susceptibilities. Very good agreement is found between the Schumacher data and the calculated susceptibility when using $J_{ex} = 12$ K and the cubic crystal field parameters calculated with Z = 3. The thin film NdN sample does not agree with the tetragonal crystal field parameters with $\epsilon = 0.003$, $J_{ex} = 8.5$ K and crystal field parameters calculated using Z = 2, which returned a moment of 0.85 μ_B in the ordered phase. No satisfactory agreement for the NdN thin film susceptibility could be found after exhausting all reasonable combinations of cubic and tetragonal crystal field parameters and J_{ex} .

We note that the tetragonal phase is not expected to persist in above the magnetic transition, so it is not surprising to find no agreement when the susceptibility is calculated with tetragonal parameters. More puzzling is the lack of agreement of the thin-film data with the cubic crystal field calculations. This suggests the possibility of lattice strain in both phases which modifies the crystal field below and above T_C . A [100] textured film might be expected to have a tetragonal distortion, while a film with [111] texturing could have an orthorhombic distortion due to the lattice mismatch with the substrate which is 24% for *c*-plane sapphire. More structural data is thus necessary to carry detailed calculations which include the correct crystal field symmetry.

We note that the experimental moments are much less than the theoretical saturation value of $\mu_B g J = 3.2 \ \mu_B$ and much less than the moments from the LSDA+U calculations of Larson *et al.* [14], which give a net moment of $m = 2.9 \ \mu_B$, with $m_L^{4f} = 5.88 \ \mu_B$, and $m_S^{4f} = -2.96$. The calculated moment best agreeing with the Schumacher data in the ferromagnetic and paramagnetic phases gives a net moment of 2.3 μ_B , with $m_S = -1.8 \ \mu_B$ and $m_L = 4.15 \ \mu_B$ which indicates that partial quenching takes place.



Figure 4.7: NdN Susceptibility. Cubic crystal field calculation parameters: $J_{ex} = 12$ K, Z = 3. Tetragonal crystal field calculation parameters: $J_{ex} = 8.5$, Z = 2.

We then conclude that the thin film sample shows quite distinct magnetic properties as compared to the bulk data of Schumacher *et al.* [73] and cannot be interpreted within cubic or tetragonal crystal field models. The Schumacher data fit very well to calculations within a cubic crystal field using the exchange parameter estimated from θ_p and point charge calculations for Z = 3. The thin film then is likely strained, presumably due to the *c*-plane Al₂O₃ substrate. It is usually found that the RENs grow with [111] texturing on hexagonal substrates [2], in this case the substrate has a lattice constant of 4.79 Å versus the Re-Re separation of 3.76 Å, leading to a large lattice mismatch. In the case of [111] oriented NdN, it is possible that the substrate could introduce an orthorhombic distortion. In that case the crystal field would have to be modified, and could possibly explain the thin film magnetic data. Information on the low temperature lattice constant and any distortions would allow for calculation of these effects, though the cubic field Hamiltonian would have to be generalized.

Furthermore, the contribution from conduction electrons due to nitrogen vacancies could play a role, as it is likely the samples have different carrier concentrations. It is doubtful that conduction electrons alone could explain the difference in the ground state ordered moment, as to account for a 1 μ_B smaller moment in the thin film would require a high carrier concentration (and metallic conductivity), while the resistivity data from this sample suggest doped semiconductor behavior with a resistivity of 0.6 m Ω -cm at 300 K increasing to 1 m Ω -cm at low temperature. We however note that GdN has been shown to have a T_C of 50 K for low carrier concentrations, increasing to 70 K for carrier concentrations above $\approx 10^{20}$ cm⁻³. This enhancement in T_C was shown to be due to the formation of magnetic polarons at nitrogen vacancies, as opposed to an RKKY-type effect [12, 13]. A similar magnetic polaron scenario in NdN might explain the rather large T_C in the thin film sample compared to the Schumacher data, however more detailed studies will need to be carried out.

4.3.3 Effects of the crystal field on T_C

Finally, we conclude the chapter with a discussion of the exchange parameter J_{ex} . It is not a priori clear how the crystal field affects the relationships between the ordering temperature, T_C , the high temperature paramagnetic Curie temperature θ_p and exchange parameter J_{ex} . In order to clarify the situation, and justify the estimation of J_{ex} from θ_p , we again examine the paramagnetic regime within the crystal field theory.

We are mostly interested in a qualitative understanding, and so carry out an analysis of the susceptibility in second order perturbation theory (see, e.g. [27, 32]) where we treat the Zeeman term as a perturbation to the spin-orbit and crystal field Hamiltonian. The exchange interaction is then incorporated in a self-consistent mean-field approach, as described in Chapter 2. We can simplify by only considering the ground state J multiplet⁷, noting that this is not strictly justified, as the J = 11/2 multiplet had a significant effect on ground state ferromagnetic moment.

⁷The second order susceptibility for arbitrary multiplets is described in [35, 61], though its complexity makes direct diagonalization of the full Hamiltonian a better option.

In the zeroth order, the Hamiltonian has eigenstates $|n_k\rangle$ that obey

$$\left(\mathscr{H}_{SO} + \mathscr{H}_{CF}\right) \left|n_{k}\right\rangle = E_{n}\left|n_{k}\right\rangle,\tag{4.33}$$

where n indexes the energy level E_n and k indexes the various degenerate states sharing the same E_n (for example the $|n_k\rangle$ could be the doubly degenerate $|\Gamma_6\rangle$ state). We now use these eigenstates to calculate the susceptibility in the *absence* of any exchange interaction, denoted χ_0 . This is given by [27, 80]:

$$\chi_{0} = \frac{N}{V} \sum_{n} \left(\frac{g^{2} \mu_{B}^{2}}{k_{B} T} \sum_{k,k'} |\langle n_{k} | J_{z} | n_{k'} \rangle|^{2} + 2\mu_{B}^{2} \sum_{m \neq n} \sum_{k,k'} \frac{|\langle n_{k} | J_{z} | m_{k'} \rangle|^{2}}{E_{m} - E_{n}} \right) \frac{e^{-\beta E_{n}}}{\mathcal{Z}},$$
(4.34)

where $\mathcal{Z} = \sum_{n} \omega_n e^{-\beta E_n}$ is the partition function, and ω_n is the degeneracy of the eigenstate $|n_k\rangle$. Here J_z is the total angular momentum operator, and E_n are the unperturbed energies found in Equation 4.33. The first term is the T^{-1} "Curie" term, while the second term is sometimes called the van Vleck contribution, though it is not the same as the van Vleck contribution from the higher multiplets. If the temperature is low enough, then only the ground state will be occupied and only the first term contributes. However, if there is a close by excited state and the separation $\Delta = E_n - E_m$ is small, then the second term becomes relevant. In the analysis of the ferromagnetic moment of NdN above, in the cubic crystal field the separation between the ground and first excited crystal field states is $\Delta \approx 40$ K, depending on the parameters. Therefore in the paramagnetic phase we must consider both states when calculating χ . If we assume only these two lowest states contribute at low temperatures (less than 100 K) then the susceptibility simplifies to

$$\chi_{0} = \frac{N}{V} \frac{g^{2} \mu_{B}^{2}}{\omega_{0} + \omega_{1} e^{-\beta \Delta}} \left(\frac{1}{k_{B}T} \sum_{k,k'} \left(|\langle J_{z} \rangle_{00}^{kk'} |^{2} + |\langle J_{z} \rangle_{11}^{kk'} |^{2} e^{-\beta \Delta} \right) + 2 \sum_{k,k'} \frac{|\langle J_{z} \rangle_{01}^{kk'} |^{2}}{\Delta} (1 - e^{-\beta \Delta}) \right),$$
(4.35)

where we have used the notation $\langle J_z \rangle_{nm}^{kk'} \equiv \langle n_k | J_z | m_{k'} \rangle$ and $\Delta = E_1 - E_0$.

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This has the form

$$\chi_0 = \frac{A(T)}{T} + B(T)$$
 (4.36)

where A(T) and B(T) vary exponentially with temperature. The susceptibility in the presence of exchange χ can be incorporated now by using the selfconsistent mean-field approximation, as was done in Chapter 2:

$$\chi = \frac{\chi_0}{1 - \lambda \chi_0} \qquad \text{where} \qquad \lambda = 2J_{ex} \frac{(g-1)^2}{(N/V)(g\mu_B)^2}. \tag{4.37}$$

We can now write χ in a form which incorporates exchange and crystal field effects:

$$\chi = \frac{\bar{A} + \bar{B}T}{T - \lambda\bar{A}},\tag{4.38}$$

where $\bar{A} = A(T)/(1 - \lambda B(T))$ and $\bar{B} = B(T)/(1 - \lambda B(T))$. We can check that in the limit $B(T) \to 0$ (equivalent to a large separation Δ between levels, or $T \to 0$) we arrive at Curie-Weiss behavior:

$$\chi = \frac{A(0)}{T - \lambda A(0)}. \quad \text{for } \Delta \to \infty$$
(4.39)

This limit is not useful for NdN however, since the ordering point, 35 K to 42 K, is roughly equal to the splitting between the ground and first excited states. Returning to Equation 4.38, we see that the exchange parameter and crystal field modify both T_C and the effective moment. The susceptibility can be seen to diverge at an effective ordering temperature

$$T_C^{\bigstar} = \lambda \bar{A} = \frac{\lambda A(T)}{1 - \lambda B(T)}.$$
(4.40)

So it is clear that the ordering temperature depends not only on the exchange, via the molecular field λ , but also on the crystal field through both A(T) and B(T) terms. Figure 4.8 shows T_C^{\bigstar} calculated with point charge parameters for Z = 3 and $J_{ex} = 12.5$ K. This value of J_{ex} roughly corresponds to Schumacher's value of $\theta_p = 15$ K. When $T_C^{\bigstar} = T$, the maximum value of T_C^{\bigstar} is reached; $T_C^{\bigstar} >$



Figure 4.8: T_C^{\bigstar} calculated with $J_{ex} = 12.5$ K and a cubic crystal field using point charge parameters for Z = 3. λ_0 corresponds to the molecular field constant for the ground state multiplet $\lambda_0 = (N/V)2J_{ex}(g-1)^2/(g^2\mu_B^2)$.

T has no physical significance. Using λ for the ground state multiplet (Eq 4.37), we see that maximum value of T^{\bigstar} is only about 17 K, just slightly increased from θ_p . However, we have neglected the effects of excited multiplets, and so the disagreement with the Schumacher data is not surprising. If we try to account for this by scaling λ by 1.5, we good agreement with the experimental T_C . We note that the full calculation of χ , shown in Figure 4.7 reproduces the difference in θ_p and T_C very well.

To summarize, Figure 4.8 illustrates that as the occupation of the crystal field changes with temperature, for the given parameters, the ordering temperature increases from that expected from exchange only. This may change dramatically depending on the separation between crystal field states and the size of the matrix elements. We can conclude that when considering the size of the exchange constant, J_{ex} , one should estimate it from the high temperature susceptibility. In fact, this is not surprising, as Curie's law is derived under the assumption that the temperature is large enough that all of the M_J levels within a J multiplet are occupied. At lower temperatures, the occupation

changes due to splitting of the crystal field, and the factor $(g-1)^2 J(J+1)$ does not reflect the actual spin contribution to the moment. Thus using the actual ordering temperature to estimate J_{ex} overestimates the exchange, in some cases by more than a factor of two, as for NdN. A Similar effect can be seen in ErN [6], though it is smaller than in NdN.

4.4 Conclusion

In conclusion, we have shown that the small SmN moment is very well explained by the incorporation of higher multiplets and crystal field with parameters estimated within the point-charge model. The Γ_7 ground state is in accord with a calculation of the effective paramagnetic moment if only the Γ_7 state is occupied, as demonstrated in Meyer *et al*[30].

We also found that the bulk NdN data of Schumacher was well described by a cubic crystal field calculation of both the ground state ordered moment and paramagnetic susceptibility. The thin-film NdN sample could not be adequately explained within a cubic or tetragonal crystal field however. The indication is that strain may play an important role in the thin film, modifying the crystal field in some way. Nitrogen vacancies may also play a role in producing different values of T_C and ordered moments in the samples. The exchange energy was shown to be best estimated from the high temperature susceptibility, and the ordering temperature was shown to have a strong crystal field dependence.

Finally, we note that the resulting spin and orbital moments calculated for SmN and NdN are partially quenched, in agreement with experimental data, and in contrast to LSDA+U calculations [14, 18] which found nearly maximum values of m_L^{4f} and m_S^{4f} . Recent neutron reflectivity experiments on DyN,ErN, and HoN found much smaller ordered moments at 5 K than the free ion $\mu_B g_J J$ values [70]. The authors pointed out the disagreement with the LSDA+Ucalculations and proposed that the ordered moments could be explained by a fully quenched (L = 0) ground state moment, however full quenching of L is unlikely. It is more likely that partial quenching of the orbital moment occurs, and via the spin-orbit coupling the spin moment m_S is quenched to a similar

4.4 Conclusion

degree, which is exactly what the crystal field calculations predict.

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Chapter 5

Twisted Magnetization in SmN/GdN

5.1 Introduction

As we have seen for SmN and NdN, the strong spin-orbit interaction of the 4f shell results in a dominant orbital contribution to the ferromagnetic moment. This is in contrast to more familiar transition metal systems, where the orbital moment is usually quenched. In this chapter we show how this orbital-dominant feature facilitates the fabrication of a novel class of magnetic heterostructures. In particular we describe an investigation of interfaces between GdN and SmN using XMCD.

Twisted, or inhomogeneous ordering of the magnetization occurs in some magnetic systems due to competing interactions which favor opposing alignments of the magnetization. Competing interactions may arise from a number of sources, including surface or bulk anisotropies, interface exchange, Zeeman coupling, or chiral interactions [81, 82]. These twisted phases can be viewed as types of engineered domain walls, and thus have important implications for spintronics applications, where current-driven domain wall motion is an active area of research [83–86]. So far, twisted phases are known to manifest in diverse magnetic systems [38, 81, 82, 87–91], however these all fall under the conventional spin-dominant paradigm of magnetism where the orbital moment plays no significant role. Competing interactions in the presence of a dominant



Figure 5.1: (a) A sketch of a single atomic layer of a spin-dominant ferromagnet (e.g. GdN) and a cross section of multiple atomic planes of an orbitaldominant (SmN) ferromagnet. (b) Cross-section of an interface between spin and orbital-dominant ferromagnets. A twisted phase develops in the orbitaldominant magnet due to exchange-Zeeman competition which occurs if the spin-dominant layer remains fixed due to its large Zeeman coupling.

orbital moment have so far remained unexplored, yet the opportunity exists within the rare-earth nitride series, where orbital-dominant magnetism is possible in the first half of the series due to strong spin-orbit coupling of the 4f electrons.

GdN, with the Gd³⁺ ion, has a half-filled 4f shell, for which Hund's rules state that the seven electrons fill all of the orbital states with spin-up electrons; L = 0 and S = J = 7/2. It thus has a purely spin moment of 7 μ_B . The indirect exchange interaction aligns the spins below a Curie temperature of about 50 K, rising to 70 K under heavy donor doping [12], but the spherical symmetry of the L = 0 shell interacts very weakly with the crystalline environment, leading to a coercive field smaller than 100 Oe.[92]

This is in stark contrast to SmN, which is not only orbital-dominant with a near-zero moment, but has a coercive field of over 6 T at 2 K due to the non-spherical orbital wave function and weak Zeeman interaction associated with the small magnetic moment.

In the following we exploit the contrasting properties of GdN and SmN in SmN/GdN thin film heterostructures, and observe a twisted phase arising from

a novel competition between spin and orbital magnetism. The spin-dominant GdN is fixed parallel to an external magnetic field, and its much larger Zeeman interaction ensures that it provides a rigid layer which pins the SmN spin at the SmN-GdN interface. The pinning of the SmN, with its 200-fold weaker Zeeman coupling, takes place through ferromagnetic exchange coupling with the GdN, resulting in a SmN spin-moment parallel to that of the GdN, while the orbital-moment is antiparallel. This interface pinning is opposed by the orbital-dominant Zeeman alignment of the bulk SmN, which tends to align the SmN magnetization in the opposite sense, and thus drives the rotation of the magnetization across the SmN layer. Figure 5.1 sketches the effects of exchange coupling between spin and orbital dominant ferromagnets.

It is important to note that the GdN/SmN system is fundamentally different from the conventional spin-dominant ferromagnetic systems displaying twisted phases, as was mentioned in Chapter 2. The most common exchange spring systems, composed of hard and soft ferromagnetic layers, are first magnetized in one direction, and when the field is reversed the hard material remains fixed while an exchange spiral is formed in the soft material [38, 93]. In another manifestation, metallic Gd/Fe systems displaying twisted phases rely on antiferromagnetic coupling between spins at the interface [88, 94–98]. With the SmN/GdN system, however, the interlayer Sm-Gd exchange is ferromagnetic, and the usual hard/soft contrast is of no interest; indeed the fixed layer (GdN) has a coercive field three orders of magnitude smaller than SmN. It is the much stronger Zeeman interaction in GdN than in SmN that effectively locks the GdN magnetization. Furthermore, the spin-dominant, metallic systems lack the novel combination of electronic and magnetic properties of SmN and GdN, which allow the facility of controlling the concentration and sign of charge carriers without disturbing the ferromagnetic ordered state, and band structure results also show electron and hole channels of majority spin [14].

In our investigation of the interface exchange coupling in GdN/SmN multilayers we have used the element selectivity of XMCD at the Sm $L_{2,3}$ and $M_{4,5}$ edges. We first demonstrate that the SmN is ferromagnetically exchange coupled to GdN through investigation of a SmN/GdN superlattice. We then demonstrate that a twisted, or rotating, magnetization develops in ultrathin SmN films coupled to GdN due to interface pinning in the SmN, short-range interionic rare-earth exchange, and the extremely weak Zeeman coupling of SmN. The observed depth dependence of the magnetization is fully consistent with an analytical model based on these competing interactions.

5.2 Experimental Details

The attenuation lengths of hard L-edge and soft M-edge X-rays dictated that quite different structures were used for the two investigations. At the L-edge the full thickness of a superlattice of $12 \times (1.5 \text{ nm SmN}/9 \text{ nm GdN})$ was probed through a 100 nm passivating AlN cap. For the much more surface sensitive M-edge we investigated two samples. The first was a bilayer of 100 nm GdN/ 5.5 nm SmN, and the second, a trilayer of 100 nm GdN/ 6 nm LaN/ 5.5 nm SmN. The non-magnetic LaN layer between the GdN and SmN was included to block the Gd-Sm exchange interaction in the trilayer. Both of the M-edge samples were passivated with 25 nm of GaN to prevent sample oxidation.

Samples were grown in a Thermionics ultra-high vacuum system with a base pressure of 1×10^{-8} Torr. High purity Gd metal was evaporated at a rate of 0.2 Å/s with a N₂ partial pressure of 4.5×10^{-4} Torr. Sm metal was evaporated at a rate of 0.3 Å/s under the same N₂ pressure. The superlattice was grown on an MgO(111) substrate, while the bi- and trilayers were grown on c-plane Al₂O₃ substrates. All the substrates were outgassed for 1 hour at 700 °C, and heated to 600 °C during growth. The GaN and AlN capping layers were grown at room temperature with the metal evaporated at a rate of 0.1 Å/s with an ion source activating the N₂. Thicknesses were determined via quartz crystal balances calibrated for SmN, GdN, AlN, and GaN via scanning electron microscope and Rutherford backscattering measurements. The SmN/GdN superlattice was characterized *ex situ* by XRD, and showed the lattice constant of GdN; as expected the in-plane lattice constant was dominated by the thicker GdN layers in all cases.

Figure 5.2 shows magnetization measurements that were carried out via a Quantum Design SQUID with the field oriented in-plane. Because the much



Figure 5.2: SQUID data from bilayer, trilayer, and superlattice all with field in-plane. (a) Temperature dependent magnetization curves (circles denote field-cooled measurements, and dashed lines zero-field cooled) and Curie-Weiss fit to the inverse susceptibility. (b) Hysteresis curves taken at 10 K.

larger magnetic moment of GdN drowns out the signal from SmN, SQUID measurements probe only the GdN magnetization. Curie-Weiss fits to the inverse susceptibility yielded paramagnetic Curie temperatures of 69 K, 68 K and 66 K for the superlattice, trilayer, and bilayer, respectively. Hysteresis loops measured at 5 K saturated at 7 μ_B per Gd³⁺ ion. The superlattice and bilayer displayed a coercive field of 120 Oe at 5 K while the trilayer had a coercive field of 90 Oe, all within the range reported for polycrystalline GdN films. [92, 99]

XMCD measurements were performed at temperatures down to 15 K and fields up to 6 T at the Sm and Gd L_{2,3} edges on beam line ID12 at the European Synchrotron Radiation Facility (ESRF) in Grenoble. M_{4,5} edge XMCD was measured at the soft X-ray line ID08 of the ESRF, at temperatures down to 10 K and in fields up to 4 T. Measurements at the M-edge were necessarily performed only at normal incidence to limit attenuation by a passivating cap. For all of the L-edge XMCD measurements the field and incident beam were directed at 10° from grazing incidence, in which geometry the very large shape anisotropy ($4\pi M \approx 2.5$ T, were M is the magnetization) of GdN ensured that the magnetization lay in the plane of the film. At both edges the applied magnetic field was along the X-ray propagation direction.

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The XMCD spectra were obtained by taking the difference of two XAS spectra with the X-ray helicity reversed while the magnetic field was held fixed. This corresponds to the difference between antiparallel and parallel alignments of the helicity and magnetization. XAS spectra have been normalized to the incident photon intensity. XMCD spectra were normalized to the XAS white line intensity at the M-edge and to the edge-jump at the L-edge.

XMCD at the Sm L_2 edge is the signal of choice for following magnetic hysteresis, for it is stronger than the L_3 edge signal. In the superlattice that feature was obscured by magnetic EXAFS (extended X-ray absorption fine structure) from the Gd L_3 edge, necessitating the use of the Sm L_3 XMCD in the superlattice. There was a similar interference in the soft X-ray measurements, where the capping-layer Ga $L_{2,3}$ edge introduced a large and variable background in the Gd $M_{4,5}$ -edge XAS.

Our investigation relies on the use of two common schemes for measuring the X-ray absorption and XMCD spectra, based on the emission of fluorescence (total fluorescence yield, TFY) or electrons (TEY). Below we exploit the differing probing depths of these two schemes in our soft X-ray $M_{4,5}$ edges, where TFY probes the full 5.5 nm of the SmN layers while TEY data probe a depth of ~ 2 nm. Saturation effects distorted the TFY mode at the Sm $M_{4,5}$ edges, but nonetheless provide relative comparisons between different samples.

5.3 L-edge XMCD Results

We first discuss the hard X-ray results from the SmN/GdN superlattice and the homogeneous SmN sample. Figure 5.3 shows XMCD data from the superlattice at the Sm L₃ edge, compared to the Sm L₃ in homogeneous SmN. These spectra primarily show the dipole transitions from 2p to empty 5d orbitals, with weaker quadrupolar excitations to the 4f shell, and thus signal the strength and sign of the spin and orbital alignments of the 5d, and less quantifiably, the 4f shells. The 5d states participate in the ordering through 4f-5d exchange, though the exchange mechanism between 5d states is not well understood [28]. The XMCD sign reversal shown in Fig. 5.3 between homogeneous SmN and thin SmN layers embedded in GdN immediately indicates that Sm-Gd interface



Figure 5.3: XMCD at the Sm L_3 edge in a SmN/GdN superlattice (SL) and a homogeneous SmN film taken at 15 K and a field of 6 T. The signal above 6715 eV is predominantly due to electric dipole (ED) transitions into the 5*d* shell, and below that the signal is due to electric quadrupole transitions (EQ) into the empty 4*f* orbitals.

exchange determines the Sm spin alignment, dominating the weak Zeeman interaction that aligns the net, orbital-dominated, moment in homogeneous SmN.

The data displayed in Figure 5.4(a) compares the hysteresis between homogeneous SmN and SmN in the superlattice, further demonstrating that the SmN coercive field in the superlattice is reduced to ~ 0.01 T, emphasizing that the SmN magnetization is firmly coupled to the GdN by the exchange interaction across the GdN/SmN interfaces. The inset shows the ~ 0.01 T coercive field measured at the Gd L₂ edge. There is an intrinsic sign difference between the most prominent XMCD features at the Sm L₂ and L₃ edges, so we have scaled the L₃ derived hysteresis by -1 in Figure 5.4(a) in order to indicate the antiparallel spin/orbit alignment between samples, which is clear from the direct L₃ edge comparison in Figure 5.3. Examples of the XMCD spectra used to produce Figure 5.4 (a) are shown in Figure 5.4 (b)-(d), along with the XAS spectra.

We now turn to the temperature dependence of the GdN L_3 and SmN L_3



Figure 5.4: (a) XMCD-derived hysteresis taken at 15 K and 6 T and measured at the Sm L_2 edge for the superlattice (squares) and at the Sm L_3 -edge for the bulk SmN film (circles). The superlattice spectrum was scaled by -1. The inset shows the Gd L_2 edge hysteresis taken at 15 K. Typical XMCD spectra from which the hysteresis curves shown in (a) are derived are shown in (b)-(d) along with the XAS spectra measured at 6 T. The black arrows show the XMCD peaks followed to determine the XMCD hysteresis in (a).


Figure 5.5: (a) Temperature dependence of Gd L_3 and Sm L_3 peaks in a field of 2.5 T for the SmN/GdN superlattice. (b) Superlattice Gd L_3 -edge XAS and XMCD spectra taken at 15 K and 6 T.

XMCD, which is shown in Figure 5.5, with an applied field of 2.5 T. The Sm moments in interface-adjacent ions are again aligned to the GdN moments across the interface at temperatures above the 27 K Curie temperature of SmN. However, at lower temperatures the Sm moment continues to rise faster than does the rapidly saturating GdN, as the Sm ions deeper in the SmN layer align by the Sm-Sm exchange interaction. At first approximation the SmN alignment follows the GdN at the interface, with Sm deeper in the SmN layers aligned only well below 27 K. Those inner ions would then not align fully until below the 17 K minimum temperature in the data. The strong interface coupling between GdN and SmN spin-moments prevails over the orbital-dominated Zeeman coupling in the SmN layers.

We may also use the results of Chapter 4 to derive more quantitative conclusions about the interface coupling. In Chapter 4 we saw that the experimentally observed SmN magnetic moment of 0.035 μ_B per Sm ion could be reproduced within the point charge model with Z = 2.4 when excited *J*-multiplets are included. The exchange parameter was estimated from the paramagnetic Curie temperature of 27 K. In the superlattice interface exchange clearly modifies this parameter.

If we assume that the effective SmN exchange is proportional to the 5d spin polarization, then the electric dipole signal at the Sm L₃ edge is a measure of

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		./			

Exchange parameter	$\langle S_z \rangle$	$\langle L_z \rangle$	$\langle L_z + 2S_z \rangle$
$J_{ex} = 7.9 \text{ K}$	-0.982	1.996	0.033
$J_{ex}^{SL} = 3J_{ex}$	-1.48	3.11	0.16

Table 5.1: Expectation values of Sm³⁺ in a cubic crystal field with Z = 2.4 (See Chapter 4). The exchange constant is estimated to be three times larger in the superlattice, resulting in a 50% larger value of $\langle S_z \rangle$.

the exchange strength in SmN. In particular, it represents the average value of the exchange strength (and spin polarization) through the film, which varies with distance from the GdN/SmN interfaces. In the superlattice the electric dipole signal is a factor of ≈ 3 larger than in homogeneous SmN, thus $J_{ex}^{SL} \approx$ $3J_{ex}$ where J_{ex} is 7.9 K, as estimated from the SmN Curie temperature. Using J_{ex}^{SL} in the calculation of the 4f magnetic moments results in a value of $\langle S_z \rangle$ increased by 50% compared to the homogeneous SmN (see Table 5.1). This value can be compared to the electric quadrupole (EQ) transitions in Figure 5.3, which represent the transitions to the 4f states. The EQ XMCD is thus proportional to the 4f spin (or orbital) moment. The amplitude of the EQ signal increases by a factor of 60% in the superlattice as compared to the homogeneous SmN, in good agreement with the calculation.

These increased amplitudes relate only to the average over the SmN layer thickness. The thin 1.5 nm SmN layers consist of 5 atomic planes of Sm ions, thus $\approx 40\%$ of the Sm ions are interfacial. If only these GdN-adjacent layers experience interface exchange they require an increase in the 5*d* polarization by a factor of 7.5 to explain the 3-fold enhancement of the EQ XMCD signal above. This seems plausible given the large spin value of GdN, which has a moment of 7 μ_B , seven times the homogeneous SmN spin moment calculated in Chapter 4.

5.4 M-edge XMCD Results

We access the magnetic alignment of SmN more directly by turning to the soft X-ray $M_{4,5}$ edges, which represent $3d \rightarrow 4f$ transitions and thus signal the spin and orbital alignment in the 4f shell. Figure 5.6(a) sketches the geometry

of the M-edge measurements, with the magnetic field and X-rays parallel to the surface normal. Figure 5.6(b) shows the XAS spectra for the bilayer and trilayer sample in both TEY and TFY modes. The spectra show the features associated with the multiplet structure of the Sm^{3+} as shown in Chapter 3.

Figure 5.6(c) shows the Sm $M_{4,5}$ -edges XMCD in both TEY and TFY modes for the two samples. For the trilayer, the TFY and TEY spectra in the SmN layer are in excellent agreement, establishing that SmN 4*f* alignment in the near-surface region and the bulk average are of the same sign, suggesting the SmN is effectively decoupled from the GdN. In contrast, both TFY and TEY signals are substantially weaker in the bilayer, and the TFY signal is even inverted. The latter is a signature of SmN that is strongly coupled to the GdN by exchange across the GdN/SmN interface.

To quantify the differences in XMCD between samples we curve fit the spectra to each other over both M_4 and M_5 edges, instead of simply comparing the intensity at the maximum XMCD signal at ~ 1077 eV. This is to reduce the effects of noise, especially for the bilayer sample. This fitting is reasonable because the strong spin-orbit coupling of the 4*f* electrons keeps spin and orbital moments firmly aligned relative to each other [65, 100], and so the XMCD sum rules [55, 56] imply that the XMCD spectral shape should remain the same between the samples, though with an overall scaling factor. This scaling factor is a measure of how the depth averaged XMCD is different between samples, and thus how the spin/orbital alignment of the 4*f* magnetic moment varies through the depth. Figure 5.7 shows XMCD spectra which represent the average of multiple measurements and least-squares fits to them.

Fitting of the spectra yields spin/orbital-alignment ratios of bilayer-totrilayer of $R_{\text{TEY}} = 0.20 \pm 0.07$ and $R_{\text{TFY}} = -0.12 \pm 0.02$. For the bilayer then, the alignment in the surface ~ 2 nm probed by TEY is Zeeman-dominated (i.e., bulk-like SmN) but the average through the film is of opposite sign, as was found also in the very thin SmN layers in the superlattice of the L_{2,3}edge study above. We interpret this inhomogeneous alignment in the bilayer as a rotation of the spin and orbital moments through the depth of the film, similar to a domain wall. The distinction is that this rotating or twisted state originates from the interface exchange-Zeeman competition.



Figure 5.6: (a) Sketch of sample geometry, with magnetic field and X-rays along the surface normal. (b) XAS spectra taken at the Sm $M_{4,5}$ edges for both the bilayer and trilayer in TEY and TFY modes. The spectra reveal the expected Sm³⁺ character present in SmN. (c) XMCD for bilayer and trilayer in TEY and TFY modes, taken with a field of 4 T and 10 K. (d) Hysteresis derived from a fit of the bilayer TFY spectra. Black line represents a smooth average as a guide to the eye, inset arrows show spin and orbital rotations.



Figure 5.7: Averaged XMCD spectra at the Sm $M_{4,5}$ edges. The bilayer spectra have been fit to the trilayer in TEY and TFY modes. The bilayer least-squares (LS) fit (blue circles) represents the bilayer spectra scaled by the fit factor R_{TXY} for TEY and TFY modes.

Figure 5.6(d) shows an unusual hysteresis curve extracted from the bulk sensitive TFY measurement of the bilayer, where SmN is deposited directly on GdN. The same fitting procedure mentioned above was used to extract the hysteresis. The Sm 4f alignment in this case shows the same sign inversion seen in the L_{2,3}-edge data in Figures 5.3 and 5.4, but with diminishing alignment with increasing fields larger than ≈ 1.5 T. It is important to note that in the field-normal configuration, the shape anisotropy of GdN prevents a saturated magnetization in applied fields smaller than ≈ 2.5 T. Its magnetization rises approximately linearly with weaker applied fields, but for larger fields the GdN is saturated; between 2 and 4 T the 4f spins are fully aligned and exert the full Gd-Sm exchange on the SmN 4f spin-moment at the interface. In this region the increasing field has the effect of modifying the exchange-Zeeman competition which in turn reduces the bulk averaged XMCD signal as the 4f spin and orbital moments rotate through the film. In the following section we pursue deeper insight into the nature of the twisting, or rotating magnetization.

5.5 Analysis and Discussion

In this section we relate the measured TEY and TFY XMCD results in the bilayer to a model of the twisting SmN magnetization. We consider a one dimensional model of the SmN magnetization in the bilayer, in which the resulting magnetization profile is determined by the balance among (i) the Sm-Sm exchange energy acting on Sm spin moments, (ii) the Zeeman energy acting on the SmN net moment, and (iii) the demagnetization field of SmN. Our description of the magnetization follows that of Goto *et al.* [38] and Thiaville & Fert [81] (briefly discussed in Chapter 2), which treats atomic planes parallel to the SmN surface as each having a uniform magnetization, such that the problem is reduced to a one dimensional model where each atomic plane is treated as a single effective magnetic moment. In the continuum limit, the magnetic free energy per unit area (at T = 0), integrated along the depth L of the SmN film can then be written as

$$\mathcal{E} = \int_0^L \mathrm{d}z \, \left[A \left(\frac{\mathrm{d}\theta(z)}{\mathrm{d}z} \right)^2 - \mathbf{M}_s \cdot \mathbf{H} - \frac{1}{2} \mathbf{M}_s \cdot \mathbf{H}_d + E_{\mathrm{anis}} \right].$$
(5.1)

where A is the exchange stiffness, \mathbf{M}_s is the saturation magnetization of the SmN, $\mathbf{H} = H\hat{\mathbf{z}}$ is the applied field, and L = 5.5 nm is the thickness of the SmN film. $\theta(z)$ is the depth-varying angle between \mathbf{H} and the spin-moment \mathbf{m}_S (see Figure 5.8(a)) We note that for the thin film geometry with the field perpendicular to the plane the demagnetization field is given by $\mathbf{H}_d = -4\pi\mathbf{M}_s = -0.01$ T which can be neglected in comparison with the Zeeman energy in the large (4 T) fields we consider here. The E_{anis} term corresponds to magnetocrystalline anisotropy, however there are no studies of its effects in SmN [30] and our results suggest it is only a weak correction. Out of plane rotation (i.e. the plane formed by \mathbf{H} and the magnetization) can be ignored as this creates a static field which tends to only increase the energy.

Simplifying Equation (5.1) we arrive at

$$\mathcal{E} = \int_0^L \mathrm{d}z \, \left[A \left(\frac{d\theta(z)}{dz} \right)^2 - \mathbf{M}_s \cdot \mathbf{H} \right].$$
(5.2)

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This equation is formally identical to that used in exchange spring-systems when anisotropy is negligible (Chapter 2) [38, 93]. The crucial distinction is that the Zeeman term adopts the opposite sign as found in conventional spindominant systems, due to the fact that the net moment is antiparallel to the \mathbf{m}_S , hence $-\mathbf{M}_s \cdot \mathbf{H} = M_s H \cos \theta(z)$. The Zeeman energy is thus minimized when $\theta(z) = \pi$. The exchange stiffness $A = 4J_{ex}S^2/na^*$ involves the exchange constant J_{ex} estimated from the experimental Curie temperature of SmN and the number n of nearest Sm ion neighbors. The nearest neighbor Sm³⁺ distance is a^* , related to the SmN lattice constant by $a^* = a/\sqrt{2}$.

Equation (5.2) can be minimized analytically (see Appendix B for details) to yield the most energetically favorable configuration, as carried out by Goto *et al.* [38] for an exchange-spring system, yielding the following expression for $\theta(z)$:

$$\theta(z) = 2 \arcsin \left[K^{-1} \left(\alpha L \right) \sin \left(\alpha z \right) \right], \tag{5.3}$$

where $\alpha = \sqrt{HM_S/2A}$, and the functions K^{-1} and sn are the inverse of the complete elliptic function of the first kind and the Jacobi elliptic function of the first kind, respectively. The boundary conditions were chosen such that $\theta(L) = 0$ (Sm spin is aligned with the Gd spin at the SmN-GdN interface) and $d\theta(z)/dz|_{z=0} = 0$ (SmN free surface). These boundary conditions account for the magnetically soft GdN being rigidly fixed parallel to the applied field due to its large Zeeman interaction. This fixed GdN then acts as the rigid pinning layer for the SmN at the interface.

A twisted phase develops on a scale of $\ell = \pi/2\sqrt{2A/HM_S}$; below this thickness a uniform magnetization ($\theta(z) \equiv 0$) is the only solution to Equation (5.3) In an applied field of 4 T this corresponds to $\ell \approx 4$ nm, on the order of the SmN film thickness. Figure 5.8(b) shows the calculation of the net moment and spin-moment projected on the z-axis (i.e., $m \cos \theta(z)$ and $m_S \cos \theta(z)$), as a function of the depth z in the 4 T field. The scale of the twist increases in a field of 2 T as the Zeeman energy weakens, illustrated in Fig. 5.8(a). In this plot we have assumed that the spin moment m_S is the fully polarized value of $2.5 \ \mu_B$, which according to the calculation in Chapter 4 is reduced to around $1 \ \mu_B$ per Sm ion. However, in the following we show that the value of m_S does



Figure 5.8: (a) A sketch of the in-plane twisted magnetization structure near the SmN-GdN interface with spin moments (blue) and orbital moments (red). (b) Calculation of the spin and net moment as a function of thickness in the SmN layer of the bilayer. The Gd moment is fixed at 7 μ_B through the GdN film, and the Sm spin-moment is pinned at the SmN/GdN interface to its maximum value of 5 μ_B .



Figure 5.9: A plot of the $m_S \cos\theta(z)\exp(-z/\lambda_{\text{TXY}})$ for various values of λ_{TXY} . For example, for the TEY ratio, we calculate $R_{\text{TEY}} = 0.24$ for $\lambda_{\text{TEY}} = 1.75$ nm and $R_{\text{TEY}} = 0.19$ for $\lambda_{\text{TEY}} = 2.25$ nm. The experimental value of $R_{\text{TEY}}^{\text{exp}} = 0.20$ thus corresponds to the value of $\lambda_{\text{TEY}} \approx 2.15$ nm.

not affect the comparison with experiment.

The resulting depth profile of the net SmN moment projected along the zaxis, $m \cos \theta(z)$, can be compared to the XMCD spectra by accounting for the depth-averaging of the XMCD measurement, in combination with the effective sampling depth in the TXY (TEY or TFY) measurement schemes, λ_{TXY} . The finite sampling depth λ_{TXY} in the TXY mode results in a detection efficiency $w_{\text{TXY}} = e^{-z/\lambda_{\text{TXY}}}$ from a depth z [41]. Thus we can approximate the depth averaged XMCD measurement as returning an effective net moment of

$$\langle m \rangle_{\text{TXY}} = \frac{1}{L} \int_0^L \mathrm{d}z \ m \cos \theta(z) e^{-z/\lambda_{\text{TXY}}}.$$
 (5.4)

Absolute values of m_S and the orbital moment m_L can in principle be extracted by applying the XMCD sum rules, however they require much greater signal-to-noise ratios than available with the present data. Instead we note that m_S and m_L in both samples are fixed antiparallel by the strong spin-orbit coupling, and the XMCD spectra remain proportional. The ratios of $\langle m \rangle_{\text{TXY}}$ between the bilayer and trilayer are thus expressions for the experimentally determined ratios, which simply reflects the depth-average of $\cos \theta(z)$ within the bilayer. The calculated ratio $R_{\text{TXY}} = \langle m \rangle_{\text{TXY}}^{\text{bilayer}} / \langle m \rangle_{\text{TXY}}^{\text{trilayer}}$ in the TFY mode gives $R_{\text{TFY}} = -0.11$, in excellent agreement with the measured ratio of $-0.12\pm$ 0.02. R_{TFY} is insensitive to the precise value of λ_{TXY} ($\approx 100 \text{ nm}$), as $d \ll \lambda_{\text{TFY}}$; the fluorescence is effectively unattenuated. The TEY-channel ratio depends more strongly on λ_{TEY} ; the experimental value of $R_{\text{TEY}} = 0.20$ is returned for an electron escape depth of $\lambda_{\text{TEY}} = 2.15 \text{ nm}$, which is consistent with the expected range [41, 45]. The resulting spin-moment depth profiles calculated using $J_{\text{ex}} = 7.9 \text{ K}$ are shown in Fig. 5.9, where $m_S \cos \theta(z) \exp(-z/\lambda_{TXY})$ is plotted as a function of depth for the various λ_{TXY} values, along with the actual spin moment profile, $m_S(z) \cos \theta(z)$. The excellent agreement of this analytical model with the experimentally measured spectra thus strongly supports the mechanism of exchange-Zeeman competition driving the twisted magnetization in the SmN layer coupled to GdN.

The effect of the enhanced interface exchange observed in the SmN/GdN superlattice has been ignored in this analysis, as is not expected to qualitatively alter the main results. The much thicker SmN in the bilayer compared to the superlattice contains approximately 15 atomic planes of Sm ions, and means that the enhanced exchange at the interface layer would have only a small effect. The agreement achieved by using only experimental parameters and reasonable values of λ_{TXY} is encouraging and indicates that other effects, including bulk and surface anisotropies are only weak corrections to the exchange and Zeeman dominated contributions. We add that the continuum approximation leading to Eq. (5.2) has been shown to be in good agreement with more exact treatment using a discretized version of the model, even down to a few monolayers [101].

5.6 Conclusion and Outlook

In summary, we have observed a novel twisted magnetization phase in a SmN/GdN bilayer by exploiting the depth dependence of the electron-yield and fluorescence-yield detection modes at the rare-earth M-edge XMCD. Remarkably, it is in fact the *hard* magnetic SmN layer which develops the twisted

phase, while the soft GdN film remains fixed parallel to the field. The interfacial pinning of the SmN moment to GdN was also clearly demonstrated in the L-edge XMCD measurements, showing that the ferromagnetic GdN-SmN exchange coupling is responsible for the pinning. The crystal field calculations of Chapter 4 provided an explanation of how the interface-exchange altered the SmN 4f spin and orbital moment alignments, in good agreement with experiment.

The relatively simple model used to describe the SmN magnetization is just a starting point for exploring these twisted phases. Acquiring XMCD data at the M-edge with higher signal-to-noise ratios would allow for the application of more sophisticated modelling, however experiments are difficult to perform on this system for a few reasons. One is the extremely small moment of SmN which leads to intrinsically weak dichroism, while the necessity for a capping layer leads to a low signal-to-noise ratio. The *in-situ* sample growth possible at a few XMCD beamlines in synchrotrons around the world would remove the need for a capping layer during measurements, allowing for much higher signal-to-noise ratios to be obtained.

The decoupling of the SmN and GdN magnetization in the SmN/LaN/GdN structure points towards magnetic tunnel junctions, especially attractive within the RENs owing to their epitaxial compatibility across the series. The appearance of a twisted phase in the SmN/GdN system also holds intriguing possibilities for spintronic applications, owing to the semiconducting nature of the pair coupled with the orbital-dominant magnetism of SmN. For example, the tuning of the twisted phase length scale $\ell \sim \sqrt{A/HM_s}$ for given fields can be achieved through doping, or replacement, with other rare-earth elements, thus modifying the exchange A and the saturation magnetization M_s [62]. The ability to control the scale of what is effectively a domain-wall width in intrinsic ferromagnetic semiconductor heterostructures also allows for the opportunity to explore spin-orbit torques in a novel system.

Chapter 5 Twisted Magnetization in SmN/GdN

Chapter 6

Twisted Magnetization in a NdN/GdN Superlattice

6.1 Introduction

In this chapter, we pursue the study of NdN/GdN superlattices, a system which shares some similarities to the SmN/GdN system investigated in Chapter 5. NdN, like SmN, is an orbital-dominant ferromagnet, making it a good candidate to explore twisted phases relying on exchange-Zeeman competition. The Nd³⁺ ion is an f^3 system, and Hund's rules yield an L = 6 orbital and S = 3/2spin contribution to the total angular momentum, which has the ground state value J = |L - S| = 9/2. In contrast to the near-zero ferromagnetic moment of SmN, NdN yields a much larger orbital-dominant moment between 0.9 -2.1 μ_B per ion in the ferromagnetic phase, as we saw in Chapter 4. The net NdN moment has a magnitude of 15 - 30 % of the GdN moment.

With this sizable NdN moment we can expect that the GdN is influenced by exchange at the interface with NdN, and we may expect that twisted magnetizations will form in both NdN and GdN layers. This is in contrast to the case of the SmN/GdN interface, where the small Zeeman coupling of the SmN meant that the GdN was aligned solely by its Zeeman interaction, which kept it rigidly aligned parallel to the field.

This large NdN moment has another important effect. While the GdN signal dominates the overall magnetization of a NdN/GdN superlattice, the

NdN contribution is still observable, in contrast to the SmN/GdN system. This means that it is possible to see clear signals of the NdN in standard lab-based magnetometry techniques. As we shall see, magnetometry, coupled with the element-specific probe of XMCD provides us a detailed picture of a remarkable system in which a twisted magnetization forms due to the presence of a large orbital-dominant moment. This investigation also serves as a confirmation for the mechanism of the orbital-driven twisted phase observed in the SmN/GdN systems.

In this chapter we focus on a single NdN/GdN superlattice, outlining the sample preparation and characterization, and then continue to a study of the magnetic properties. First we discuss results from magnetometry, which investigates the temperature and field dependence of the sample. Next we turn to an XMCD study of the superlattice, measured at the Nd $L_{2,3}$ edges, which probes the Nd 5*d* states which participate in mediating the exchange. In both magnetization and XMCD studies we present clear evidence of a twisted magnetization phase in the NdN and GdN layers.

6.2 Experimental Details

The sample investigated in this chapter is a $10 \times (10 \text{nm MdN}/10 \text{ nm GdN})$ superlattice grown on a GaN(0001) buffer layer with a sapphire (0001) substrate. The general procedure was the same as used in Chapter 5 and discussed in Chapter 2. Growth took place in a N₂ pressure of 2×10^{-4} Torr, NdN and GdN were evaporated with an electron gun at a rate of 0.1 to 0.2 Å/s. The substrate was outgassed for one hour at 600° C, while the temperature was kept at 390° C during the growth. A GaN capping layer of approximately 50 nm was grown at room temperature at a rate of 0.1 Å/s with a plasma source exciting the N₂ in a pressure of 2×10^{-4} Torr. Figure 6.1 shows a 2θ XRD scan of the superlattice and from a substrate for comparison. The reflection at 31° corresponds to overlapping GdN and NdN [111] reflections. Also visible is the GdN/NdN [220] reflection at 53°, indicating that the film is polycrystalline.

Magnetization measurements were carried out via a Quantum Design SQUID and vibrating sample magnetometer (VSM). These measurements were all car-



Figure 6.1: XRD pattern from the NdN/GdN superlattice with substrate, a GaN(0001) buffer layer on Al_2O_3 (0001).

ried out with the field in-plane.

6.3 Magnetization Results

We begin by examining the "global" magnetization of the superlattice, which is a sum of contributions from the individual GdN and NdN layers. Figure 6.2 displays the zero-field cooled (ZFC) and field cooled (FC) magnetization curves. In the ZFC measurement, the sample is cooled from room temperature to 5 K in zero field; the magnetization is then measured as the temperature is increased in an applied field of 250 Oe. In the FC process, the magnetization is measured with decreasing temperature in a field of 250 Oe.

We see that in both curves, as the temperature is decreased, the magnetization increases rapidly starting at about 70 K until approximately 50 K, corresponding to the onset of ferromagnetism in the GdN layers. The region above \approx 70 K corresponds to the paramagnetic phases of GdN and NdN. We use a Curie-Weiss approach to fit the susceptibility, assuming that the GdN



Figure 6.2: Temperature dependent magnetization of the NdN/GdN superlattice in a 250 Oe field, showing both field-cooled (FC) and zero-field cooled (ZFC) measurements. Inset shows Curie-Weiss behavior in the inverse susceptibility taken from the FC measurement.

dominates the paramagnetic response. In this case χ is given by

$$\chi = M/H = \frac{A}{T - \theta_p} + \chi_0, \tag{6.1}$$

and χ_0 is a temperature independent background primarily due to the diamagnetic signal from the substrate. After removing the background signal χ_0 , we may then plot χ^{-1} , which should be proportional to $T - \theta_p$ in the high temperature region above the T_C of both NdN and GdN, shown in the inset of Figure 6.2. The linear behavior is clearly visible, yielding a $\theta_p = 65 \pm 1$ K, expected for polycrystalline GdN [12, 57, 92]. One might expect a contribution from the NdN layers in this approach, however it would be strongly suppressed due to the smaller moment and lower T_C . As an estimate, in the Curie-Weiss theory the constant A in Equation 6.1 is proportional to m_{eff}^2 , where $m_{\text{eff}} = g_J \mu_B \sqrt{J(J+1)}$ is the effective paramagnetic moment. This value is roughly 5 times larger in GdN, and at 85 K the factor of $(T - \theta_p)^{-1}$ is about 3 times larger in GdN than for NdN, so the overall NdN signal at 85 K should be about 15 times weaker for NdN, explaining the Curie-Weiss behavior with the θ_p of GdN. Below the GdN T_C , the rapidly increasing magnetization continues until around 50 K. In the range of 30-40 K the NdN should become ferromagnetic, and indeed we see a change in slope in both curves in this temperature range. It is difficult to pinpoint the precise T_C of NdN in the superlattice, however we assume that it corresponds approximately to the values discussed in Chapter 4, which ranged from ≈ 35 to 42 K. The ZFC magnetization has different behavior in the low temperature region due to the random orientation of the domains in the ZFC process, which reduces the magnetization compared to the FC measurement. We note that the low temperature behavior of the FC magnetization differs from that in homogeneous GdN samples [10, 12] which approach saturation as a ferromagnetic Brillouin function. This appears to be due to the ferromagnetic NdN influencing the net magnetization of the superlattice. To further elucidate the interplay between ferromagnetic NdN and GdN, we turn to field-dependent magnetization measurements.

Figure 6.3 shows the superlattice M - H loop taken at 5 K. The sample was first zero-field cooled to 5 K, with the magnetization then increased to 6 T. The blue curve represents the subsequent measurement as the field is decreased from 6 T, while the red curve was measured for increasing field. Examining the blue curve, upon decreasing from 6 T and reaching H = 0 (see inset), we clearly see that the remanent magnetization $M_R = -0.3 \times 10^2$ emu/cm³ is *negative*. The coercive field, $H_C = -0.02$ T, is negative as well in this case. The negative sign for H_C and M_R indicates that the net magnetization of the superlattice switches sign before H does. Furthermore, as the field decreases, there is a change in slope between -2 T and -4 T, which cannot be ascribed to bulk GdN or NdN behavior, which each have coercive fields well below 2 T in magnitude.

The negative remanent and coercive fields point to complex behavior in the superlattice, and indicate that the hysteresis curve cannot be interpreted within a model of two non-interacting ferromagnets, in which the global magnetization is simply the sum of individual layers having bulk-like magnetization. Exchange bias systems where ferromagnetic films are coupled to antiferromagnetic films may also exhibit complex hysteresis loops [102], however, they are qualitatively different systems, and can be viewed as ferromagnetic systems



Figure 6.3: M-H plot for the NdN/GdN superlattice, at 5 K, with field in-plane, after zero-field cooling. Sketches of the various moment arrangements (1)-(5) in the GdN and NdN layers are given as the field decreases from saturation 6 T; the sketches should thus be read from right to left.

where the origin of the hysteresis is shifted by some exchange-bias field H_{EB} .

How can we explain the negative remanent field M_R ? We first of all assume at that 5 K and $\mu_0 H = 6$ T the moments are close to their saturation values, approximately 7 μ_B per ion for GdN and 0.9 - 2.1 μ_B per ion for NdN. In this case the NdN moment is only 16 - 30% of the GdN moment. The only reasonable explanation for the negative magnetization at remanence is for the GdN, with its much larger moment, to have its magnetization direction partially reversed when H = 0. The reversal of the GdN can then be explained if ferromagnetic exchange coupling between NdN and GdN spins is present at the interfaces. Because NdN is an orbital dominant ferromagnet, this FM exchange coupling mimics antiferromagnetic exchange coupling: when the spin moments are aligned the net magnetizations are antiparallel. The NdN, with its large (≈ 1.5 T in bulk NdN) coercive field at 5 K, is unlikely to switch due to its large anisotropy energy, and therefore the interface exchange causes the GdN to reverse while the NdN remains fixed, acting as a hard anchoring layer. This situation is sketched in Figure 6.3, where both the NdN and GdN layers have their magnetization sketched in configurations corresponding to points on the blue (decreasing field) part of the M-H curve. In the following we discuss the magnetization configurations in more detail.

Starting in configuration (1) in Figure 6.3, at 6 T, the GdN and NdN layers have their magnetization aligned fully along the field. Upon decreasing the field to configuration (2), the interface-adjacent GdN layers begin to be aligned by ferromagnetic exchange with the NdN, and thus reverse their direction. The NdN layer is rigid due to its large anisotropy compared to GdN. Upon reaching zero field (3), the NdN maintains its alignment, while the GdN alignment is dominated by interface exchange. The GdN magnetization reversal nucleates from the interfaces and a twisted magnetization is formed such that the net magnetization of the GdN is negative, and large enough to make the global superlattice magnetization negative. As the field becomes negative in (4), the GdN is now fully aligned with the field, while the innermost NdN layers begin to reverse their magnetization. Finally, when the field reaches -6 T in configuration (5), the NdN magnetization and GdN are both fully aligned by the field. The



Figure 6.4: Superlattice hysteresis loops measured at (a) T = 35 K, which shows positive M_R and H_C and at (b) T = 50 K which shows the hysteresis resembling a homogeneous GdN film.

process is symmetric upon increasing the field from this point.

We summarize the process described in Figure 6.3 as taking part in two steps. The first step is the GdN layers form a twisted magnetization phase as the field is decreased from 6 T, eventually fully reversing at some small negative field. This results in the negative M_R . The second step occurs between about -1 and -4 T, where the NdN forms a twisted phase and slowly reverses, resulting in the "hump" in the blue magnetization curve between -4 and -1 T. These two processes are due to the competition between the Zeeman coupling, interface coupling, and anisotropy.

Figure 6.4 shows additional hysteresis loops measured at T = 35 K (with fields up to 8 T, via VSM measurements) and 50 K. At 35 K, we notice that M_R is positive, signalling that the average GdN alignment does not reverse until after the field changes sign. There is again a "hump" feature in the magnetization, occurring between -1.5 and -0.3 T when the field is decreased. This suggests the NdN is undergoing magnetization reversal via a twisted phase in this region. At 35 K it is clear that the NdN has a reduced anisotropy and magnetization and is not able to effectively pin the GdN through interface exchange, but is still influenced by the interface exchange with GdN. Figure 6.4(b) shows the M-H loop at 50 K, above the NdN T_C . It resembles the hysteresis loop of a homogeneous GdN film.



Figure 6.5: (a) Temperature dependent remanent magnetization after fieldcooling in +6 T. (b) Coercive field H_C versus temperature for the superlattice.

These hysteresis measurements show that with increasing temperature the NdN anisotropy will vary strongly as T approaches 40 K, and the NdN will not be able to act as a rigid pinning layer for the GdN. To better understand this temperature dependence, we turn to new temperature dependent magnetization measurements. Figure 6.5(a) shows the temperature dependent remanent magnetization of the superlattice. The curve was obtained by field-cooing in a 6 T field in order to fully saturate the magnetization of both layers. After the field cooling process, the field was reduced to zero. The curve thus represents the remanent magnetization as a function of increasing temperature.

One immediately recognizes that the magnetization in Figure 6.5(a) is *negative* at 5 K, which is at first sight surprising, however this agrees with the negative value of M_R in Figure 6.3 when the field is decreasing. In the large 6 T field, the GdN and NdN should be fully saturated, and when the field is reduced to zero, the NdN should remain largely aligned due to its large coercive field. The GdN layer magnetization, on the other hand, with a two orders-of-magnitude smaller coercive field, begins to reverse due to interface exchange with the rigid NdN layers.

The decreasing magnetization as the temperature rises from 5 to 20 K is a result of the inner GdN magnetization reversing as the GdN anisotropy energy diminishes. From 20 K to 40 K the flat slope implies that the GdN magnetization is largely aligned by interface exchange, as there is no Zeeman coupling competing with the interface exchange. At about 40 K the bulk NdN is no

longer in the ordered phase, while the GdN however remains ferromagnetic. Above 40 K the negative magnetization rapidly approaches zero as thermal fluctuations reduce the GdN alignment until the GdN T_C is reached. This is clear evidence that the GdN is responsible for the negative remanent field in Figure 6.3.

We also plot H_C as a function of temperature, shown in Figure 6.5(b), where the data has been extracted from additional hysteresis measurements. Here the transition from a negative to positive H_C occurs between 20 and 35 K, coinciding with the temperature of the sign change of M_R . The negative H_C is of course a consequence of the GdN being reversed, thus above 35 K the GdN is aligned parallel to the field. At 50 K, above the NdN T_C , we see that the small ≈ 6 mT coercive field is close to that expected from GdN alone, while the maximum 40 mT coercive field occurs at 35 K, while the NdN is still in an ordered phase.

Based on this magnetization data it is clear that the large NdN anisotropy, orbital dominant moment, and the ferromagnetic exchange coupling together result in a complex magnetic system where both NdN and GdN layers form twisted phases. At small fields, the GdN magnetization is dominated by interface exchange which reverses it before the field changes sign. The NdN is however prevented from reversing at its typical bulk H_C value due to this interface exchange, and only reverse very gradually via a twisted phase, fully reversing only in fields over 5 T. In the next section we explore the NdN and GdN layer magnetization separately via the element specific XMCD technique, which will give us indispensable insight into this complex magnetic system.

6.4 XMCD Investigation

In this section we make use of the element specific nature of XMCD to shed light on the individual behavior of the GdN and NdN layers in the superlattice. The XMCD is measured at the Nd L_2 and Gd $L_{2,3}$ edges, which is in the hard X-ray regime, with energies exceeding 7 keV. At these energies, the absorption cross section is relatively low, precluding the possibility of studying single interfaces. Superlattice structures are then necessary to increase the signal by effectively multiplying the number of interfaces. Here we measure the same superlattice sample which was measured in the previous section, allowing for direct comparisons to be made.

6.4.1 XMCD experimental details

The XMCD was measured at beamline 39XU at the SPring-8 synchrotron in Japan. The spectra were taken with the X-rays and the magnetic field co-linear and at an angle of 18° from grazing incidence. The experiment took place in fields of up to 1.2 T, and temperatures down to 16 K, though most measurements took place at 30 K. The XMCD was measured at a fixed magnetic field while the x-ray polarization was switched. The dichroic signal is then given by the difference between antiparallel and parallel alignments of the helicity and magnetic field. The detection scheme was partial fluorescence yield (PFY) as discussed in Chapter 3. In the PFY scheme, the $L_{\alpha 1}$ fluorescence is measured when probing the Nd or Gd L₃ edge, while the L_{β_1} emission line is measured at the Nd or Gd L_2 edge. This method however eliminates the possibility of observing quadrupole transitions $(2p \rightarrow 4f)$ which directly probe the 4f electrons, as the L_{α_1,β_1} emission lines involve the 3d states and not the 4f. Because fluorescence has a long mean free path of well over 1000 nm at these emission line energies, the measured XMCD represents the average signal from all the superlattice layers of one composition.

The XMCD spectra were normalized to the edge-jump measured from the XAS. A correction to the XMCD spectra was necessary at the Nd and Gd edges to account for a small imbalance between the degree of left and right circular polarization of the incident X-rays. To account for this, samples were field cooled from room temperature down to 16 K in both ± 1.2 T. The sum of these two XMCD spectra should in principle yield zero for equal amounts of left and right polarized X-rays, however a small signal proportional to the absorption spectrum was present. This small background is then subtracted from the XMCD spectra. Figure 6.6 shows the raw and corrected spectra as well as the background signal, proportional to the XAS at the Gd L₂ and Nd L₂ edges. The GdN L₂ edge requires only a small correction due to the large



Figure 6.6: XMCD signal correction at the Gd L_2 edge (a) and Nd L_2 edge (b). XMCD spectra were measured at 16 K after field-cooling in ± 1.2 T. The background signal is proportional to the XAS signal, and is subtracted to reveal the actual XMCD signal.

amplitude of the XMCD, while the NdN L_2 is significantly distorted before correction.

6.4.2 Gd $L_{2,3}$ and Nd L_2 edges

We first look at the superlattice Gd L₂ and L₃ edges, shown in Figure 6.7, which shows the XAS and XMCD spectra, taken in a field of 1.2 T at 16 K, with a 30 K spectra also measured at the L₂ edge. The sign of the XMCD spectra agree with those in studies on GdN carried out by Leuenberger *et al.* [103], and agree with the results of the SmN/GdN superlattice in Chapter 5. This Gd XMCD sign means that the GdN magnetic moment (i.e. spin moment) is aligned parallel to the field. This is expected, as the large 7 μ_B/Gd^{3+} moment leads to a strong Zeeman coupling. At 30 K the Gd L₂ maintains its alignment, with slightly reduced magnitude.

We check the NdN alignment by turning to the NdN L_2 edge, shown in Figure 6.8. This figure shows the L_2 XAS and XMCD for the NdN/GdN superlattice and for the homogeneous NdN sample as well, for comparison. The L_3 for the superlattice is not shown as it is too weak to clearly resolve any structure. In the figure we observe that the Nd L_2 is of the same sign for the superlattice and homogeneous sample, though the intensity is a factor of



Figure 6.7: XAS and XMCD spectra from the NdN/GdN superlattice at (a) the Gd L₃ edge with T = 16 K, and (b) the Gd L₂ edge with T = 16 & 30 K. The spectra were measured after field cooling in 1.2 T.



Figure 6.8: Nd L_2 edge XAS and XMCD spectra for (a) the NdN/GdN superlattice at 16 K and 30 K and (b) the homogeneous NdN sample at 16 K, both after field cooling and measuring in 1.2 T.

two smaller in the superlattice. The sign of the Nd L_2 XMCD in both samples agrees with that of the Sm L_2 XMCD in homogeneous SmN shown in Chapter 5. This sign of the Sm L_2 XMCD was shown to correspond to the orbital dominant magnetization in Ref. [19]. The sign difference between the Nd L_2 and Gd L_2 edge XMCD also confirms the orbital dominant NdN moment.

We can then conclude that the superlattice NdN layers have their average magnetization parallel to the field at 15 K and 1.2 T. This is in contrast to

Chapter 6 Twisted Magnetization in a NdN/GdN Superlattice

the SmN/GdN superlattice in Chapter 5, which showed the SmN layers had their magnetization antiparallel to the external field due to the exchange coupling with GdN. The difference can be explained by 1) the much large Zeeman coupling of NdN and 2) the thicker NdN layers (10 nm NdN layers versus 1.5 nm SmN layers). The reduction in the Nd L₂ signal by a factor of two in the superlattice suggests that the inner Nd ions in the NdN layers are Zeeman dominated, while the interface adjacent layers have their magnetization reversed by exchange with GdN. The result is a reduction in the average magnetization in the NdN superlattice layers compared to bulk NdN.

To gain insight more into the magnetic alignment of the GdN and NdN layers we turn to field-dependent XMCD measurements in the following section.

6.4.3 XMCD hysteresis

In this section we examine the field dependence of the XMCD at the Gd L_2 and Nd L_2 edges in the superlattice, shown in Figure 6.9. The temperature was fixed at 30 K for these measurements, and the applied field extended to $\mu_0 H = \pm 1.2$ T. The hysteresis loops were determined by fitting each spectrum to the XMCD spectrum measured at 1.2 T. The sign of the hysteresis was chosen to follow that of the magnetization: while the most prominent peak in the Gd L_2 XMCD is negative at 1.2 T, the magnetization is positive, thus the Gd L_2 hysteresis was scaled by -1. For the NdN the sign of the most prominent L_2 peak is positive at 1.2 T, thus it does not require scaling by -1. At the Gd L_2 edge only half a hysteresis loop was measured for increasing field (red), while the blue curve was obtained by inverting the red curve along both axes. A full NdN hysteresis curve was measured for both increasing and decreasing fields.

We first look at the GdN hysteresis and note both the remanent magnetization and coercive field are positive, in accordance with Figure 6.5(b), which shows that the net coercive field of the superlattice changes from negative to positive between 20 and 35 K. From the XMCD it is clear that the GdN magnetization is aligned parallel to the field at 1.2 T, and remains aligned at remanence, in contrast to the magnetization data taken at 5 K, where the GdN magnetization changes sign before the field reaches zero. In the magnetization data at 5 K, it is the GdN-NdN exchange which causes the GdN magnetization to invert its sign. This implies that in the current situation, the positive GdN at zero field can be explained by the GdN being only weakly influenced by the NdN-GdN interface exchange.

It is also clear that the GdN hysteresis loop self-intersects at approximately ± 0.1 T and ± 0.6 T. This is a signature of exchange coupling with NdN. As the field is decreased from 1.2 T, the Zeeman coupling of the GdN weakens and the NdN exchange exerts some influence, however not enough to invert the GdN completely. One however notices that in contrast to the low temperature magnetization data of Figure 6.3, the magnetization with *decreasing* field (blue



Figure 6.9: XMCD hysteresis measured at both Gd and Nd L_2 edges, where the sign has been chosen to correspond with the net magnetization within respective GdN and NdN layers. Sketches of moments correspond to the blue curves, for decreasing H.

curve) is lower in the XMCD hysteresis. The shape of the Gd L_2 hysteresis makes it clear that it behaves largely as a homogeneous GdN sample would, with perturbations from this behavior due to the NdN exchange coupling.

We now turn to the NdN hysteresis, following the Nd alignment as the field is decreased from 1.2 T. As the field decrease, we see that the Nd signal decreases as well, becoming zero at 0.5 T. This signals that as the NdN Zeeman coupling weakens, a twisted magnetization arising from interface exchange-Zeeman competition nucleates from the interfaces deeper into NdN layers. The decreasing field increases the twist length scale, which according to the model of Chapter 5 varies as $\ell \propto 1/\sqrt{|H|}$. The periodic boundary conditions of the superlattice mean that the twist is symmetric about the center of the NdN layers, and when H = 0.5 T the average alignment of the NdN in the plane of the film is zero. Below 0.5 T the NdN magnetization is dominated by interface exchange, resulting in a negative magnetization alignment with respect to the field. When the field reaches 0.1 T the NdN spin-moment is strongly coupled to the GdN by interface exchange, and the magnetization rigidly follows the GdN in the low field region where there is vanishing Zeeman coupling. The NdN reversal continues until -0.2 T, when the Zeeman coupling of the NdN is large enough to compete with the NdN-GdN exchange. A twisted phase begins to nucleate in the inner NdN layers as the NdN Zeeman coupling becomes stronger. The average NdN alignment passes through zero at -0.5 T and then arrives in the Zeeman dominated regime where the orbital moment is parallel to H.

This situation is shown in the sketches in Figure 6.9, which show the spin and orbital moments of the GdN and NdN layers assuming periodic boundary conditions. The sketches are idealized to some degree, as the effect of incomplete saturation of the NdN and GdN layers have been ignored. The shape anisotropy in the thin film geometry should keep the magnetization of the film in plane, thus we have only considered rotations of the magnetization in the plane of the film, similar to a Bloch domain wall.

Figure 6.10 shows an additional 16 K hysteresis loop extracted from XMCD at the Nd L_2 edge (with the 30 K data also shown for comparison. The 16 K data shows the same characteristics as the 30 K measurement, though with a



Figure 6.10: Comparison of the Nd L_2 hysteresis from the NdN/GdN superlattice measured at 16 K and 30 K. Red and blue curves denote measurements with H increasing and decreasing, respectively.

larger amplitude expected at lower temperature.

6.5 Discussion

The preceding sections have clearly demonstrated that in the NdN/GdN superlattice the unique interface exchange coupling produces complex magnetic structures. The twisted phase due to exchange-Zeeman competition manifests in two ways: in the low temperature SQUID magnetization data we saw that the GdN magnetization switched first, while the NdN magnetization reversed fully in very large negative fields. In contrast, the XMCD hysteresis showed that the NdN magnetization reverses first, followed by the GdN only after the field reverses. This suggests categorization of the twisted phases as follows: a "soft phase" where the soft GdN layers pass through a twisted phase and reverse before the field does, and a "hard phase" where the hard NdN layers enter a twisted phase and reverse before the field reaches zero. The boundary between these phases depends on both temperature and the maximum applied



Figure 6.11: A proposed phase diagram of the twisted magnetic phases in the NdN/GdN superlattice. H_{sat} represents the approximate field required to saturate the magnetization in bulk NdN. H_C is the coercive field of NdN.

field.

The origin of these two phases is related to the magnetic anisotropy of the NdN layers. At 5 K the coercive field is about 1.5 T, while in GdN it is of order 0.01 T. Because of the rather low T_C of NdN, the anisotropy energy decreases significantly as the temperature is increased. For the XMCD measurements at 16 and 30 K, the NdN anisotropy is relatively small, and the NdN is dominated by the interface exchange coupling with GdN. In the 5 K SQUID measurements however, the 6 T field is large enough to fully align the NdN layers, which then remain fixed due to the large anisotropy, while the GdN layers enter a twisted phase.

Figure 6.11 shows a phase diagram taken from all available magnetization and XMCD measurements, with temperature plotted along the horizontal axis and the maximum applied field ($\mu_0 H_{\text{max}}$) along the vertical axis. The soft phase, in which the GdN enters a twisted phase, is located in the upper left quadrant, with the maximum applied field at 6 T. The three data points (blue stars) all have $M_R < 0$, signalling the GdN layers reverse their magnetization before H reaches zero. The grey hexagon at 35 K represents the hysteresis in Figure 6.11, and which shows that $M_R > 0$, though it is only 25% of the saturation magnetization at high field. At this temperature and maximum applied field, the GdN may still enter a twisted phase, but the interface-exchange is not strong enough to produce a negative magnetization in the GdN layer. This point is then possibly in the soft phase.

The two XMCD measurements at 16 K and 30 K (red diamonds) in the hard phase are separated from the soft phase by the line $H_{\rm sat}$ which represents the saturation field of bulk NdN, and corresponds approximately to the boundary between the soft and hard phase. It seems that a field of at least $H_{\rm sat}$ must be applied to align the NdN magnetization to a sufficient degree for producing a rigid pinning layer for the GdN layers to develop a twisted phase. If the maximum applied field is much less than $H_{\rm sat}$, the NdN magnetization is more disordered and the interface exchange coupling will decrease in energy. The GdN magnetization will consequently be dominated by Zeeman coupling.

Finally, the green triangles represent SQUID measurements which show no apparent evidence of a twisted phase. Below the NdN T_C , this is most likely because the maximum applied field is not large enough to align the NdN layers to any significant degree. Above the NdN T_C , the GdN is responsible for the ordering. Interface exchange may take place with the GdN, but above the NdN T_C there is no intra-layer NdN exchange to support any twisted phase, even in large fields. In this case one expects only the atomic layers adjacent to the GdN to be exchange coupled.

6.6 Conclusion and Outlook

The combination of lab based magnetization measurements and the element specific tool of XMCD paint a complex picture of the NdN/GdN system, which we have explored for the first time. There are two primary conclusions we make in regards to the NdN/GdN system. First, there is the appearance of two different kinds of twisted phases. The soft phase where the GdN enters a twisted phase upon decreasing the field from saturation, and the hard phase where the NdN layers enter a twisted phase when decreasing the field from saturation,



Figure 6.12: XMCD at the Dy and Y L_3 edge in a DyFe₂/YFe₂ superlattice, from Dumesnil *et al.*, Ref. [104]. YFe₂ is a weak ferrimagnet and DyFe₂ is a hard ferrimagnet. (a) The hard phase XMCD derived hysteresis at 100 K, (b) soft phase XMCD derived hysteresis at 200 K.

while the GdN layers behave in a more usual manner. The second conclusion is that this NdN/GdN system confirms our model of an orbital-driven twisted phase described in Chapter 5 for the SmN/GdN system. The orbital-dominant magnetization of SmN and NdN make this unusual asymmetry between ferromagnetic interface exchange and Zeeman coupling possible, and drives the competition resulting in the twisted phases.

Further work is needed to better understand the NdN/GdN system. In particular, XMCD experiments with large fields and lower temperatures are necessary to better compare with the lab based magnetometry. The sketches of the GdN and NdN magnetizations may have more complex behavior than we have sketched above. To obtain a better picture of the magnetic structure detailed calculations will need to be made.

We note there exist similar types of twisted phases in the metallic exchangespring $DyFe_2/YFe_2$, where the $DyFe_2$ is a hard ferrimagnet with the Dy moment dominant, and YFe_2 is a weak ferrimagnet with the Fe moment dominant [104, 105]. Dy, as a heavy rare-earth, has the spin and orbital moments parallel. In this case, there is ferromagnetic Fe-Fe exchange, however this exchange results in an antiferromagnetic coupling of the net magnetizations. This leads to similar hard and soft twisted phases as in the NdN/GdN superlattice system, shown in Figure 6.12 for a $\text{DyFe}_2/\text{YFe}_2$ superlattice (From Dumesnil *et al* [104]. The figures show Dy and Y L₃ edge XMCD derived hysteresis loops. The soft phase (Fig. 6.12(b)) shows very similar behavior to the 16 K XMCD data in Figure 6.9.

The accrued knowledge from the study of the complex behavior of $DyFe_2/YFe_2$ will doubtless aid in future investigations of NdN/GdN and SmN/GdN heterostructures. However we note again the important distinction: the rare-earth nitride superlattices are intrinsic ferromagnetic semiconductors. The strong spin-orbit coupling keeps the spin and orbital moments fixed relative to each other even when strong exchange fields are present, as was shown in the calculations of Chapter 4 and 5. It may be interesting to study the magnetoresistance of REN heterostructures with twisted phases. There are some reports of giant magnetoresistance due to twisted phases in conventional exchange spring systems such as $DyFe_2/YFe_3$ [106]. The effect of such an unconventional "domain wall" in the REN superlattice may yield interesting results.

Chapter 7

Conclusions and Outlook

7.1 Results

In this thesis we have investigated the magnetic properties of SmN and NdN in detail, and advanced our understanding of these materials in two major ways. We first investigated the fundamental quantity of the magnetic moment in SmN and NdN. We showed that crystal field calculations, when properly carried out by including excited *J*-multiplets, lead to good agreement with experimental data. Our results differ from previous band-structure calculations using advanced density-functional theory methods, which predicted nearly maximal values of the orbital and spin moments in NdN and SmN, while our results showed that the crystal field effects in SmN and NdN cause significant quenching of the orbital and spin moments. This partial quenching has also been observed in some heavy rare-earth nitrides such as DyN, ErN, and HoN, adding support to our finding that quenching plays an important role in the RENs, in contrast to previous calculations.

In NdN, good agreement was found with the published NdN data from Schumacher *et al.* and the crystal field calculations, however the ordered moment and larger T_C of thin-film NdN could not be adequately explained. Likely causes of the smaller ordered moment and larger T_C in the NdN thin-film are substrate-induced strain and the effects of doping due to nitrogen vacancies. The effect of nitrogen vacancies are known to modify the Curie temperature in GdN due to the formation of magnetic polarons, suggesting the possibility of a similar effect occurring in NdN.

The second major result is the observation of unconventional twisted magnetization phases in SmN and NdN films when coupled to GdN. These twisted phases were shown to arise from competition between ferromagnetic interface exchange (acting only on spin) and the orbital-dominant Zeeman coupling of SmN and NdN. When SmN is exchange coupled to GdN (with a purely spin moment) an external field keeps GdN fixed while the Zeeman coupling tends to rotate the SmN magnetization, this competition results in the twisted phase. Using the element-specific technique of XMCD, we observed a twisted SmN magnetization in a SmN/GdN bilayer. An analytical model was developed to explain the XMCD at the M-edge in a natural way. We furthermore showed that the crystal-field calculations could explain the enhanced spin and orbital alignment at the interface SmN layers, lending further support to the technique. In a NdN/GdN superlattice magnetization and XMCD measurements unambiguously revealed twisted phases occurring in both NdN and GdN, depending on the temperature and maximum applied field. The observation of the twisted phase in the NdN/GdN system also confirms the findings in the SmN/GdN system, establishing that the orbital-dominant Zeeman coupling competes with ferromagnetic interface exchange with GdN to drive the phase.

Systems exhibiting similar twisted phases either rely on large anisotropy differences between materials, or have antiferromagnetic exchange coupling at interfaces to produce competition interactions resulting in a twisted phase. All of these systems are 1) metallic and 2) spin-dominant, establishing that twisted phases in rare-earth nitride heterostructures are quite unconventional.

7.2 Future Outlook

The good agreement between the crystal field calculations and experiment for SmN and NdN suggest that calculations could be applied to other RENs to good effect. The next to study would be the latter half of the REN series, where DyN, ErN, and HoN have detailed experimental studies of their magnetic properties [6, 70]. It would be useful to determine any trends in the crystal field parameters across the series. Ultimately, a knowledge of the spin
and orbital moments would benefit other theoretical calculations that depend on these values. Another useful effort would be to revisit band structure calculations in the RENs in light of the findings in this thesis. More accurate predictions of the band structures and the resulting spin and orbital moments would greatly aid in the interpretation of a vast range of experiments. Finally, it would be interesting to see if advanced band structure calculations could provide some insight into the crystal field model in the RENs, and perhaps some correspondence between the two approaches could be made.

There are many possible directions to take in studying twisted phases in REN heterostructures. The obvious next steps are to conduct more XMCD experiments on the SmN/GdN and NdN/GdN systems. *In-situ* growth at an M-edge XMCD beamline would allow for more detailed depth-dependent studies. Further L-edge XMCD studies in larger fields and lower temperatures are already being planned for NdN/GdN superlattices. Depth sensitive neutron reflectivity measurements should also provide more detailed information. These additional measurements in a variety of temperatures, fields, and geometries should provide a better picture of the twisted structure. Measurements to determine the anisotropy contributions would also be useful and aid in modelling these phases.

The ability to substitute rare-earth ions may also lead to interesting results. Substituting Gd ions in SmN and NdN should reduce the overall magnetization while also modifying the exchange, which could allow the ability to tune the length scales of the twisted phases independently of the applied field. These twisted phases can thus be viewed as engineered domain-walls with tunable domain-wall widths. Current-driven domain wall motion is an active field, so it may be interesting to explore this area in the RENs. An open question is the transport characteristics through these twisted phases, which may show some interesting behavior. There have been reports of giant magnetoresistance in metallic exchange-spring systems [106] for example, so it seems worth pursuing similar experiments in the RENs, in addition to tunneling magnetoresistance. Because the RENs can be doped to achieve a wide range of carrier concentrations, the conductivity can be tuned to the desired application, while the magnetic properties are relatively unaffected. There are thus many unexplored Chapter 7 Conclusions and Outlook

avenues worth pursuing in REN heterostructures.

7.2 Future Outlook



Appendices

Appendix A

Matrix Elements of Irreducible Tensor Operators

A.1 Irreducible Tensor Operators

The Wigner-Eckart theorem provides a useful relationship for matrix elements of tensor operators with respect to total angular moment eigenstates $\{|LSJM_J\rangle\}$ (see, e.g. Refs [32, 107, 108]). An irreducible tensor operator is fully defined by its commutation relations with components of the total angular moment operator **J**. First we define the following angular moment "ladder" operators:

$$J_{\pm} = J_x \pm i J_y. \tag{A.1}$$

These operators have the following commutation relations (the commutator is [A, B] = AB - BA):

$$[J_{\pm}, J_{\mp}] = \pm 2J_z$$
 and $[J_z, J_{\pm}] = \pm J_{\pm}.$ (A.2)

An irreducible tensor operator can now be defined as an object $\mathcal{T}_q^{(k)}$ which satisfies the following commutation relations:

$$\left[J_z, \mathcal{T}_q^{(k)}\right] = q \mathcal{T}_q^{(k)} \tag{A.3}$$

$$\left[J_{\pm}, \mathcal{T}_{q}^{(k)}\right] = \sqrt{k(k+1) - q(q\pm 1)} \mathcal{T}_{q\pm 1}^{(k)}, \tag{A.4}$$

where the rank k, of the operator refers to the number of independent components, equal to 2k + 1, and q indexes these components, with $q = -k, -k + 1, \ldots, k - 1, k$. For example k = 0 corresponds to a scalar operator (one component), k = 1 a vector operator with components q = -1, 0, 1, and $k \ge 2$ corresponds to tensor operators.

The term "irreducible" corresponds to the fact that $\mathcal{T}_q^{(k)}$ transforms under rotations as a spherical harmonic of rank k, and cannot be decomposed into a sum of lower rank operators (in contrast, Cartesian tensor operators are not necessarily irreducible).

A.2 The Wigner-Eckart Theorem

The statement of the Wigner-Eckart theorem is made for angular momentum eigenstates $|\alpha, JM\rangle$ where α indicates other quantum numbers (such as L, S, and the radial quantum number n). The theorem tells us how to calculate matrix elements of an irreducible tensor operator $\mathcal{T}_q^{(k)}$:

$$\langle \alpha JM | \mathcal{T}_q^{(k)} | \alpha' J'M' \rangle = (-1)^{J-M} \begin{pmatrix} J & k & J' \\ -M & q & M' \end{pmatrix} \langle \alpha J | | \mathcal{T}^{(k)} | | \alpha' J' \rangle \quad (A.5)$$

where the large parentheses denotes the Wigner-3*j* symbol and the reduced matrix element $\langle \alpha J || \mathcal{T}^{(k)} || \alpha' J' \rangle$ is independent of M and M'. The 3*j* symbol is defined in terms of the Clebsch-Gordan coefficient by

$$\begin{pmatrix} j_1 & j_2 & J \\ m_1 & m_2 & -M \end{pmatrix} = (-1)^{M+j_1-j_2} \frac{\langle j_1 j_2 m_1 m_2 | j_1 j_2 : JM \rangle}{\sqrt{2j+1}}, \qquad (A.6)$$

where $\mathbf{j}_1 + \mathbf{j}_2 = \mathbf{J}$ and $m_1 + m_2 = M$. The Clebsch-Gordan coefficients form the unitary transformation between the $\{|j_1j_2m_1m_2\rangle\}$ basis and $\{|j_1j_2: JM\rangle\}$ basis. For example,

$$|j_1 j_2 : JM\rangle = \sum_{m_1} \sum_{m_2} \langle j_1 j_2 m_1 m_2 | j_1 j_2 : JM\rangle | j_1 j_2 m_1 m_2\rangle.$$
 (A.7)

In terms of Clebsch-Gordan coefficients the Wigner-Eckart theorem reads

$$\langle \alpha JM | \mathcal{T}_q^{(k)} | \alpha' J'M' \rangle = \frac{\langle J'kM'q | JM \rangle}{\sqrt{2J+1}} \langle \alpha, J | | \mathcal{T}^{(k)} | | \alpha', J' \rangle.$$
(A.8)

The meaning of the Wigner-Eckart theorem (A.5) is that it separates the geometrical factors (depending on M, M') out from the part describing the physical operator, which is described by the reduced matrix element. For vector operators k = 1, if J' = J, the Wigner-Eckart reduces to the simplified projection theorem:

$$\langle \alpha, JM | \mathcal{T}_q | \alpha', JM' \rangle = \frac{\langle \alpha, JM | \mathcal{T} \cdot \mathbf{J} | \alpha', JM \rangle}{J(J+1)} \langle JM | J_q | JM' \rangle.$$
 (A.9)

For example, setting $\mathcal{T} = \mathbf{L}$, for $L_z = L_0$ the projection theorem gives

$$\langle \alpha, JM | L_z | \alpha', JM' \rangle = \frac{\langle \alpha, JM | \mathbf{L}^2 + \frac{1}{2} (\mathbf{J}^2 - \mathbf{L}^2 - \mathbf{S}^2) | \alpha', JM' \rangle}{J(J+1)} \langle JM | J_z | JM' \rangle$$
$$= \frac{1}{2} + \frac{1}{2} \frac{L(L+1) - S(S+1)}{J(J+1)} \langle JM | J_z | JM' \rangle.$$
(A.10)

Similarly for $S_z = S_0$,

$$\langle \alpha, JM | S_z | \alpha', JM' \rangle = \frac{\langle \alpha, JM | \mathbf{S}^2 + \frac{1}{2} (\mathbf{J}^2 - \mathbf{L}^2 - \mathbf{S}^2) | \alpha', JM' \rangle}{J(J+1)} \langle JM | J_z | JM' \rangle = \frac{1}{2} - \frac{1}{2} \frac{L(L+1) - S(S+1)}{J(J+1)} \langle JM | J_z | JM' \rangle .$$
(A.11)

Thus the operator $M_z = L_z + 2S_z$ can be seen to be

$$\langle \alpha, JM | L_z + 2S_z | \alpha', JM' \rangle = \frac{3}{2} - \frac{1}{2} \frac{L(L+1) - S(S+1)}{J(J+1)} \langle JM | J_z | JM' \rangle$$
$$= g_J \langle JM | J_z | JM' \rangle, \qquad (A.12)$$

where we have defined the Landé g_J -factor. From this definition it is easy to

show that

$$\langle \alpha, JM | S_z | \alpha', JM' \rangle = (g_J - 1) \langle JM | J_z | JM' \rangle$$
 (A.13)

$$\langle \alpha, JM | L_z | \alpha', JM' \rangle = (2 - g_J) \langle JM | J_z | JM' \rangle,$$
 (A.14)

which were given in Chapter 4. A simpler alternative for deriving the relation between $L_z + 2S_z$ and J_z exists using purely geometrical considerations, and is found in many introductory quantum mechanics textbooks. The Wigner-Eckart and projection theorems allow for the use of algebraic methods without resorting to geometrical considerations.

Consequences of the Wigner-Eckart Theorem

An important consequence of the Wigner-Eckart theorem is that matrix elements of tensor operators within a fixed *J*-multiplet (i.e. J' = J) are proportional to each other. Given tensor operators $\mathcal{T}_q^{(k)}$ and $\mathcal{O}_q^{(k)}$, we have

$$\frac{\left\langle \alpha, JM' | \mathcal{T}_q^{(k)} | \alpha', JM' \right\rangle}{\left\langle \alpha, JM' | \mathcal{O}_q^{(k)} | \alpha', JM' \right\rangle} = \frac{\left\langle \alpha, J | | \mathcal{T}^{(k)} | | \alpha', J \right\rangle}{\left\langle \alpha, J | | \mathcal{O}^{(k)} | | \alpha', J \right\rangle},$$
(A.15)

which shows that the ratio of these operators does not depend on the geometry of the system through M, M'.

More generally, given a Hamiltonian \mathscr{H} which depends on parameters such as $\Lambda, J_{ex}, A_4, A_6$, if only the lowest *J*-multiplet is considered an eigenstates of \mathscr{H} can be written as

$$|\psi_i\rangle = \sum_M c_M^i |\alpha, JM\rangle, \qquad (A.16)$$

where the coefficients depend on the parameters of the Hamiltonian. In this case the expectation value of a tensor operator within the state $|\psi_i\rangle$ is given

by

$$\left\langle \psi_i | \mathcal{T}_q^{(k)} | \psi_i \right\rangle = \sum_{M,M'} c_M^{*i} c_{M'}^i \left\langle \alpha, JM | \mathcal{T}_q^{(k)} | \alpha', JM' \right\rangle \tag{A.17}$$

$$= \left(\sum_{M,M'} c_M^{*i} c_{M'}^i (-1)^{J-M} \begin{pmatrix} J & k & J \\ -M & q & M' \end{pmatrix} \right) \left\langle \alpha J || \mathcal{T}^{(k)} || \alpha' J' \right\rangle$$
(A.18)

$$= \mathcal{U}_{k,q}(J) \left\langle \alpha J || \mathcal{T}^{(k)} || \alpha' J' \right\rangle.$$
(A.19)

Thus the matrix elements of the q-th component of every tensor operator of rank k within a single J multiplet are proportional to $\mathcal{U}_{k,q}(J)$. The ratio of reduced matrix elements give the proportionality constants between operators. Varying the parameters of the Hamiltonian changes $\mathcal{U}_{k,q}(J)$, but not the ratio of tensor operators. Thus within a single J-multiplet the ratio of the matrix elements of any two tensor operators remains fixed.

If higher *J*-multiplets are considered, then the ratio of the matrix elements of tensor operators depend on the coefficients c_M^i , and thus the parameters in the Hamiltonian. In this case

$$\frac{\left\langle \psi_{i} | \mathcal{T}_{q}^{(k)} | \psi_{i} \right\rangle}{\left\langle \psi_{i} | \mathcal{O}_{q}^{(k)} | \psi_{i} \right\rangle} = \frac{\mathcal{U}_{k,q}(J) \left\langle \alpha J || \mathcal{T}^{(k)} || \alpha' J' \right\rangle + \mathcal{U}_{k,q}(J, J+1) \left\langle \alpha J || \mathcal{T}^{(k)} || \alpha' J+1 \right\rangle + \dots}{\mathcal{U}_{k,q}(J) \left\langle \alpha J || \mathcal{O}^{(k)} || \alpha' J' \right\rangle + \mathcal{U}_{k,q}(J, J+1) \left\langle \alpha J || \mathcal{O}^{(k)} || \alpha' J+1 \right\rangle + \dots}$$
(A.20)

This is an important consideration for Sm³⁺, where the spin and orbital moments are antiparallel and nearly equal and magnitude, so small changes in the ratio of $\langle L_z \rangle / \langle S_z \rangle$ can change the net moment considerably.

A.3 Matrix Elements Between Arbitrary Multiplets

Here we derive the matrix elements for arbitrary *J*-multiplets given in Chapter 4. We first derive Equations 4.12, the matrix element $\langle JM|L_z|J'M'\rangle$. We first

apply the Wigner-Eckart Theorem to separate out the M dependence, using the notation $L_z = L_0^{(1)}$:

$$\left\langle LSJM|L_0^{(1)}|LSJ'M'\right\rangle = (-1)^{J-M} \begin{pmatrix} J & k & J' \\ -M & q & M' \end{pmatrix} \left\langle LSJ||L^{(1)}||LSJ'\right\rangle$$
(A.21)

The calculation of $\langle LSJ||L^{(1)}||LSJ'\rangle$ is more involved because $L^{(1)}$ is acting on only one part of a coupled system of angular momentum vectors. The derivation of this matrix element uses the Clebsch-Gordan decomposition multiple times to recouple the angular moment states, along with repeated use of the Wigner-Eckart theorem. The result involves a double sum over four Clebsch-Gordan coefficients (or 3j symbols), which more compactly expressed by a Wigner 6j-symbol. For a coupled system with $j_1 + j_2 = J$, and an operator $\mathcal{T}^{(k)}(1)$ acting on j_1 , the reduced matrix element in general is given by

$$\langle \alpha, j_1 j_2 J || \mathcal{T}^{(k)}(1) || \alpha', j'_1 j'_2 J' \rangle = \delta_{j_2, j'_2}(-1)^{j_1 + j_2 + J' + k}$$

$$\times \sqrt{J(J+1)J'(J'+1)} \begin{cases} J & k & J' \\ j'_1 & j_2 & j_1 \end{cases}$$
(A.22)
$$\times \langle \alpha, j_1 || \mathcal{T}^{(1)} || \alpha', j'_1 \rangle ,$$

where the braces represent the Wigner 6j symbol (see, e.g. Ref. [107] for a derivation of (A.22) and general recursion relations and special cases of the 6j symbol). In our case, with k = 1, $j_1 = j'_1 = L$ and $j_2 = j'_2 = S$, Equation (A.21) reduces to

$$\left\langle LSJM_{J}|L_{0}^{(1)}|LSJ'M'\right\rangle = (-1)^{J-M+L+S+J'+1} \times \sqrt{J(J+1)J'(J'+1)}$$
$$\times \begin{pmatrix} J & k & J' \\ -M & q & M' \end{pmatrix} \begin{cases} J & 1 & J' \\ L & S & L \end{cases}$$
$$\times \langle L||L^{(1)}||L\rangle.$$
(A.23)

The calculation of the final reduced matrix element can now be done explicitly. By the Wigner-Eckart theorem we have

$$\left\langle LM_L | L_0^{(1)} | LM'_L \right\rangle = (-1)^{L-M_L} \begin{pmatrix} L & 1 & L \\ M_L & 0 & M'_L \end{pmatrix} \left\langle L | | L^{(1)} | | L \right\rangle.$$
 (A.24)

If we choose $M_L = M'_L$, we can calculate both the matrix element on the left of Eq. (A.24) and 3j symbol explicitly using the formula [107]

$$\begin{pmatrix} a & a & 1 \\ \beta & -\beta & 0 \end{pmatrix} = (-1)^{a-\beta} \frac{\beta}{[a(a+1)(2a+1)]^{1/2}}.$$
 (A.25)

The 3j symbol is invariant under even permutations of the columns, thus we can put Eq. (A.24) into the form of Eq. (A.25). Plugging in values of $M_L = M_{L'}$ we find

$$\left\langle LM_L|L_0^{(1)}|LM_L\right\rangle = M_L = \begin{pmatrix} L & L & 1\\ M_L & -M_L & 0 \end{pmatrix} \left\langle L||L^{(1)}||L\right\rangle, \quad (A.26)$$

where we have used the fact that $L_z |LM_L\rangle = M_L |LM_L\rangle$. We can thus solve for the reduced matrix element:

$$\langle L||L^{(1)}||L\rangle = \sqrt{L(L+1)(2L+1)}.$$
 (A.27)

The final matrix element can now be expressed using the fact that the 6j symbol is invariant under any permutation of the columns, and invariant under permutations of upper and lower arguments in any two columns:

$$\left\langle LSJM_{J}|L_{0}^{(1)}|LSJ'M_{J}'\right\rangle = (-1)^{J-M+L+S+J'+1} \times \sqrt{J(J+1)J'(J'+1)} \\ \times \begin{pmatrix} J & k & J' \\ -M & q & M' \end{pmatrix} \begin{cases} L & L & 1 \\ J & J' & S \end{cases} \sqrt{L(L+1)(2L+1)}$$
(A.28)

This is the same as Equation 4.12. The same procedure can be used to calculate the matrix elements of S_z , given in equation 4.11.

Appendix A Matrix Elements of Irreducible Tensor Operators

For the calculation of the crystal field matrix elements (Equation 4.19) a slightly more complicated reduced matrix element must be calculated. It is given by

$$\langle \Psi(4f^n)L||\sum_i r_i^k Y^k||\Psi(4f^n)L\rangle = \langle 4f|r^k|4f\rangle\langle f^nL||\sum_i Y^k(\theta_i,\phi_i)||f^nL\rangle,$$
(A.29)

where in Chapter 4 we used the notation $\langle r^k \rangle = \langle 4f | r^k | 4f \rangle$. The difficulty in this case is that $\sum_i Y^k(\theta_i, \phi_i)$ acts on single particle states, so the multielectron state $|f^n L\rangle$ must be expanded into single particle states consistent with antisymmetry under interchange of any two electrons. This expansion is done using *coefficients of fractional parentage* (cfp), describe in detail in Cowan [21]. However, because calculations using cfp are tedious, the matrix elements of the form (A.29) have been tabulated for all p, d and f shell configurations in Ref. [109]. The calculations of such reduced matrix elements are given in terms of a *unit* tensor operator

$$\mathcal{U}^{(k)} \equiv \sum_{i=1} \mathfrak{u}^{(k)}(i), \qquad (A.30)$$

related to spherical harmonics by

$$Y_q^k = \left\langle l || Y^k || l' \right\rangle \mathfrak{u}_q^{(k)}, \tag{A.31}$$

and with the property $\langle l||\mathfrak{u}^{(k)}||l'\rangle = 1$ (here *l* refers to a single particle orbital quantum number, with l = 3 for the 4*f* shell). In this way the reduced matrix elements may be determined by

$$\left\langle \Psi(4f^n)L\right| \left|\sum_{i} r_i^k Y^k\right| \left|\Psi(4f^n)L\right\rangle = \left\langle 4f|r^k|4f\right\rangle \left\langle L\right| \left|\mathcal{U}^{(k)}\right| \left|L\right\rangle \left\langle f\right| \left|Y^k\right| \left|f\right\rangle,$$
(A.32)

Each separate expectation value can then be found in tables. As noted in Chapter 4, the radial integrals $\langle 4f|r^k|4f\rangle$ have been calculated in Hartree-Fock and Dirac-Fock schemes [69, 110]. Values of $\langle l||C^k||l'\rangle$ (where $C^k = [4\pi/(2k+1)]^{1/2}Y^k$) are tabulated in Cowan [21]. The matrix elements of Equation (A.29) have conveniently been calculated in [35] for the Hund's rules

A.3 Matrix Elements Between Arbitrary Multiplets

$$\begin{array}{r} \text{Values of } \langle (4f)^n L || \sum_k r_i^k Y^K || (4f)^n L \rangle \text{ in units of } \langle r^k \rangle \\ \hline \hline k & \text{Nd}^{3+} & \text{Sm}^{3+} \\ \hline \hline 2 & -\left(\frac{5}{4\pi} \frac{2^3 \cdot 7 \cdot 13}{3^2 \cdot 5 \cdot 11}\right)^{1/2} & \left(\frac{5}{4\pi} \frac{2^3 \cdot 11 \cdot 13}{3^3 \cdot 5}\right)^{1/2} \\ 4 & -\left(\frac{9}{16\pi} \frac{2^8 \cdot 7 \cdot 13 \cdot 17}{3^2 \cdot 11^3}\right)^{1/2} & \left(\frac{9}{16\pi} \frac{2^9 \cdot 13}{3^2 \cdot 11}\right)^{1/2} \\ 6 & -\left(\frac{13}{32\pi} \frac{2^{10} \cdot 5^4 \cdot 17 \cdot 19}{3^2 \cdot 11^3 \cdot 13}\right)^{1/2} & -\left(\frac{13}{32\pi} \frac{2^{10} \cdot 5^3 \cdot 17}{3^3 \cdot 11 \cdot 13}\right)^{1/2} \end{array}$$

Table A.1: Reduced matrix elements for Sm^{3+} and Nd^{3+} ions, taken from Ref. [35]

ground states of all the rare-earths, and are tabulated (in terms of $\langle r^k \rangle$), reproduced in Table A.1 for Sm³⁺ and Nd³⁺.

Appendix A Matrix Elements of Irreducible Tensor Operators

Appendix B

Free Energy Minimization

Here we derive the twisted magnetization profile of Chapter 5 by minimizing the free energy. The solution to the formally equivalent case of the exchangespring was given by Goto *et al.* [38], however no proof was given. Here we show how to determine the function $\theta(z)$ which minimizes the free energy using the calculus of variations. The basic methods of the calculus of variations can be found in, e.g. Refs. [111, 112]. We first present the general method of minimizing a functional with mixed boundary conditions.

B.1 Extremizing a Functional

The archetypal example of the calculus of variations involves finding the function u(x) which minimizes (or extremizes) the functional J[u]. Here a functional is a map from the space of functions to a scalar in \mathbb{R} .

We assume J is given by the following:

$$J[u] = \int_{a}^{b} dx \ L(x, u, u'), \tag{B.1}$$

with the boundary conditions $u(a) = \alpha$ and $u(b) = \beta$. The first order variation of u is given by $u_{\epsilon}(x) = u(x) + \epsilon w(x)$. If we force the variation to satisfy the boundary conditions (i.e. "fixed" boundary conditions) $u_{\epsilon}(a) = \alpha$ and $u_{\epsilon}(b) = \beta$, we have w(a) = w(b) = 0. Carrying out the minimization (or extremization) procedure by setting the functional derivative equal to zero, we Appendix B Free Energy Minimization

find

$$0 = \frac{d}{d\epsilon} J[u + \epsilon w] \bigg|_{\epsilon=0},$$
(B.2)

$$= \int_{a}^{b} dx \ w(x) \left(\frac{\partial L}{\partial u} - \frac{d}{dx}\frac{\partial L}{\partial u'}\right) + \left[w(x)\frac{\partial L}{\partial u'}\right]_{a}^{b}, \tag{B.3}$$

$$= \int_{b}^{a} dx \ w(x) \left(\frac{\partial L}{\partial u} - \frac{d}{dx} \frac{\partial L}{\partial u'} \right) + w(b) \frac{\partial L}{\partial u'} \bigg|_{x=b} - w(a) \frac{\partial L}{\partial u'} \bigg|_{x=a}.$$
 (B.4)

The last two terms are zero because w(a) = w(b) = 0 and we recover the Euler-Lagrange equations:

$$\frac{\partial L}{\partial u} - \frac{d}{dx}\frac{\partial L}{\partial u'} = 0. \tag{B.5}$$

When one boundary is left free, i.e. we allow variations of w(x) that don't vanish at x = b (in addition to those that vanish at a and b), the term $w(b)\partial L/\partial u'|_{x=b}$ vanishes for arbitrary w only if

$$\left. \frac{\partial L}{\partial u'} \right|_{x=b} = 0. \tag{B.6}$$

In situation of Chapter 5, the functional to be minimized is

$$E[\theta] = \int_0^L dz \, \left[A \left(\frac{d\theta(z)}{dz} \right)^2 + M_s H \cos \theta(z) \right]. \tag{B.7}$$

Using the variations $\theta_{\epsilon}(z) = \theta(z) + \epsilon w(z)$ we have the boundary conditions $\theta(0) = 0$ and we allow arbitrary variations at z = L, i.e. $\theta(L)$ is left free to be whatever minimizes E. Thus, in addition to satisfying the Euler-Lagrange equations, $\theta(z)$ must also satisfy the additional boundary condition

$$\left. \frac{\partial L}{\partial \theta'} \right|_{L} = 2A \frac{d\theta(z)}{dz} \right|_{L} = 0 \tag{B.8}$$

$$\implies \left. \frac{d\theta(z)}{dz} \right|_L = 0. \tag{B.9}$$

However, because $\partial L/\partial z = 0$ (a translational invariance symmetry), Noether's theorem guarantees there is a conserved quantity. The conserved quantity is given by

$$\theta' \frac{\partial L}{\partial \theta'} - L = \text{const.}$$
 (B.10)

This reduces the order of the differential equation in $\theta(z)$ by one, and thus provides a simpler method of solution compared to solving the Euler-Lagrange equations directly.

B.2 Explicit Solution for the Twisted Phase

Making use of the conserved quantity of Eq. (B.10), we see that for the form of L given in Eq. (B.7), we have

$$(\theta')^2 - \lambda^2 \cos \theta(z) = \text{const.}, \tag{B.11}$$

where $\lambda^2 = M_s H/A$. Using the boundary condition $\theta'(L) = 0$ immediately identifies the constant as $-\lambda^2 \cos \theta(L) \equiv -\lambda^2 \cos \theta_0$. After some algebra and integration, we find

$$z\lambda = \int_0^{\theta(z)} \frac{\mathrm{d}\tilde{\theta}}{\sqrt{\cos\tilde{\theta} - \cos\theta_0}}.$$
 (B.12)

Using the identity $\cos \phi = 1 - 2 \sin^2(\phi/2)$ and defining $k = \sin(\theta_0/2)$, we arrive at

$$z\lambda = \frac{1}{\sqrt{2}} \int_0^{\theta(z)} \frac{\mathrm{d}\tilde{\theta}}{\sqrt{k^2 - \sin^2(\tilde{\theta}/2)}}.$$
 (B.13)

Finally, we make the substitution $\xi = k^{-1} \sin^2(\tilde{\theta}/2)$ and find

$$z\alpha = \int_0^{k^{-1}\sin(\theta(z)/2)} \frac{\mathrm{d}\xi}{\sqrt{(1-\xi^2)(1-k^2\xi^2)}},\tag{B.14}$$

where $\alpha = \lambda/\sqrt{2} = \sqrt{M_s H/2A}$. This integral is an incomplete elliptic function of the first kind. It can be inverted by the use of the Jacobi elliptic function

sn in the following way:

$$\operatorname{sn}(z\alpha) = \frac{\sin\frac{\theta(z)}{2}}{k} = \frac{\sin\frac{\theta(z)}{2}}{\sin\frac{\theta(L)}{2}}.$$
 (B.15)

When z = L, we find

$$L\alpha = \int_0^1 \frac{\mathrm{d}\xi}{\sqrt{(1-\xi^2)(1-k^2\xi^2)}} = K(k), \tag{B.16}$$

where K(k) is the complete elliptic function of the first kind, with module k (see, e.g., Abramowitz & Stegun [113] for properties of elliptic functions and Jacobi elliptic functions). We note that $K(k) \ge \pi/2$ for $|k| \le 1$, and so in order to obtain a non-trivial solution, we must have $L\sqrt{M_sH/2A} \ge \pi/2$ for a twisted phase to exist. The explicit solution of $\theta(z)$ is given by

$$\theta(z) = 2\sin^{-1}\left(K^{-1}(\alpha L)\operatorname{sn}(z\alpha)\right) \qquad \alpha = \sqrt{\frac{M_s H}{2A}}, \qquad (B.17)$$

where K^{-1} is the inverse of the complete elliptic function of the first kind. While complete elliptic functions are found in standard computational packages, K^{-1} is generally not among the built-in function. In this thesis we inverted K(k) by using the Newton-Raphson method to find the roots k^* of $K(k) - \alpha L = 0$, where successive approximations of the roots are made by $k_{n+1}^* = k_n^* - K(k_n)/K'(k_n)$, until suitable convergence is reached. The derivative of K(k) is given by

$$K'(k) = \frac{dK}{dk} = \frac{E(k)}{k(1-k^2)} - \frac{K(k)}{k},$$
(B.18)

where E(k) is the complete elliptic function of the second kind, defined by

$$E(k) = \int_0^1 \mathrm{d}\xi \frac{\sqrt{1 - k^2 \xi^2}}{\sqrt{1 - \xi^2}}.$$
 (B.19)

Numerical schemes for calculating the functions $(K(k), E(k), \operatorname{sn}(u))$ can be found in Ref. [113], and are also found as built-in functions for many computational packages.

Appendix B Free Energy Minimization

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